



# **Update on the ERIS-AO and MAORY-NGS Control Systems**

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INAF Osservatorio Astronomico di Teramo

## Extending Collaborations within INAF

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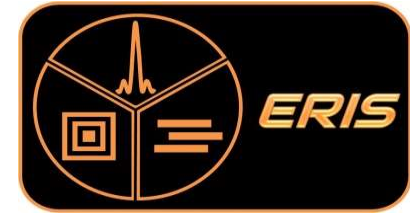


### Attività di collaborazione:

- **ERIS**
  - ✓ Elettronica AO (NGS+LGS)
  - ✓ Calibration Unit (CU)
  - ✓ ICS (software)
  
- **MAORY**
  - ✓ Elettronica & Software LORs
  - ✓ LORs FMECA (*Failure Mode, Effects, and Criticality Analysis*)
  
- **Science**
  - ✓ *M. Cantiello, ADONI 2017*

# ERIS

(Enhanced Resolution Imager and Spectrograph)



- **UT4@VLT (Cassegrain focus): AOF + 4LGFS**
- **Two Science Instruments:**
  1. **NIX (ATC+ETH):** IR imager providing diffraction limited imaging, Sparse Aperture Masking (SAM) and pupil plane coronagraphy capabilities from 1 to 5  $\mu\text{m}$ .
  2. **SPIFFIER (SPectrometer for Infrared Faint Field Imaging with Enhanced Resolution, MPE):** near-IR (1.08-2.43  $\mu\text{m}$ ) integral field spectrograph (upgraded version of SPIFFI).
- **An AO System (LGS + NGS)**
- **A Calibration Unit (CU) for all ERIS instrumentation**

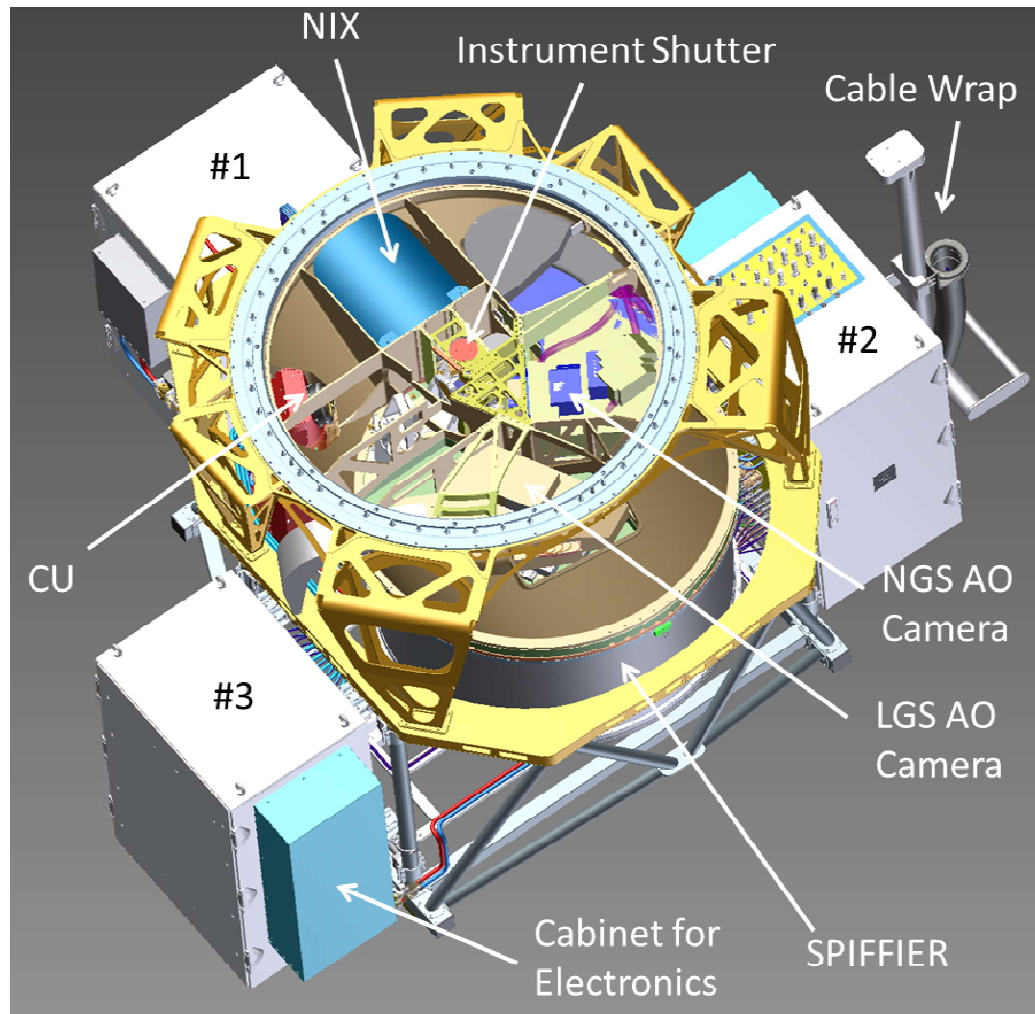
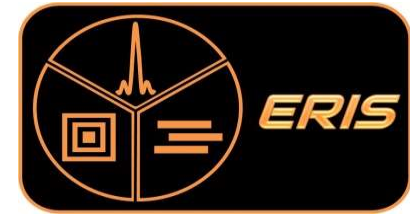
**FDR 29/05/2017**

**First Light 2020**

(ERIS AO Performance: *G. Agapito, ADONI2016*)

# ERIS

(Enhanced Resolution Imager and Spectrograph)



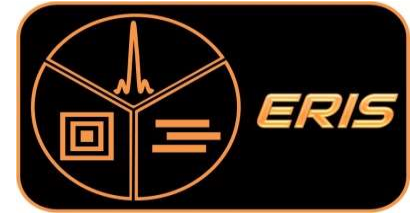
**All Control Electronics in  
3 corotating cabinets:**

- ✓ **WFSs CCD controllers**
- ✓ **AO+CU PLC based ICE**
- ✓ **Piezo Controllers**
- ✓ **NIX electronics**
- ✓ **SPIFFIER electronics**
- ✓ **Power Supplies**
- ✓ **Thermal Control, Fans,...**

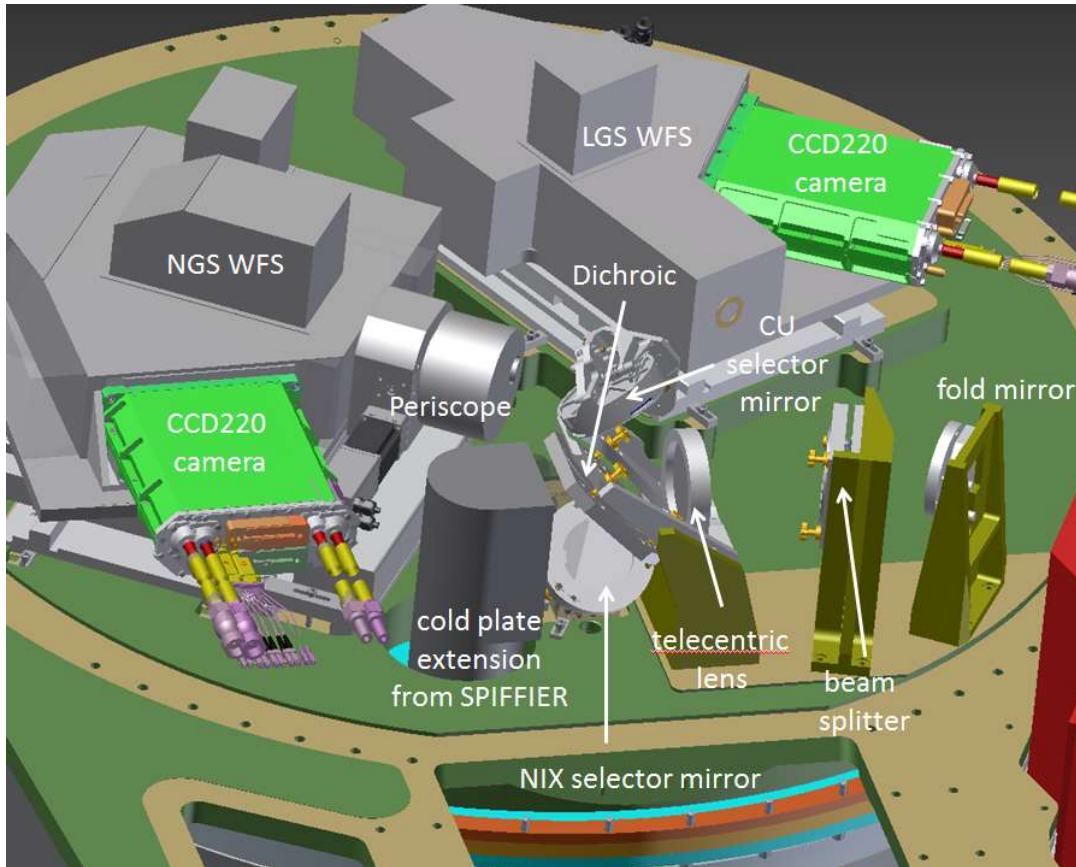
**24 RU 1200 mm  
Air flowing / Water cooling**

# ERIS

(Enhanced Resolution Imager and Spectrograph)

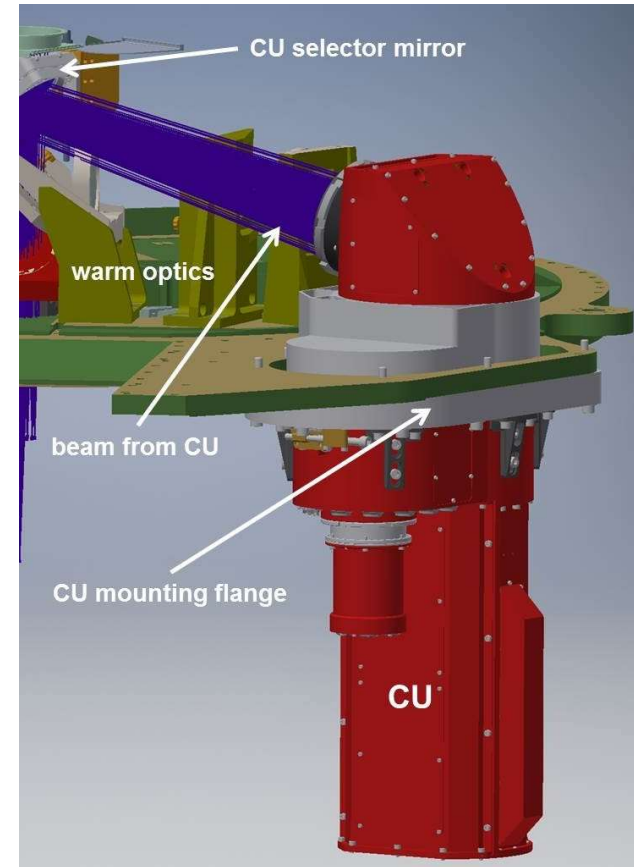


AO



LGS + NGS + WO

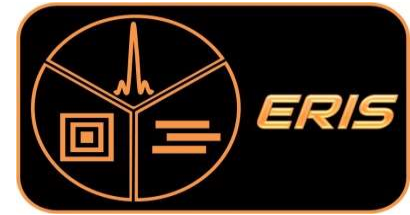
CU



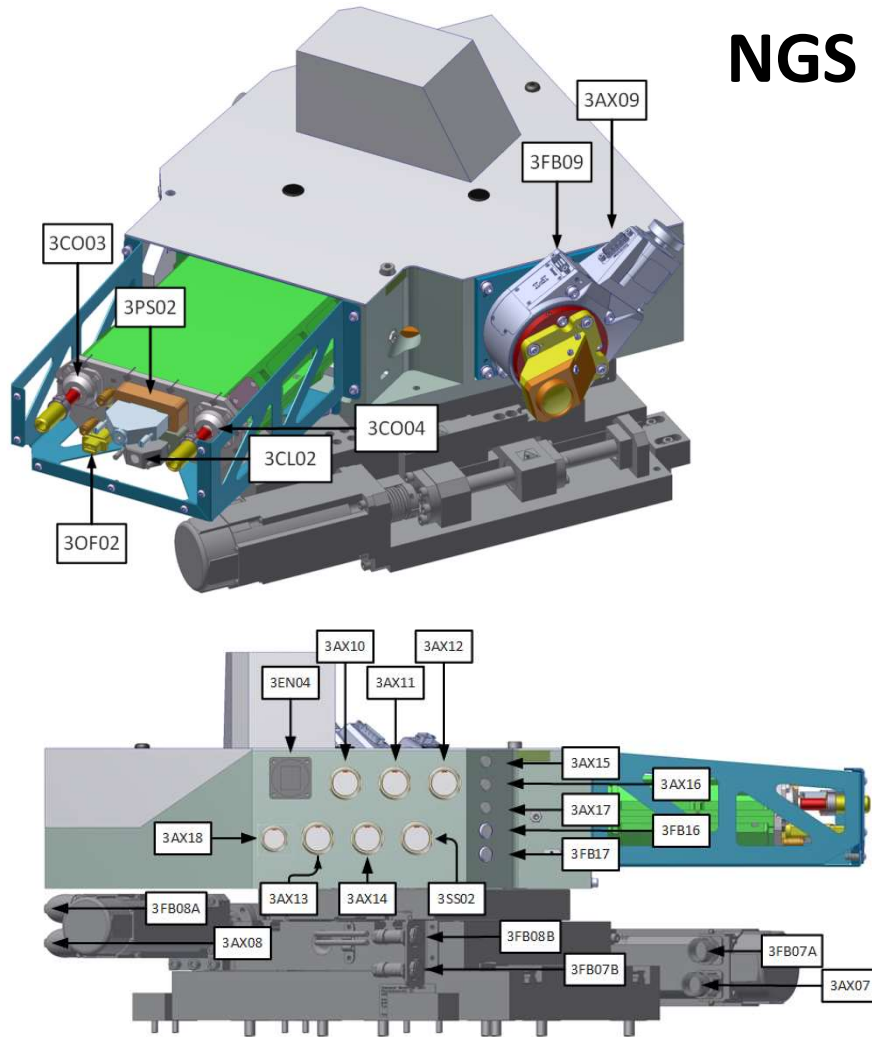
CU Main Bench

# ERIS

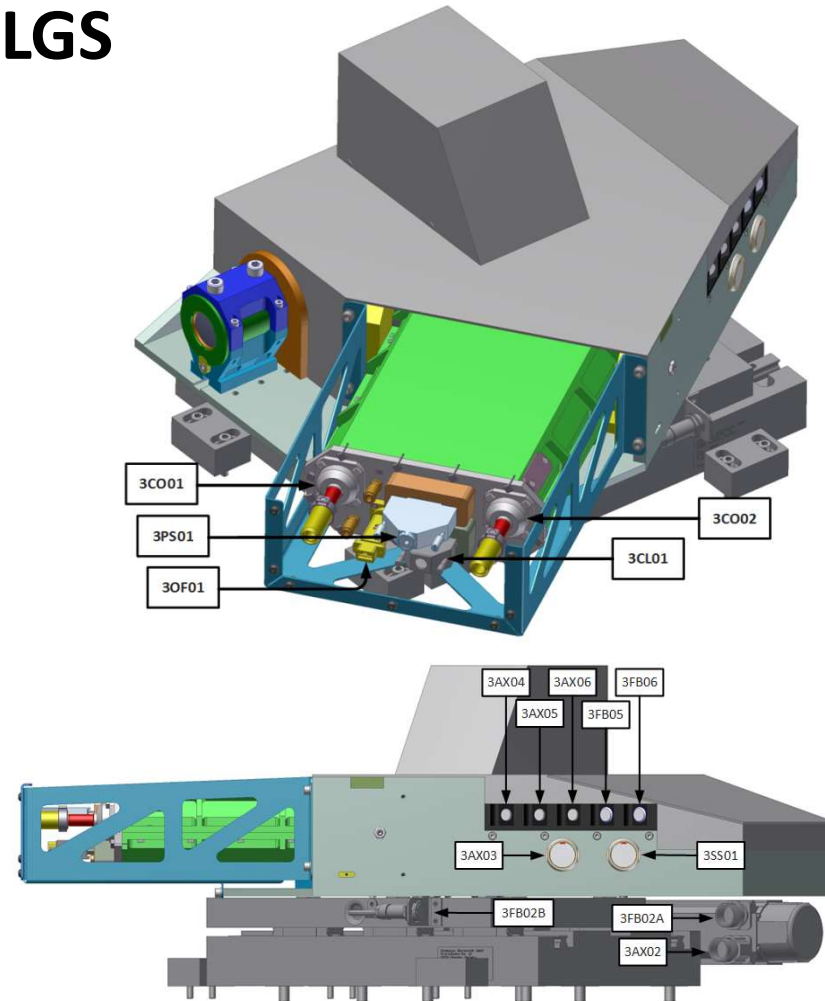
(Enhanced Resolution Imager and Spectrograph)



NGS

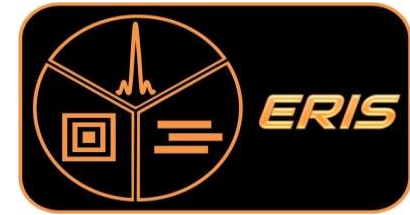


LGS

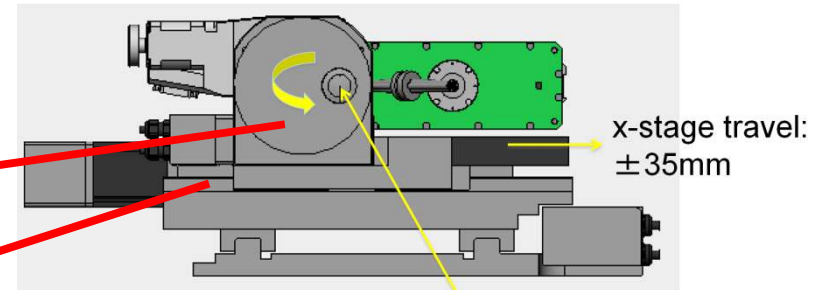
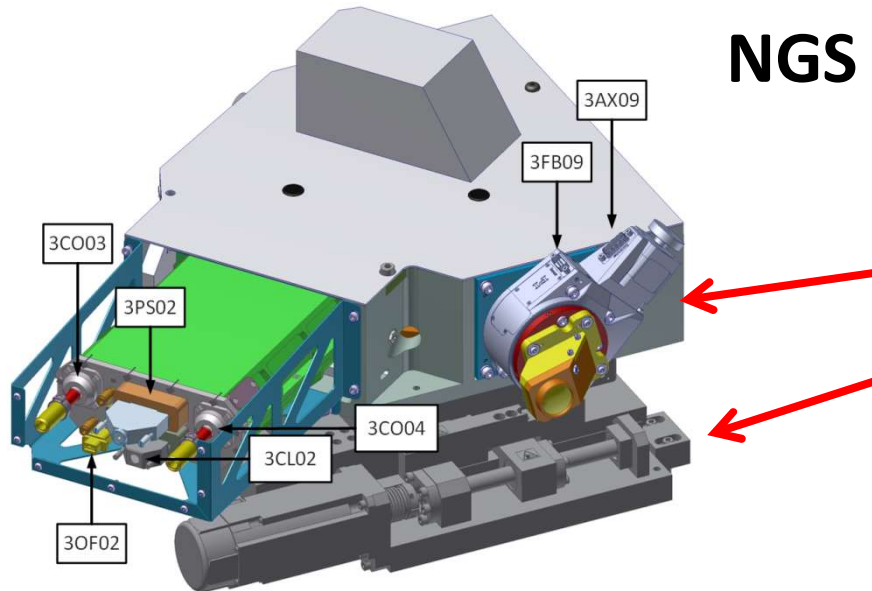


# ERIS

(Enhanced Resolution Imager and Spectrograph)



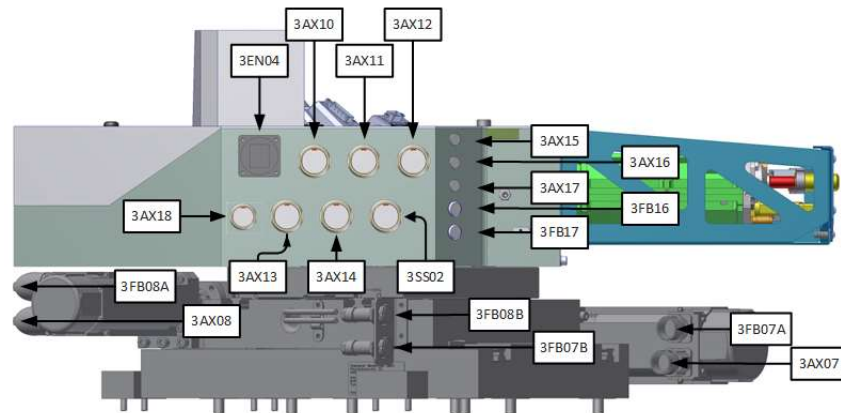
Combined Coordinated motion for XY  
NGS patrolling and tracking on the focal plane



Periscope optical input (y-scan  $\pm 32\text{mm} \rightarrow R=1'$ )

[AODEV-003] Differential tracking. In any AO mode, the NGS WFS must be able to perform one of several possible differential trackings (TS-ERIS-OPS-013, TS-ERIS-OPS-014):

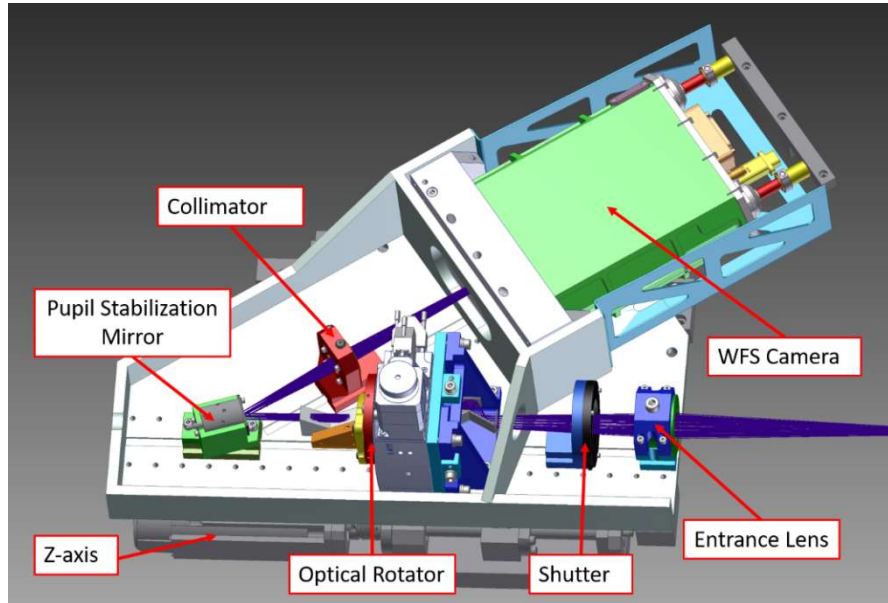
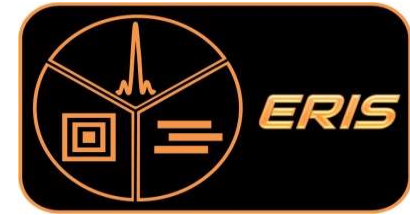
1. Any sidereal / non-sidereal combination between science target and AO reference star
2. Circular following of sidereal NGS when observing in pupil-tracking mode.



In both modes, the NGSX and NGPE need to move continuously during integration following a predefined trajectory. In both cases, the maximum speed of this movement will be 100 arcsec/hour (28 mas/sec), and the tolerance on positioning is  $\pm 1$  mas

# ERIS

(Enhanced Resolution Imager and Spectrograph)

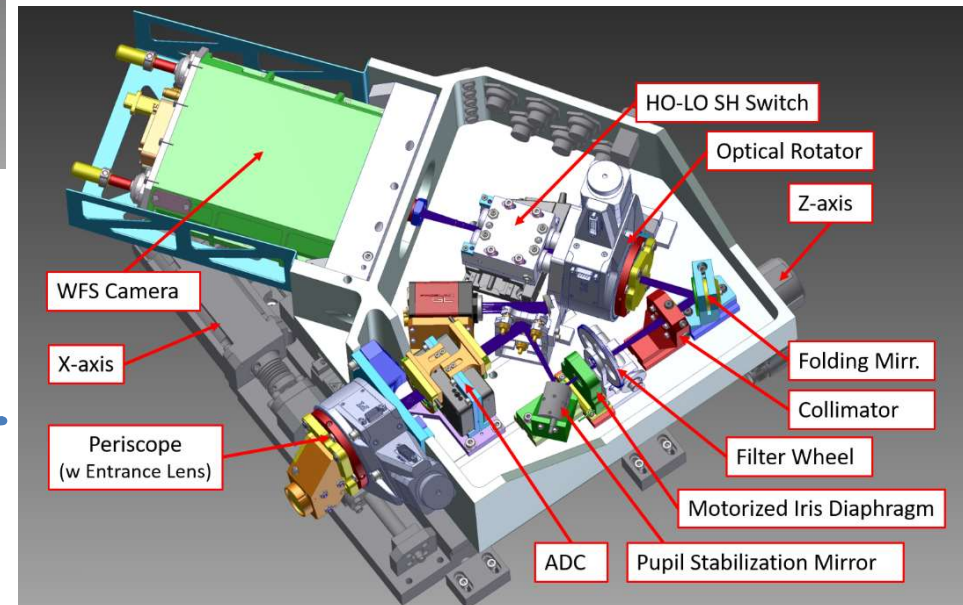


## LGS

- 3 motorized axes (1 tracking)
- 1 piezo (PSM)
- 1 beam shutter
- 1 CCD220
- Sensors (T+RH)

## NGS

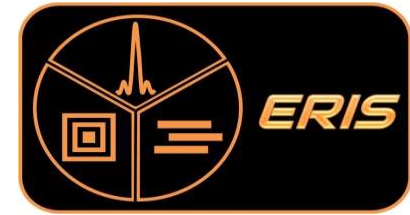
- 8 motorized axes (K-mirr + ADC + diff. tracking)
- Technical camera
- 2 piezo (PSM + Iris)
- CCD220
- Sensors (T+RH)





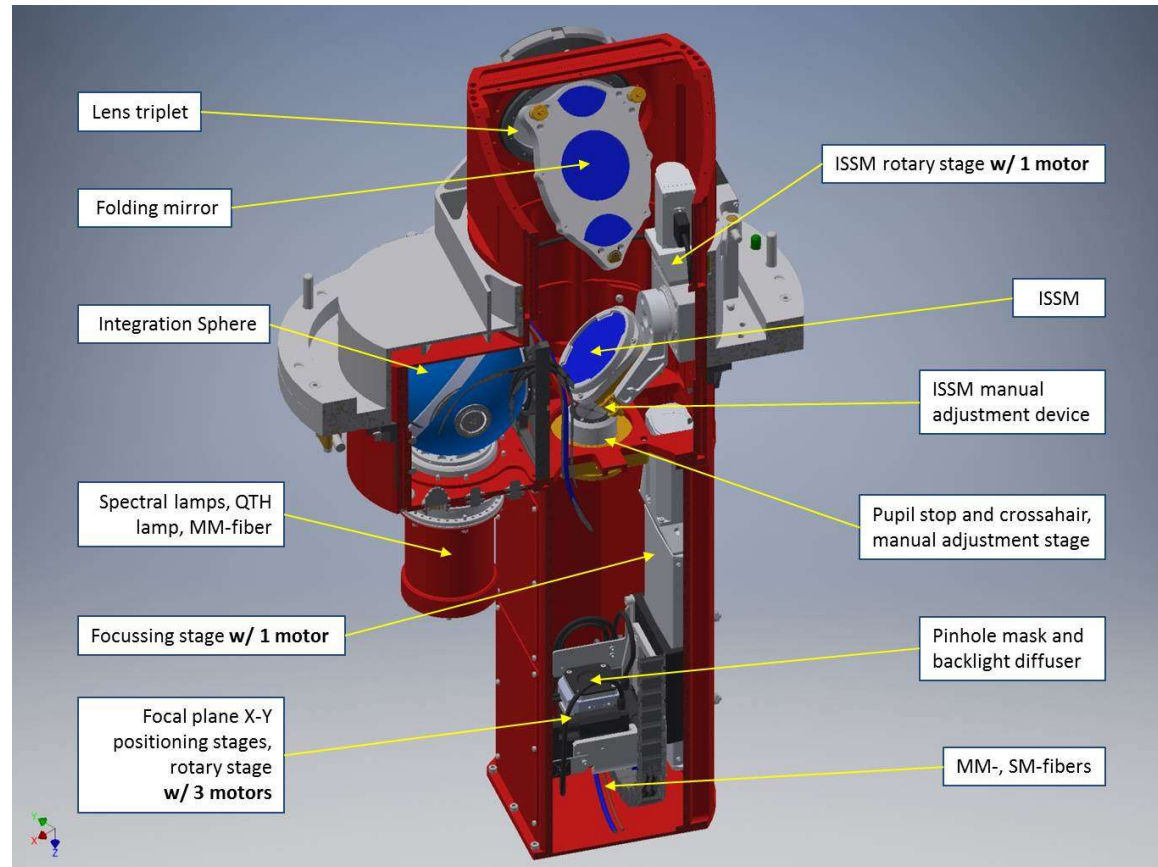
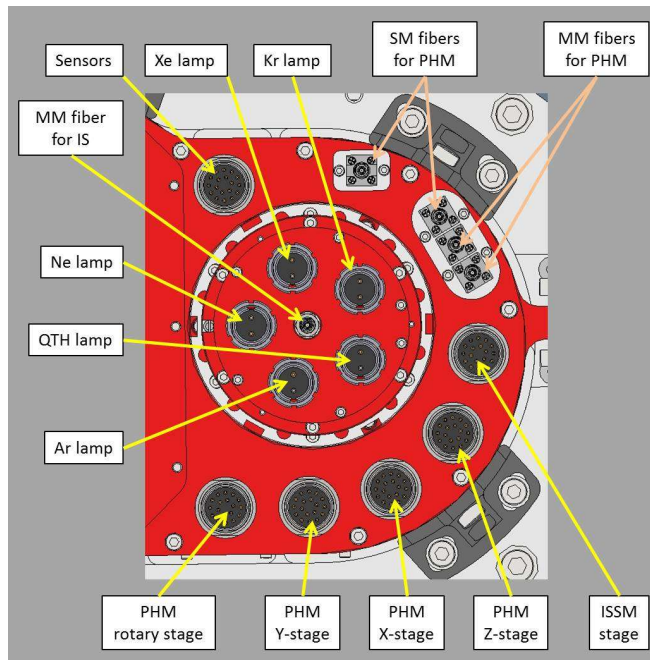
# ERIS

(Enhanced Resolution Imager and Spectrograph)



## CU

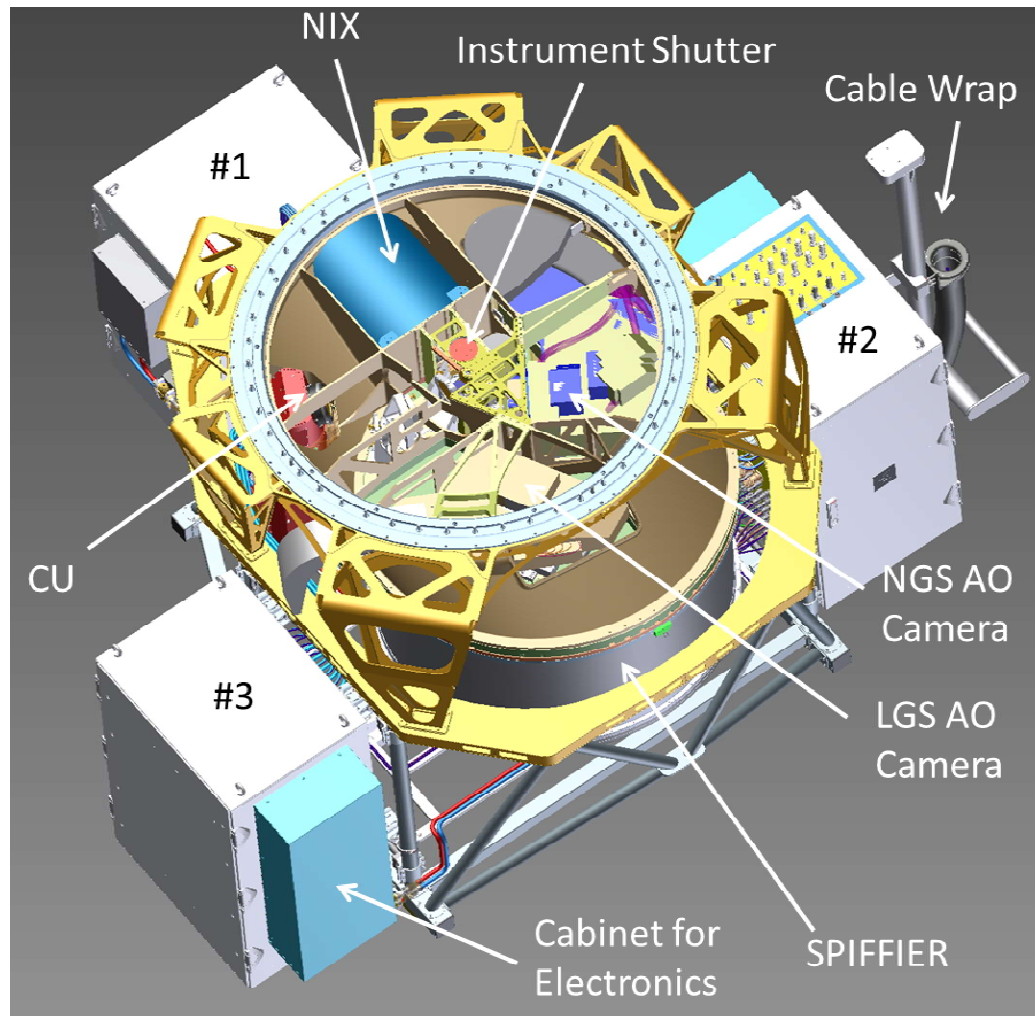
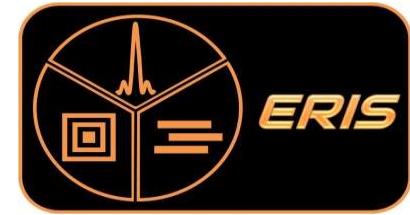
- 7 motorised axes
- 1 piezo (PHM rot)
- 5 spectral lamp
- 2 FF lamps (LDLS +QTH)
- Sensors (T+RH+Flux)



**FF+DL+Ex. Sources capabilities for  
NIX+SPIFFIER+AO (0.8-2.4 um)**

# ERIS

(Enhanced Resolution Imager and Spectrograph)



## Main Constraints (E-DAR)

- ✓ Volume at the optical bench
- ✓ Volume inside Cabinets
- ✓ Mass and Power budget
- ✓ Cable routing (size, bending)

## ESO Specs compliance

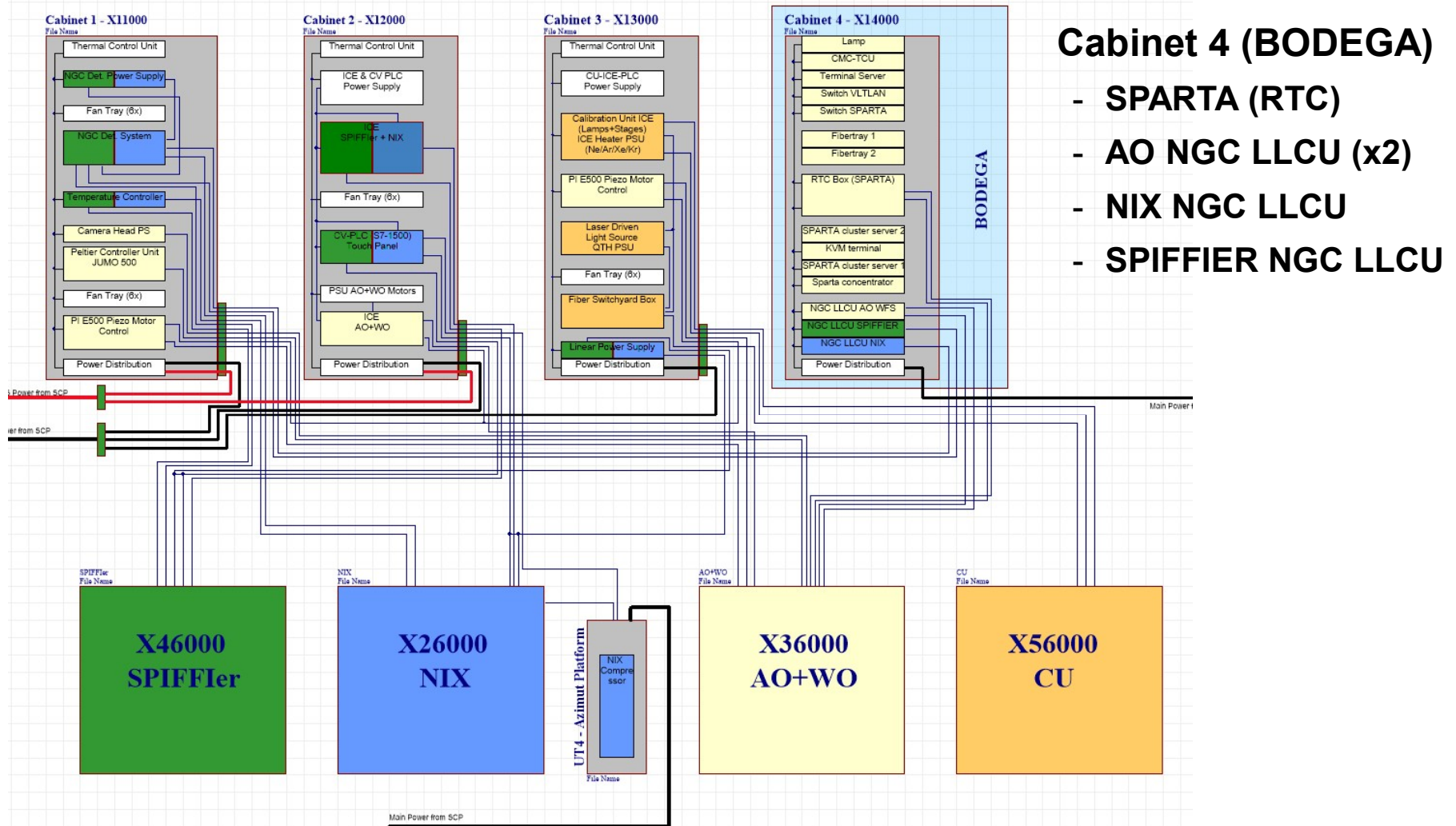
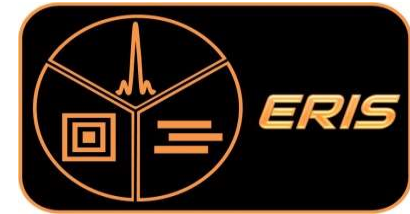
- ✓ Instrument Electronics
- ✓ Control Electronics
- ✓ Cables & Connectors
- ✓ Interfaces definition
- ✓ Documentation ...

## Troubles...

- Discontinued products from manufacturers pre-FDR, ...

# ERIS

(Enhanced Resolution Imager and Spectrograph)

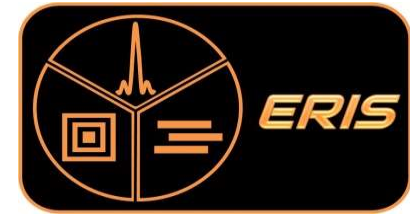


## Cabinet 4 (BODEGA)

- SPARTA (RTC)
- AO NGC LLCU (x2)
- NIX NGC LLCU
- SPIFFIER NGC LLCU

# ERIS

**(Enhanced Resolution Imager and Spectrograph)**



## Beckhoff EtherCAT (ESO/ULT Standard)

- ✓ PLC based Control System
- ✓ Embedded (Win) PC with RT kernel
- ✓ Flexible Distributed Architecture
- ✓ Fieldbus Communication
- ✓ TwinCAT/OpenMC motion control libraries



## Applied to ERIS Electronics:

- ✓ Stepper / DC / Brushless motors (terminals + EtherCAT servodrives)
- ✓ Several feedback type (SinCos, RS-422, SSI) for all axes
- ✓ Digital I/O for discrete control signal and status monitoring
- ✓ Analog I/O for continuous control signal and status monitoring
- ✓ IEEE5588 Time Synchronization
- ✓ Compact Architecture with modular control lines



# MAORY

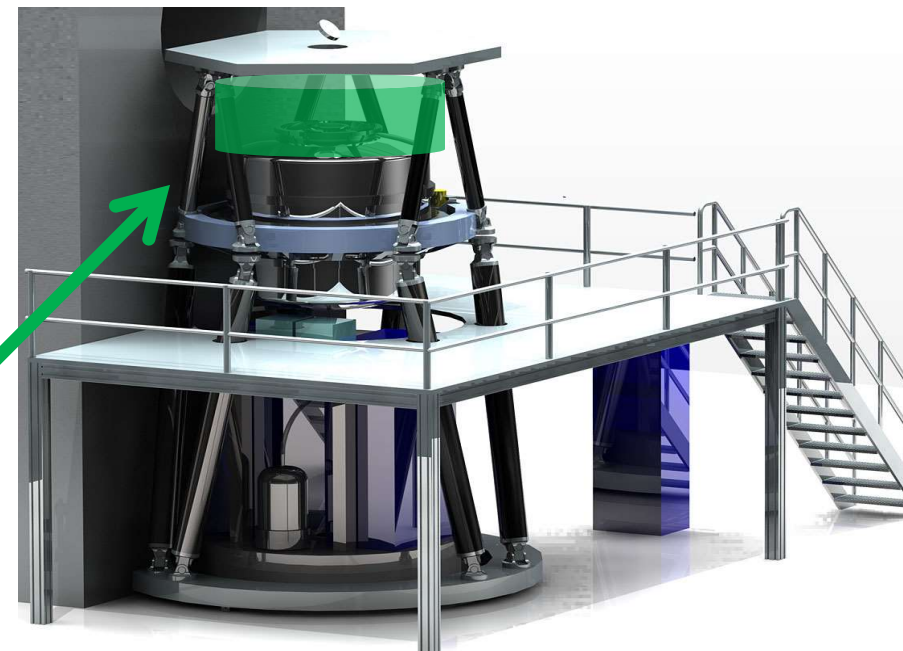
(Multi-conjugate Adaptive Optics Relay)



## MCAO

- 6 LGSs
- 3 Low Order and Reference (LORs)

*M. Lombini, ADONI2017*



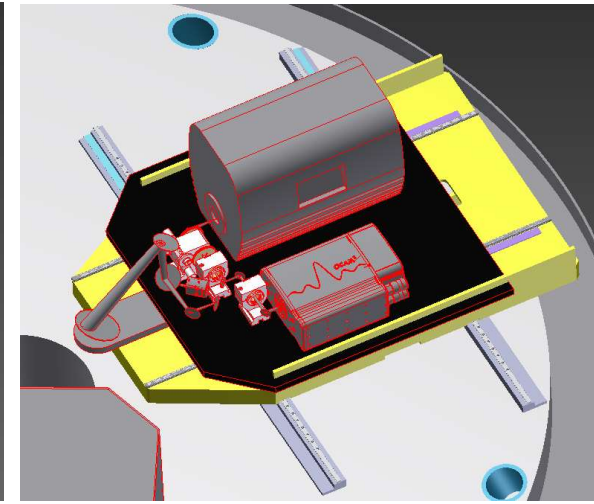
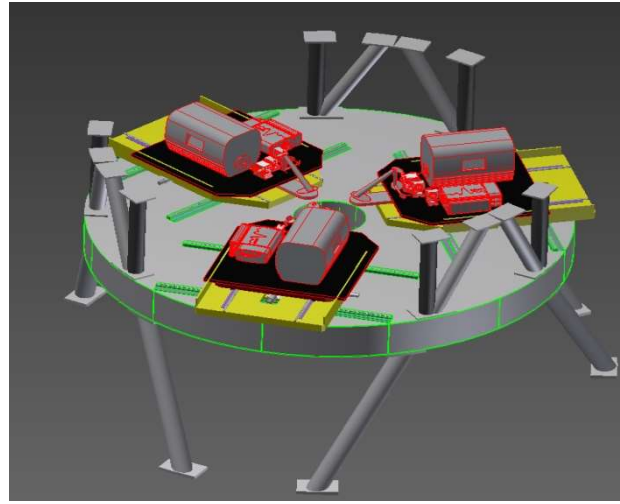
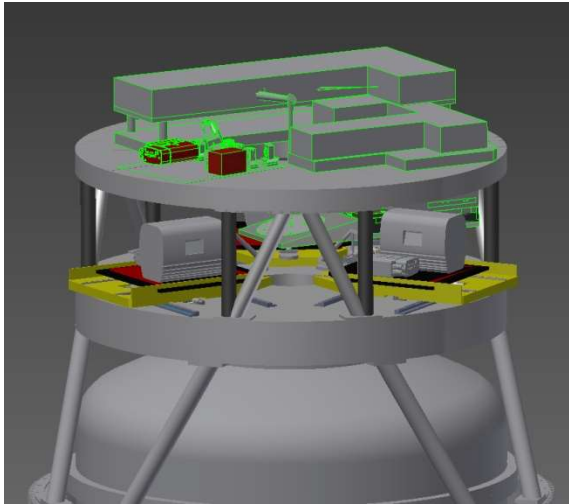
## Green Doughnut

- below the MAORY PF Relay
- 2.4x1 m (60%-40% SCAO-LORs)
- Co-rotating with MICADO

LORs OptoMech: *M. Bonaglia, ADONI 2017*

# MAORY

## (Multi-conjugate Adaptive Optics RelaY)



### LORs configuration:

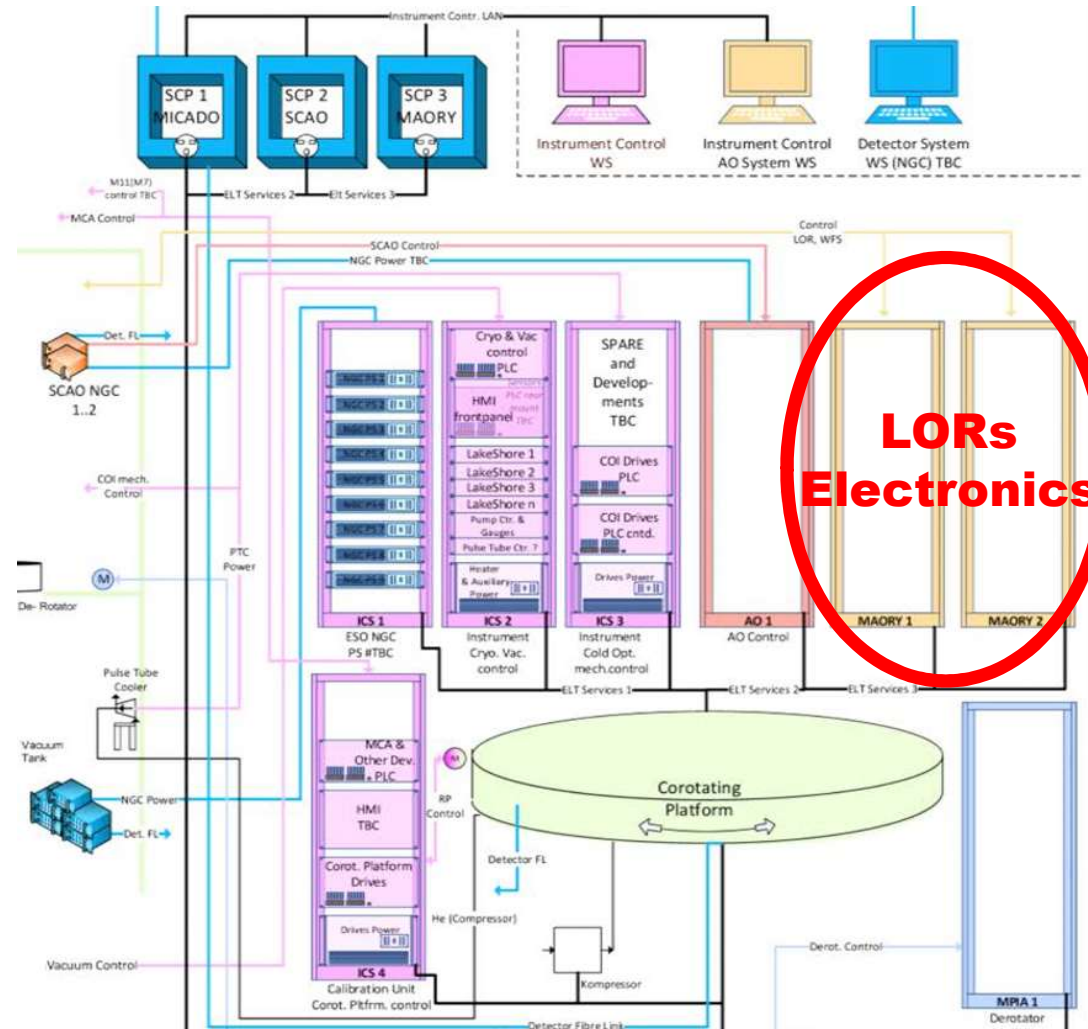
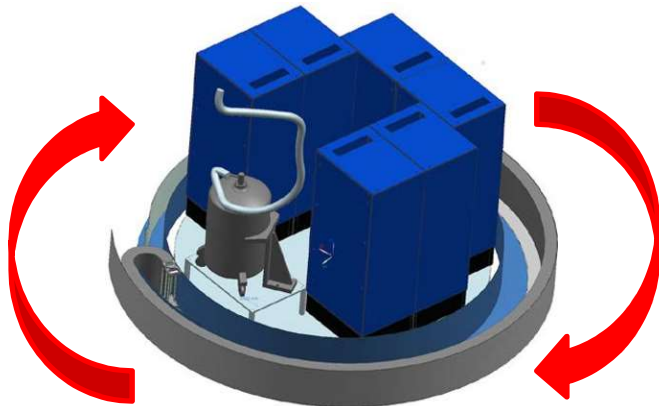
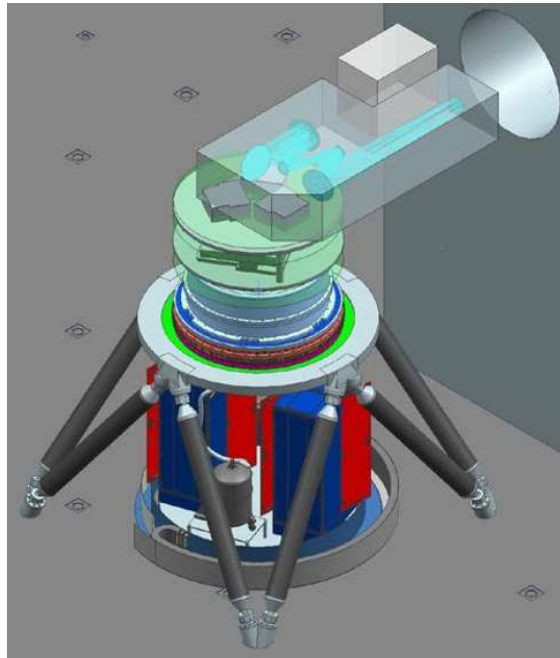
- ✓ Linear stage (focus )
- ✓ TT-mirror (piezo positioner)
- ✓ Atmospheric Dispersion Corrector (ADC)
- ✓ C-RED (infrared channel, SH 3x3)
- ✓ OCAM2 (visible channel, SH 10x10)
- ✓ XY support board (600x300 mm travel)

### Main Constraints for Electronics Design

- ✓ Volume and mass budget
- ✓ Heat dissipation, air conditioning
- ✓ Safety Interlocks to avoid collisions
- ✓ SCAO-LORs interdependencies
- ✓ Cables length (max 10m for cameras)
- ✓ Cables and pipes routing to PF
- ✓ ICE cabinets volume

# MAORY

(Multi-conjugate Adaptive Optics RelaY)





# Extending Collaborations within INAF

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## Summary

- **ERIS**

- ✓ AO (LGS+NGS) Electronics DAR+ICD to ESO
- ✓ Calibration Unit full design to ESO

**(FDR 29/05/2017)**

- **MAORY**

- ✓ LORs Electronics Design (in progress)
- ✓ LORs FMECA (first f2f meeting on 05/05/2017)

**(PDR 02/02/2018)**

*M. Cantiello* (science)  
*A. Di Cianno* (electronics)  
*M. Dolci* (system engineering)  
*A. Valentini* (mechanics)



# **Update on the ERIS-AO and MAORY-NGS Control Systems**

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