

**N-body techniques for
astrophysics:
Lecture 1 – General Introduction
Euler and Leapfrog methods**

A few words about the course:

The aim of this course:

**to learn the basic concepts of state-of-the-art
techniques of N-body simulations in astrophysics**

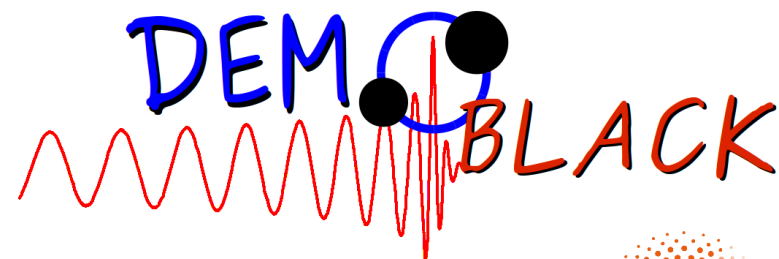
At the end of the course you should be able to:

- set up and run some very simple simulations;**
- critically read and understand a paper about astrophysical
N-body simulations**

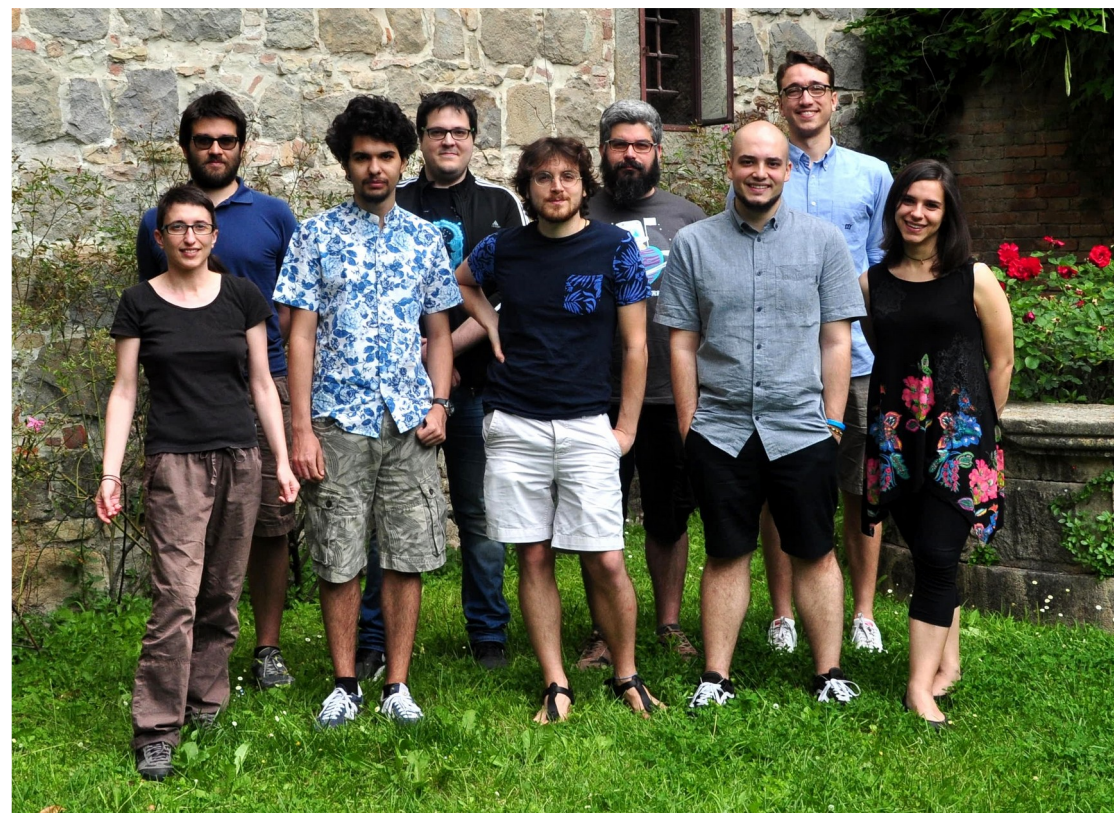
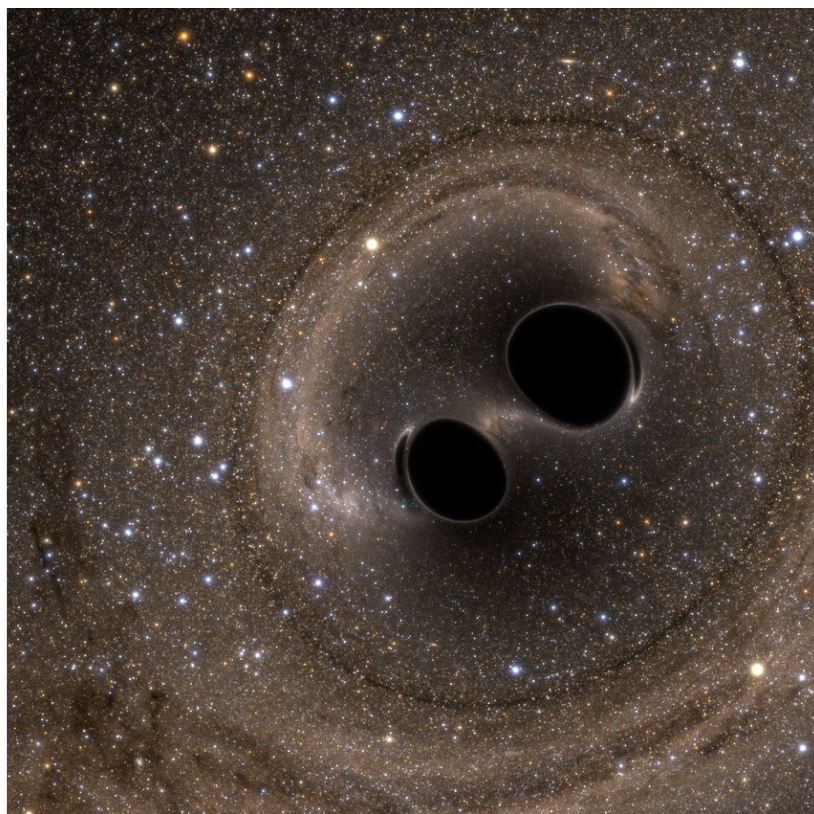
A few words about the course:

Address:

Prof. Michela Mapelli,
University of Padova
email michela.mapelli@unipd.it
<http://web.pd.astro.it/mapelli/>



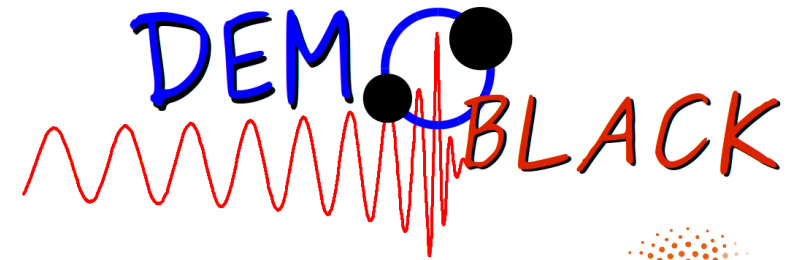
My team DEMOBLACK studies the formation channels of gravitational wave sources (black holes, neutron stars)



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1. Lectures will be published at

<http://web.pd.astro.it/mapelli/lectures.html>

and on Moodle

<https://elearning.unipd.it/dfa/enrol/index.php?id=439>

password: nb20Dot

2. Note: fill in the course evaluation sheet.

It is anonymous, it helps me improving the lectures

3. ASK MANY QUESTIONS, it is important for you and me!!!!

A few words about the course:

The EXAM:

- * Each lecture will consist of an explanation section
+ an exercise section
- * The final exam consists in the evaluation of the exercises
done during the lectures
- * You pass the exam if you do at least 60% of the exercises
- * If you want help with the exercises, please write your codes in
C, C++, python or fortran

The resources:

you will have a guest account on our server

```
ssh -p1022 course@scighera.oapd.inaf.it -X
```

```
cd your_last_name/
```

**BUT DON'T MESS UP WITH
OUR SERVER, PLS**

don't use the server
for something not related
to the course!



WHAT IS an N-Body SIMULATION?



WHAT IS an N-Body SIMULATION?

numerical integration of the forces acting on N particles for a time t

- *astrophysics*
- *fluid-dynamics*
- *molecular dynamics*
- ...

WHAT IS an N-Body SIMULATION ** IN ASTROPHYSICS **?

numerical integration of the force of GRAVITY acting on N particles for a time t

WHAT IS an N-Body SIMULATION?

numerical integration of Newton equation

$$\ddot{\vec{r}}_i = -G \sum_{j \neq i} m_j \frac{\vec{r}_i - \vec{r}_j}{|\vec{r}_i - \vec{r}_j|^3}$$

Or the equivalent system of $2 \times N \times \text{ndim}$ 1st ord. differential eqs

$$\left\{ \begin{array}{l} \dot{v}_i = - \sum \frac{G m_j}{r_{ij}^3} x_{ij} \\ \dot{x}_i = v_i \end{array} \right.$$

DOES IT HAVE ANALYTIC SOLUTION?

WHAT IS an N-Body SIMULATION?

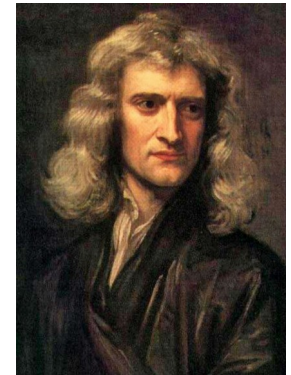
1687: Newton finds the equation

$$\ddot{\vec{r}}_i = -G \sum_{j \neq i} m_j \frac{\vec{r}_i - \vec{r}_j}{|\vec{r}_i - \vec{r}_j|^3}$$

1710: Bernoulli derives
analytic solution for $N = 2$

1885: a challenge was proposed
(to be answered before 21/01/1889)
in honor of the 60th birthday of
King Oscar II of Sweden and Norway.

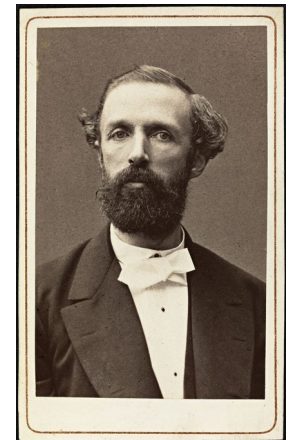
'Given a system of arbitrarily many mass points that attract each according to Newton's law, under the assumption that no two points ever collide, try to find a representation of the coordinates of each point as a series in a variable that is some known function of time and for all of whose values the series converges uniformly.'



Newton



Bernoulli



*Oscar II
of Sweden*

NOBODY FOUND THE SOLUTION

1991: Qiudong Wang finds a convergent power series
solution for a generic number of bodies.
Mathematically correct, but too difficult
and slow convergence



Q. Wang

WHAT IS an N-Body SIMULATION?

- Analytic problem only for $N = 2$ (and restricted $N = 3$)
- gravity force does not fade off (even far away particle interact)
 - calculation of a system of N particles cannot be decomposed in smaller pieces

$$\left\{ \begin{array}{l} \dot{v}_i = - \sum \frac{G m_j}{r_{ij}^3} x_{ij} \\ \dot{x}_i = v_i \end{array} \right.$$

A system of $2 \times N \times N_{\text{dim}}$ differential equations with NO known analytic solution

→ FIND A NUMERICAL SOLUTION

WHAT WOULD YOU DO?



WHAT IS an N-Body SIMULATION?

TAYLOR EXPANSION

$$x_i(t + \Delta t) = x_i(t) + \frac{dx_i(t)}{dt} \Delta t + \frac{1}{2} \frac{d^2x_i(t)}{dt^2} \Delta t^2 + O(\Delta t^3)$$

$$v_i(t + \Delta t) = v_i(t) + \frac{dv_i(t)}{dt} \Delta t + \frac{1}{2} \frac{d^2v_i(t)}{dt^2} \Delta t^2 + O(\Delta t^3)$$

Predicting
time $t + \Delta t$
with info at
time t

Truncation order
gives error order

A 1st order method has Δt order errors
A 2nd order method has Δt^2 order errors
A 3rd order method has Δt^3 order errors

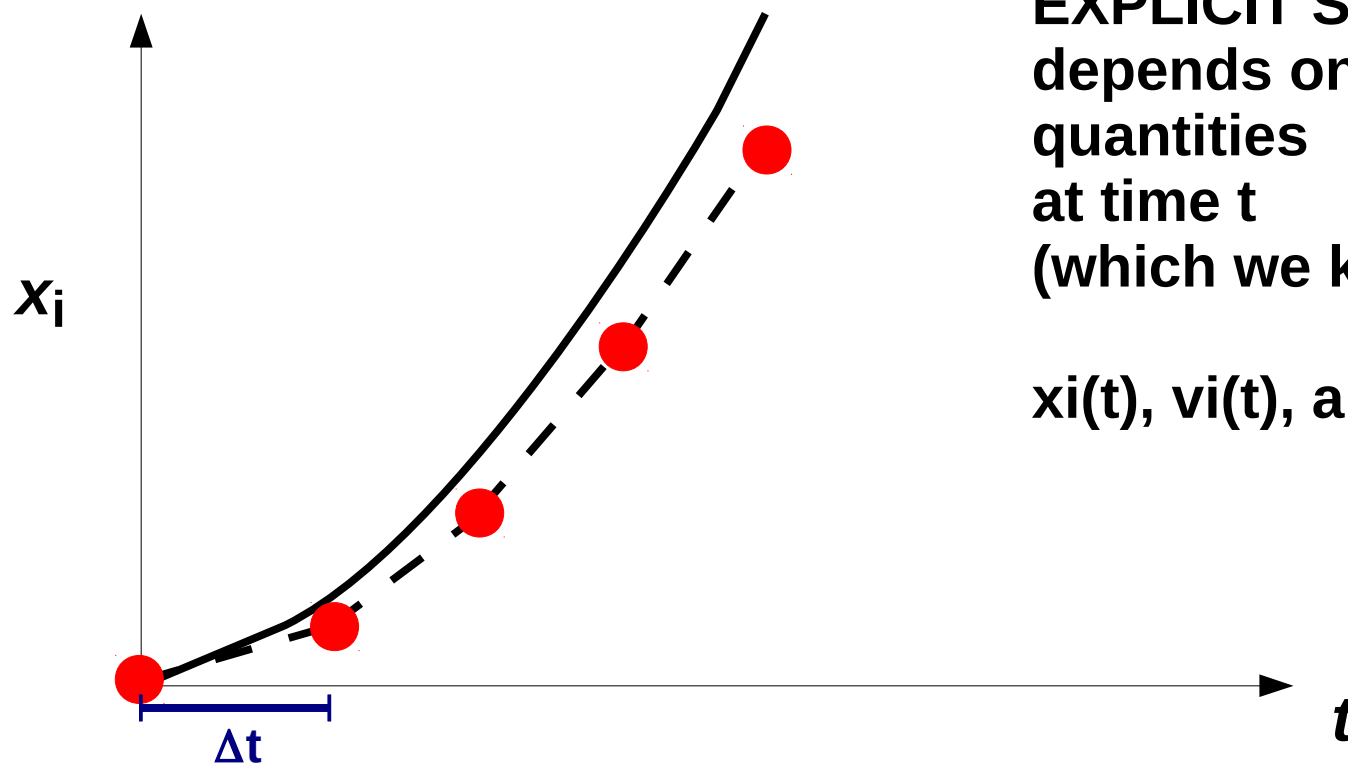
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EULER METHOD:

Taylor expansion at 1st order

$$x_i(t + \Delta t) = x_i(t) + \frac{dx_i(t)}{dt} \Delta t$$

$$v_i(t + \Delta t) = v_i(t) + \frac{dv_i(t)}{dt} \Delta t$$



EXPLICIT SCHEME =
depends only on
quantities
at time t
(which we know)

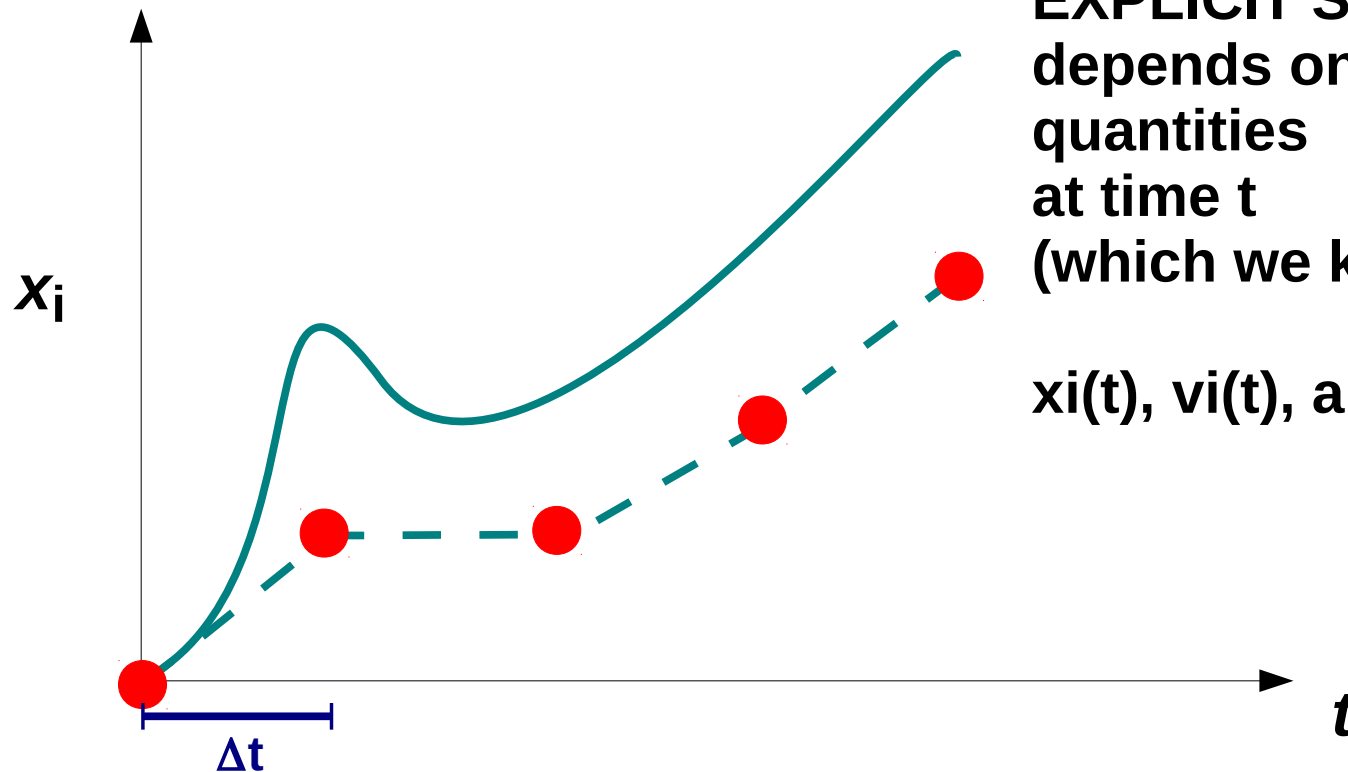
$x_i(t), v_i(t), a_i(t)$

EULER METHOD:

Taylor expansion at 1st order

$$x_i(t + \Delta t) = x_i(t) + \frac{dx_i(t)}{dt} \Delta t$$

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EXPLICIT SCHEME =
depends only on
quantities
at time t
(which we know)

$x_i(t), v_i(t), a_i(t)$

EULER METHOD:

Exercise # 1:

calculate motion of two bodies
in a binary system with Euler method

Initial conditions:

$$X1 = 1.0$$

$$Y1 = 1.0$$

$$Vx1 = -0.5$$

$$Vy1 = 0.0$$

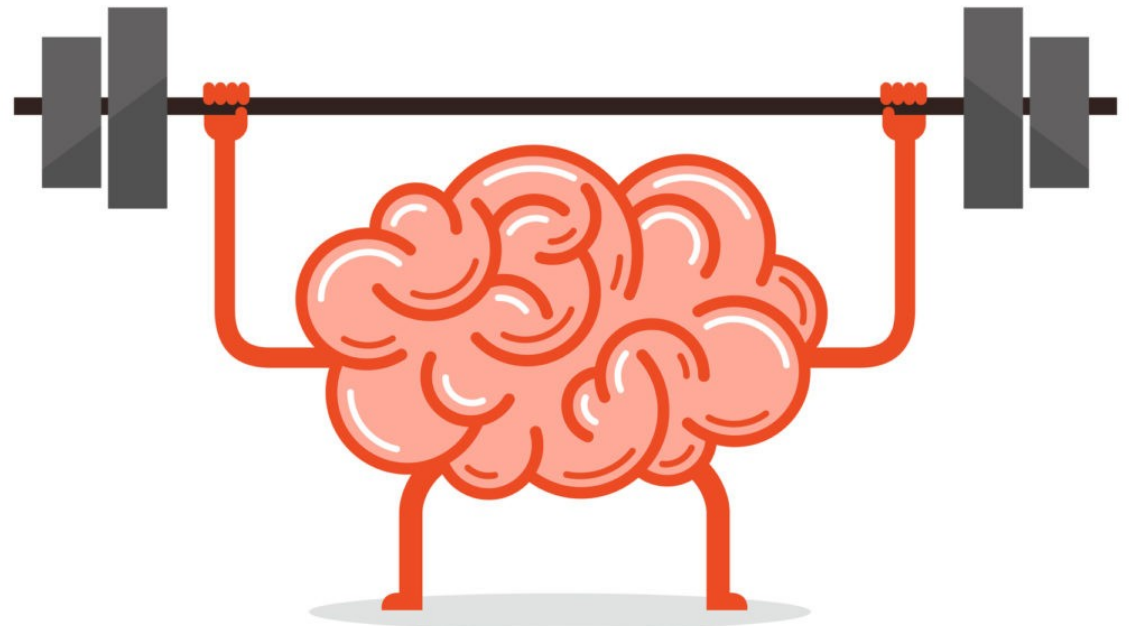
$$X2 = -1.0$$

$$Y2 = -1.0$$

$$Vx2 = 0.5$$

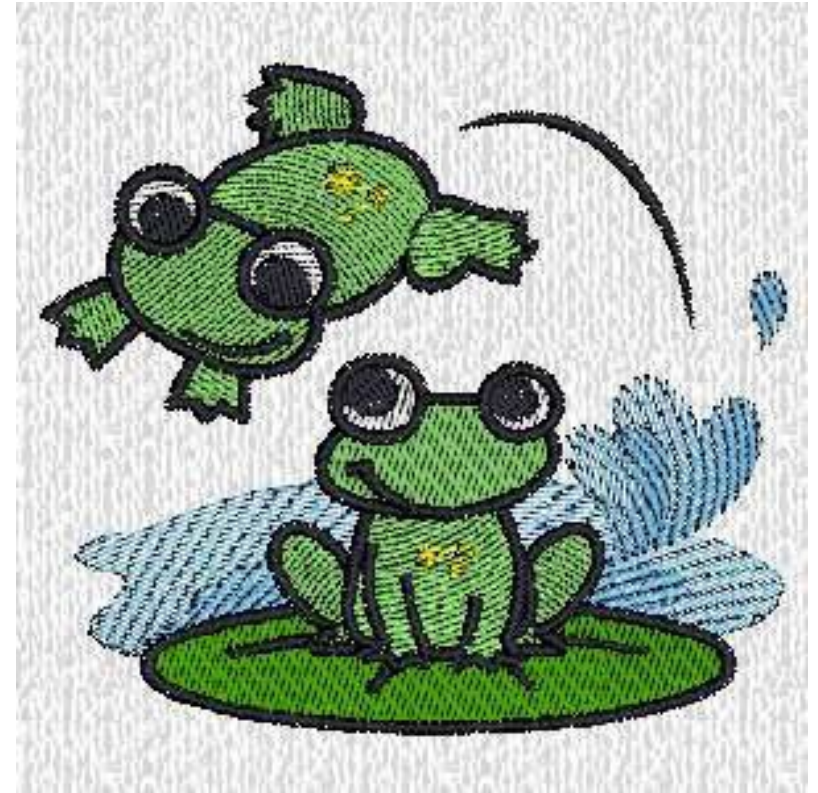
$$Vy2 = 0.0$$

Assume $m1 = m2 = 1$, $G = 1$



LEAPFROG METHOD:

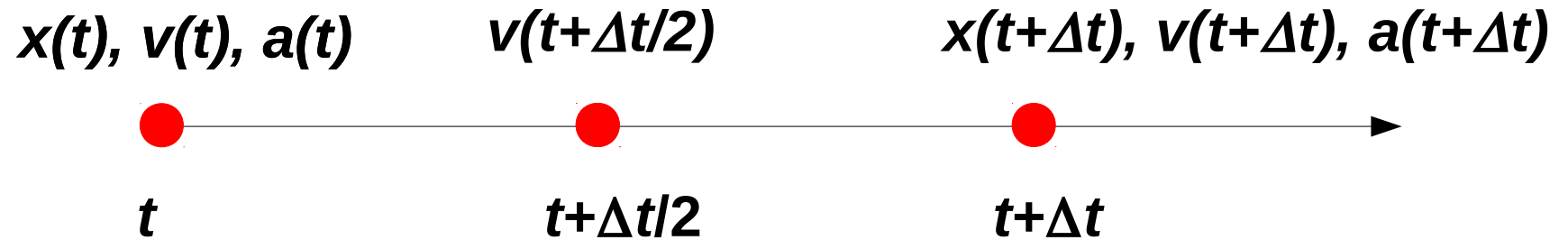
The name comes from the leapfrog game



IDEA: evaluation of velocity and position jumps like little happy frogs within a timestep..

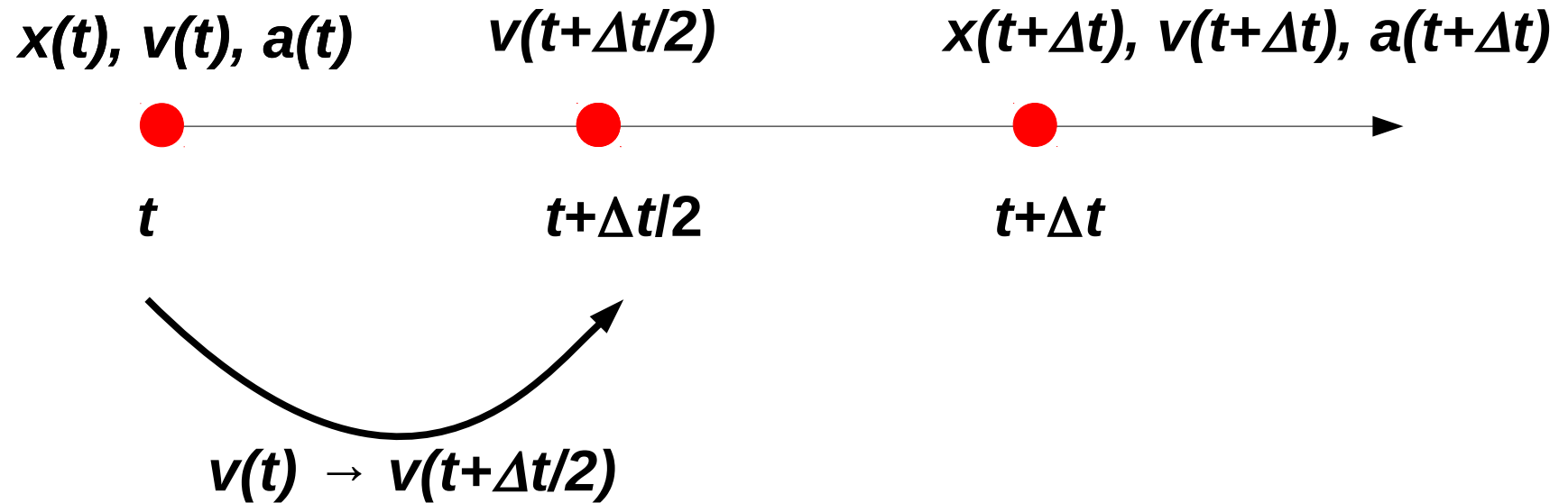
LEAPFROG METHOD:

same as Euler but evaluated in between a timestep



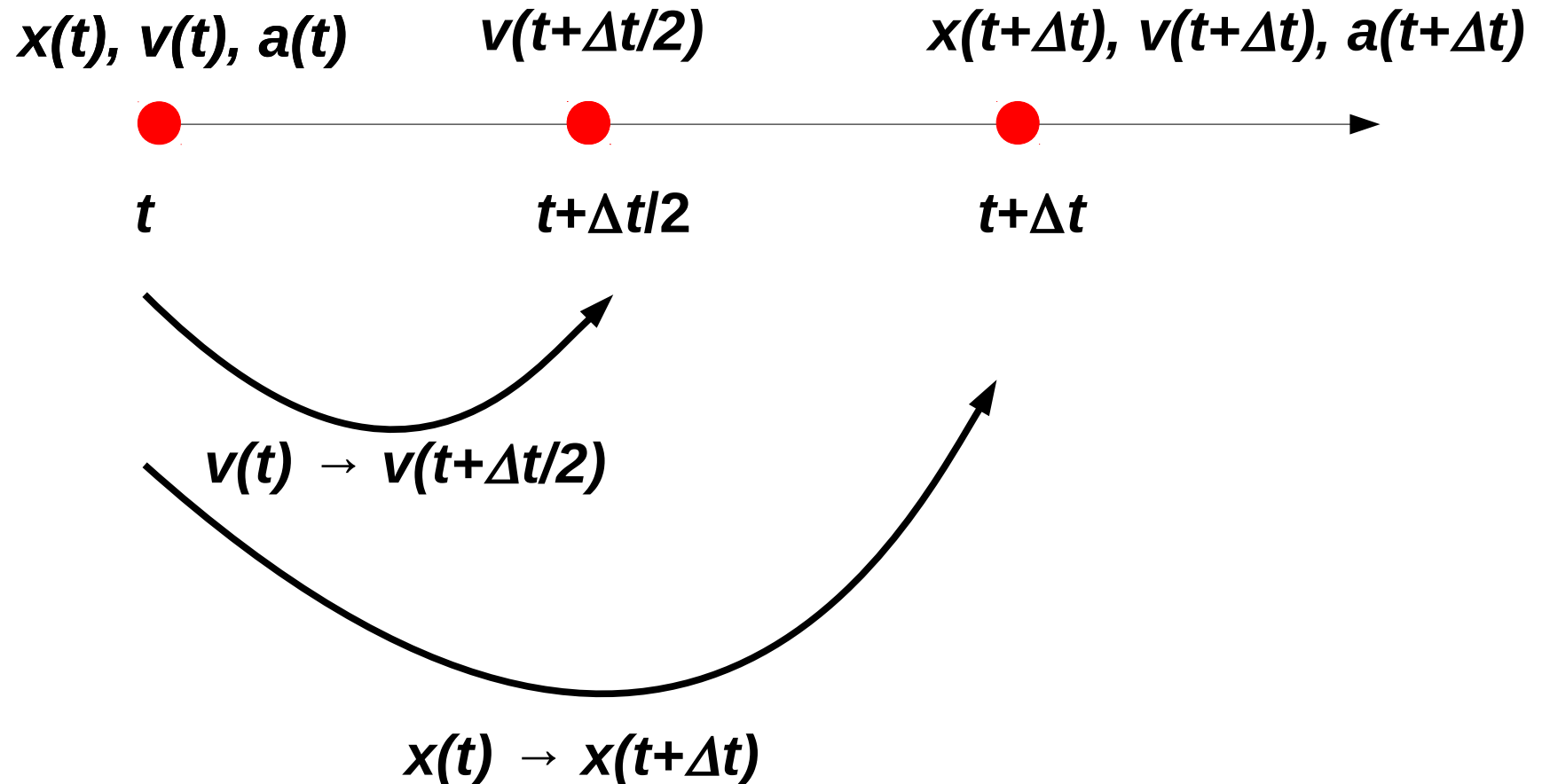
LEAPFROG METHOD:

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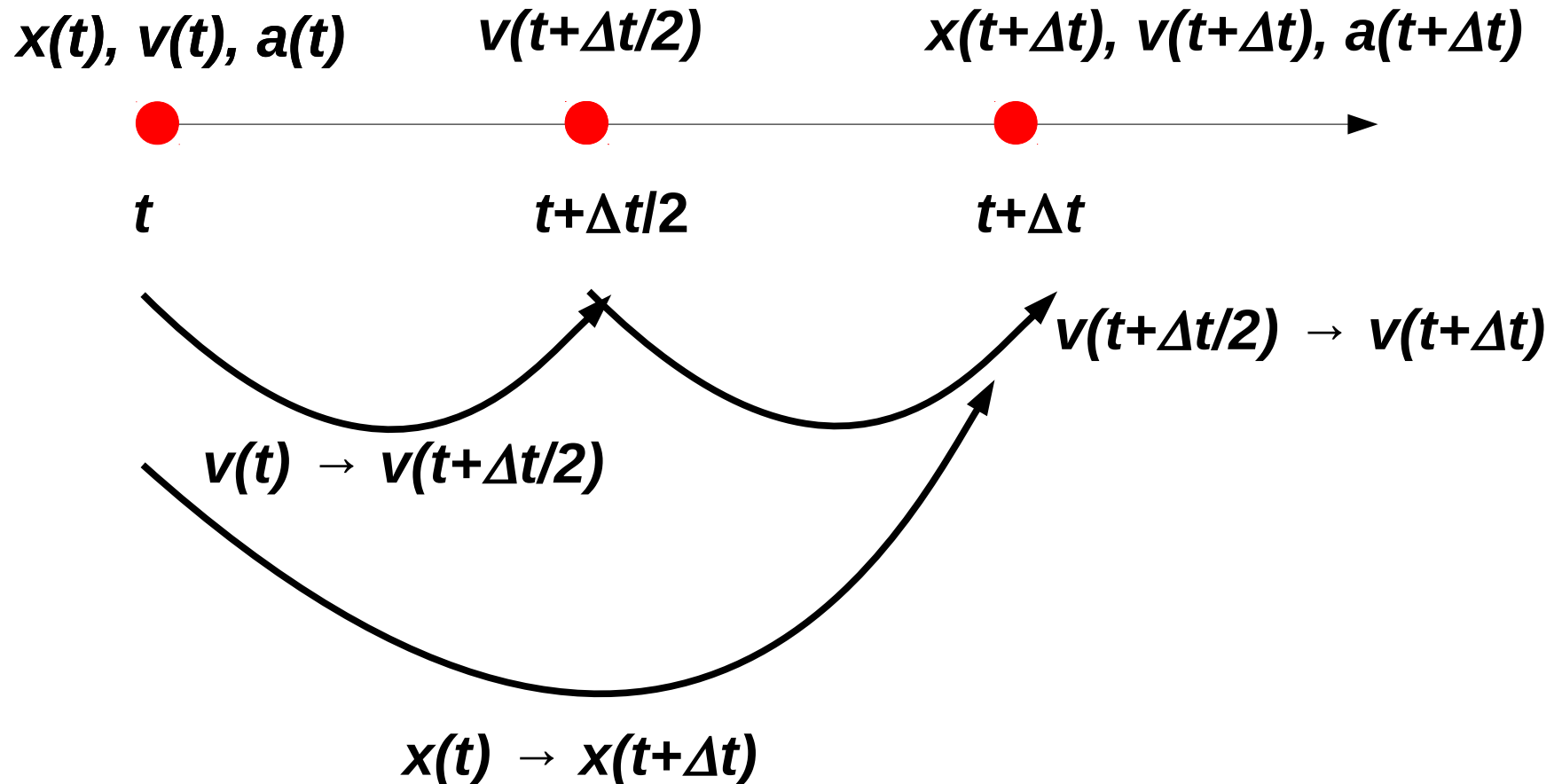
LEAPFROG METHOD:

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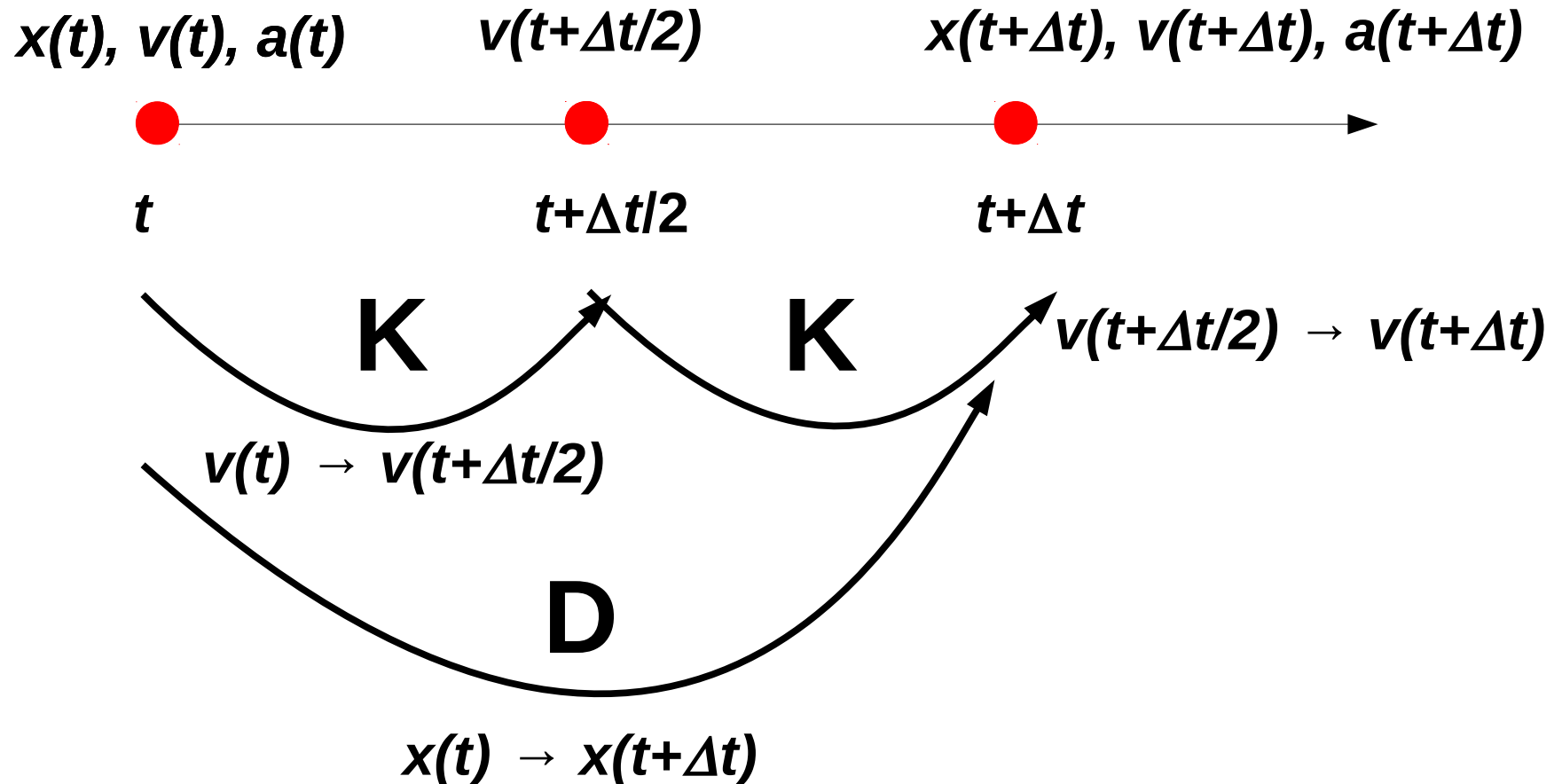
LEAPFROG METHOD:

same as Euler but evaluated in between a timestep



LEAPFROG METHOD:

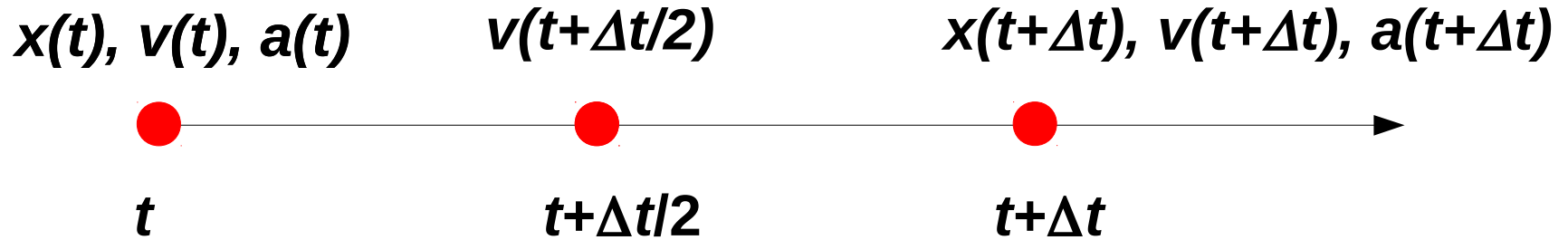
same as Euler but evaluated in between a timestep



Kick + Drift + Kick (KDK) scheme

LEAPFROG METHOD:

same as Euler but evaluated in between a timestep



$$v\left(t + \frac{\Delta t}{2}\right) = v(t) + \frac{\Delta t}{2} a(t)$$

$$x(t + \Delta t) = x(t) + v\left(t + \frac{\Delta t}{2}\right) \Delta t$$

$$v(t + \Delta t) = v\left(t + \frac{\Delta t}{2}\right) + \frac{1}{2} \Delta t \underline{a(t + \Delta t)}$$

$$x(t + \Delta t) = x(t) + v(t) \Delta t + \frac{1}{2} a(t) \Delta t^2$$

→

$$v(t + \Delta t) = v(t) + \frac{1}{2} a(t) \Delta t + \frac{1}{2} a(t + \Delta t) \Delta t$$

LEAPFROG METHOD:

Exercise # 2:

calculate motion of two bodies
in a binary system with Leapfrog method

Initial conditions:

$$X1 = 1.0$$

$$Y1 = 1.0$$

$$Vx1 = -0.5$$

$$Vy1 = 0.0$$

$$X2 = -1.0$$

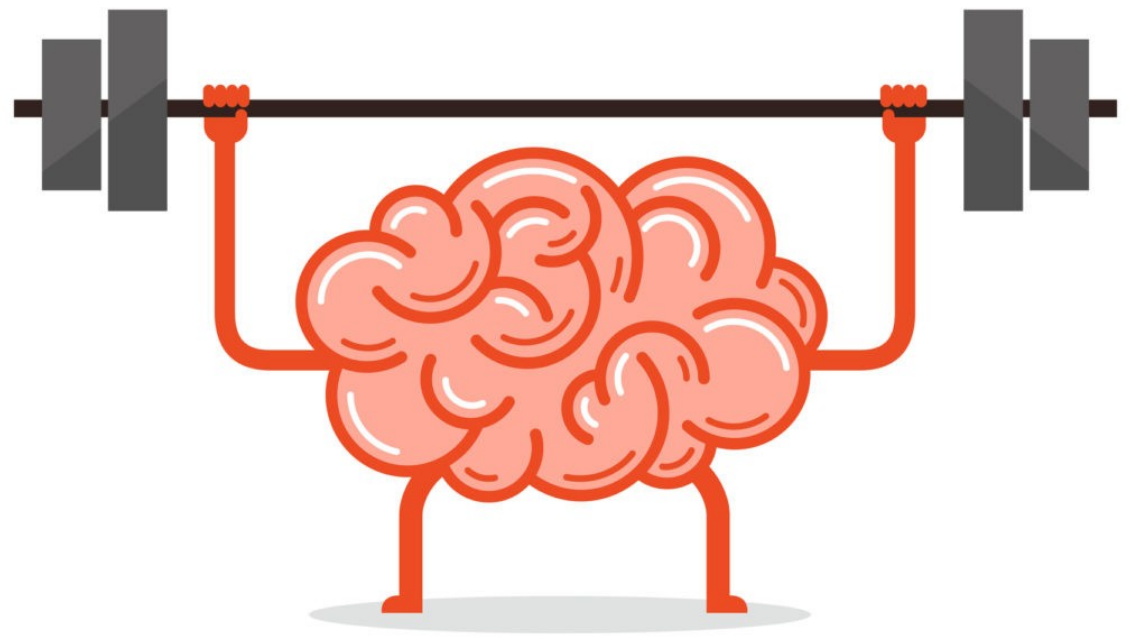
$$Y2 = -1.0$$

$$Vx2 = 0.5$$

$$Vy2 = 0.0$$

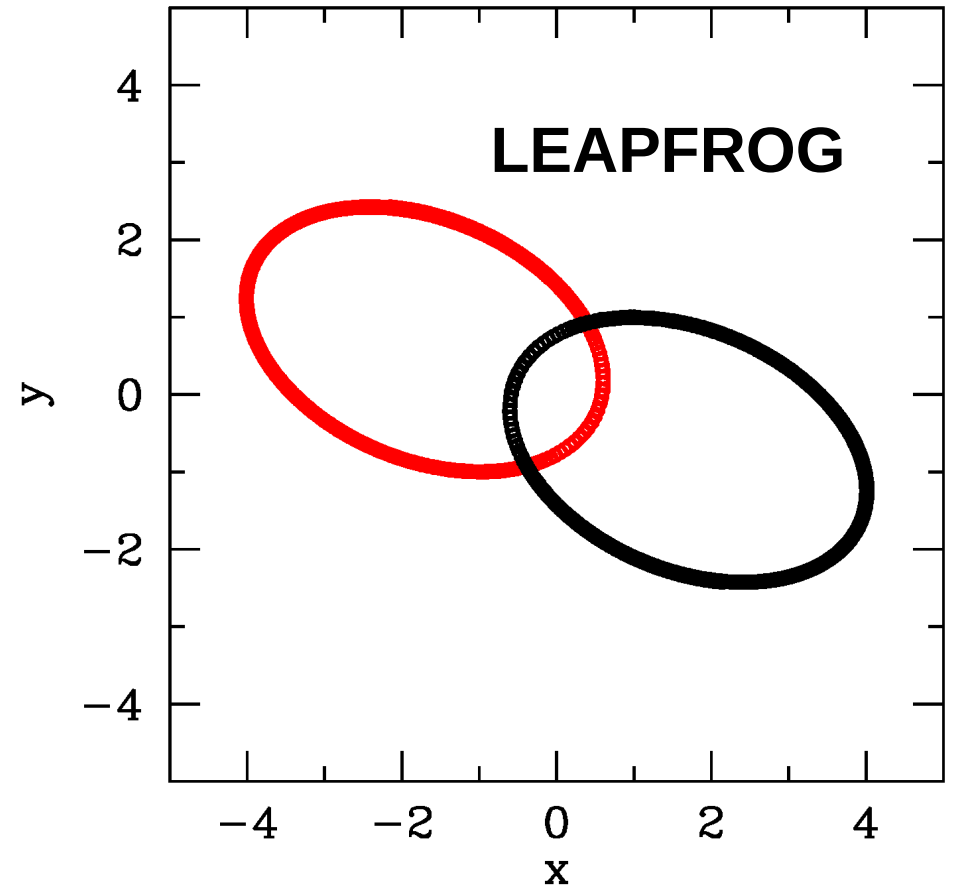
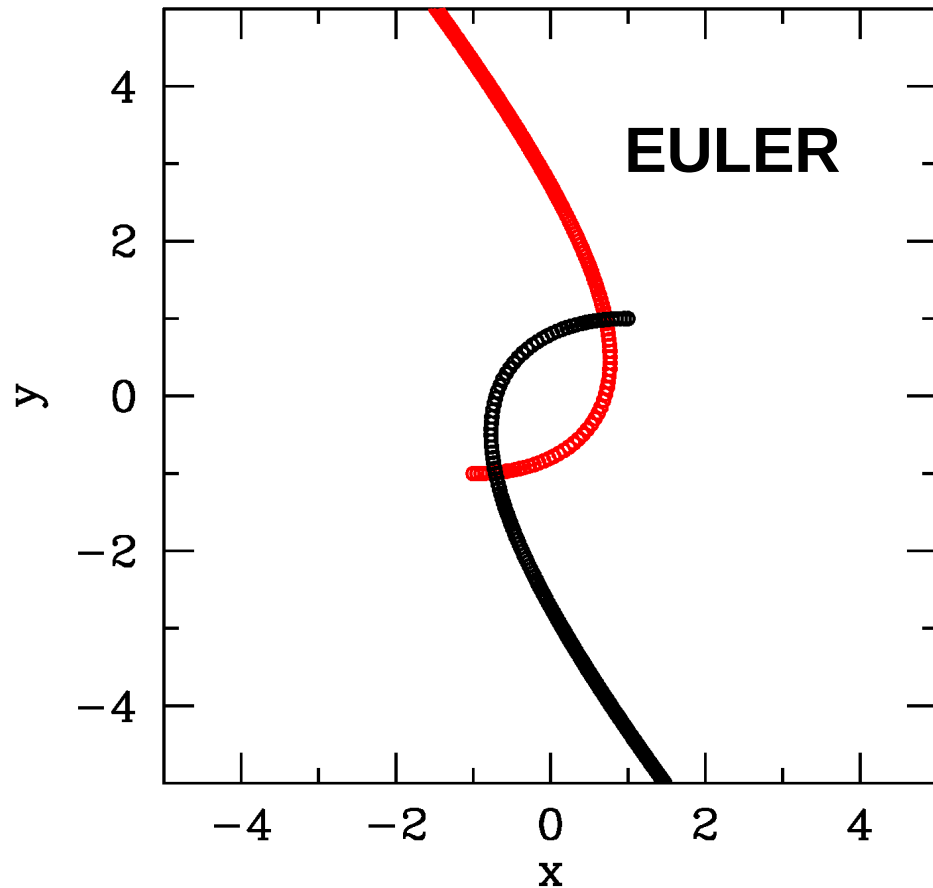
Assume $m1 = m2 = 1$, $G = 1$

and calculate energy conservation in Leapfrog and Euler case



EULER vs LEAPFROG METHOD: a simple test

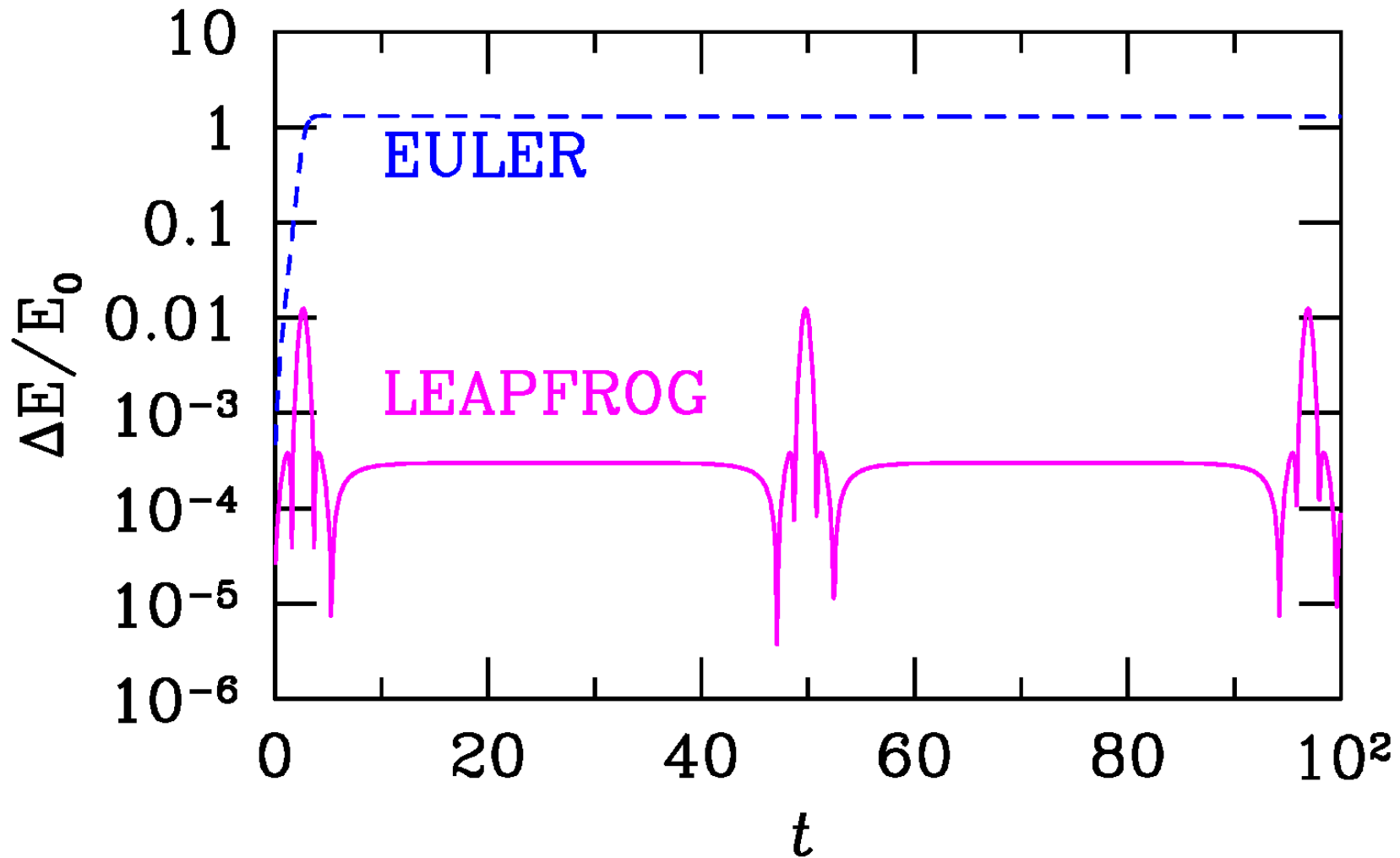
Both Euler and Leapfrog are 2d order methods, but..



Same initial conditions: integration of a Keplerian binary

EULER vs LEAPFROG METHOD: a simple test

Both Euler and Leapfrog are 2d order methods, but..



Same initial conditions: integration of a Keplerian binary

N-body UNITS:

MOST N-body codes work in N-body units

since Gravity is the main force, choose units so that $G=1$

DEFINITION OF CODE UNITS (SO THAT $G=1$)

$$6.67 \times 10^{-8} \frac{\text{cm}^3}{\text{s}^2 \text{g}} \approx G = \frac{U_e^3}{U_t^2 U_m}$$

$$\Rightarrow U_t^2 = \frac{U_e^3}{G U_m}$$

N-body UNITS:

DEFINITION of M_{SCALE} , T_{SCALE} , L_{SCALE}

$$M_{\text{SCALE}} := \frac{1}{U_m}$$

$$T_{\text{SCALE}} := \frac{1}{U_t}$$

$$L_{\text{SCALE}} := \frac{1}{U_L}$$

N-body UNITS:

FROM CODE UNITS TO PHYSICAL UNITS and VICEVERSA:

$$M_{\text{code}} = M_{\text{phys}} \quad M_{\text{scale}} = \frac{M_{\text{phys}}}{M_{\text{TOT}}}$$

mass of particles in the code (mass in code units) = mass of particles in physical units
 $M_{\text{scale}} := \frac{1}{m_{\text{TOT}}}$

$$T_{\text{code}} = T_{\text{phys}} \quad T_{\text{scale}} = \frac{T_{\text{phys}}}{0.25 \text{ Myr}}$$

time in code units = time in physical units
 $T_{\text{scale}} := \frac{1}{U_t} \approx \frac{1}{0.25 \text{ Myr}}$
im are example

$$L_{\text{code}} = L_{\text{phys}} \quad L_{\text{scale}} = \frac{L_{\text{phys}}}{1 \text{ pc}}$$

length in code units = length in physical units
 $L_{\text{scale}} := \frac{1}{U_L} \approx \frac{1}{1 \text{ pc}}$
im are example 1 pc

$$V_{\text{code}} = V_{\text{phys}} \quad \frac{L_{\text{scale}}}{T_{\text{scale}}} = V_{\text{phys}} \frac{U_t}{U_L} = V_{\text{phys}} \frac{0.25 \text{ Myr}}{1 \text{ pc}}$$

velocity in code units = velocity in physical units

N-body UNITS:

What is the advantage of N-body units?



N-body UNITS:

What is the advantage of N-body units?

- 1. choosing right units helps the integrator!
Rounding errors' importance is different
if input quantities are 10^{-30} , 10^{45}
rather than 1, 2**
- 2. your N-body problems is perfectly SCALABLE
(unless stellar evolution or gas are involved,
i.e. dissipative processes)**

N-body UNITS:

Exercise # 3:

Rewrite codes of exercises #1 and #2
in N-body units for the following system

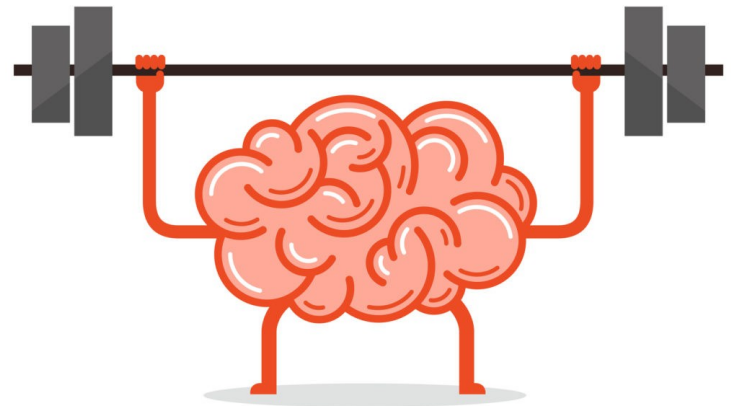
$$M1 = 1.989e33 \text{ g}$$

$$M2 = 5.972e27 \text{ g}$$

semi-major axis of
the minor body = $1.496e13 \text{ cm}$

$$\text{eccentricity} = 0$$

Remember that $G = 6.667e-8 \text{ cm}^3 \text{ g}^{-1} \text{ s}^{-2}$



N-body UNITS:

Exercise # 3b:

Write a Leapfrog scheme for N particles with $N > \sim 10$ and arbitrary initial conditions

