

Dynamics of Stars and Black Holes in Dense Stellar Systems:

Lecture I:

STAR CLUSTERS AS COLLISIONAL SYSTEMS

- 1. Relevant timescales of dense stellar systems**
- 2. Early evolution of dense star systems**
- 3. Equilibrium models**
- 4. N-body simulations of star clusters + star evolution**

Dynamics of Stars and Black Holes in Dense Stellar Systems:

Slides at

<http://web.pd.astro.it/mapelli/lectures.html>

Michela Mapelli

<http://web.pd.astro.it/mapelli/>

michela.mapelli@oapd.inaf.it

1. Relevant timescales of dense stellar systems:

- what is the utility of a timescale?
- what is two-body relaxation and its timescale?
- what is dynamical friction and its timescale?

NOTE:

the blue box

in these slides will be a question for you

1. Relevant timescales of dense stellar systems:

Timescale:

- * characteristic time for a process to take place
- * the shorter it is, the more efficient the process
- * comparing timescales we can understand what will occur in a system

1. Relevant timescales of dense stellar systems:

Timescale:

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TWO-BODY RELAXATION TIMESCALE:

Time for a star to lose memory of its initial velocity completely, as an effect of gravitational encounters

AKA

Time needed for a system to relax (=reach relaxation) by two-body encounters

1. Relevant timescales of dense stellar systems:

COLLISIONAL/COLLISIONLESS?

Collisional systems are systems where interactions between particles are EFFICIENT with respect to the lifetime of the system

Collisionless systems are systems where interactions are negligible

When is a system collisional/collisionless?

When its RELAXATION TIMESCALE is short wrt lifetime

Gravity is a LONG-RANGE force → cumulative influence on each star/body of distant stars/bodies is important: often more important than influence of close stars/bodies

Let us consider a IDEALIZED galaxy of N identical stars with mass m , size R and uniform density

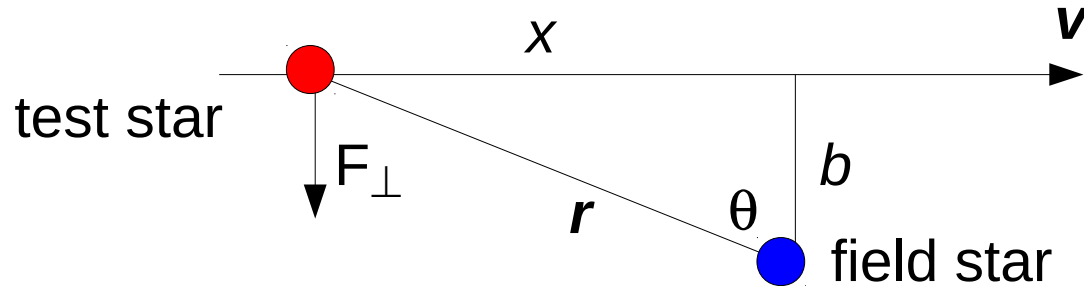
Let us focus on a single star that crosses the system

How long does it take for this star to change its initial velocity completely?,

$$\frac{\delta \vec{v}_{\perp}}{\vec{v}} \sim 1 \quad \text{where} \quad \delta v_{\perp} = \text{component of velocity perpendicular to the initial velocity vector}$$

1. Relevant timescales of dense stellar systems:

Let us assume that our test star passes close to a field star at relative velocity v and impact parameter b



The test star and the perturber interact with a force

$$\begin{aligned} F_{\perp} &= \frac{G m^2}{r^3} r_{\perp} = \frac{G m^2}{r^2} \cos \theta \\ &= \frac{G m^2 b}{(x^2 + b^2)^{3/2}} = \frac{G m^2}{b^2} \frac{1}{\left[1 + \left(\frac{vt}{b}\right)^2\right]^{3/2}} \end{aligned}$$


1. Relevant timescales of dense stellar systems:

From Newton's second law $m \dot{v}_{\perp} = F_{\perp}$

we get that the perturbation of the velocity integrated over one entire encounter is

$$\delta v_{\perp} = \int_{-\infty}^{+\infty} \frac{F_{\perp}}{m} dt = \frac{G m}{b^2} \int_{-\infty}^{+\infty} \frac{dt}{\left[1 + \left(\frac{vt}{b}\right)^2\right]^{3/2}}$$

$$= \frac{G m}{b v} \int_{-\infty}^{+\infty} \frac{ds}{(1 + s^2)^{3/2}} = \frac{2 G m}{b v}$$


$$dt = \frac{b}{v} d\left(\frac{vt}{b}\right)$$

Accel. at closest approach	Force duration
$2 \left(\frac{G m}{b^2}\right)$	$\left(\frac{b}{v}\right)$

1. Relevant timescales of dense stellar systems:

Now we account for all the particles in the system

Surface density of stars in idealized galaxy: $\frac{N}{\pi R^2}$

Number of interactions per unit element:

$$\delta n = \frac{N}{\pi R^2} 2 \pi b db$$

We define

$$\delta v_{\text{TOT}}^2 = \delta n \delta v_{\perp}^2 = \frac{2 N}{R^2} \left(\frac{2 G m}{b v} \right)^2 b db$$

And we integrate over all the possible impact parameters...

1. Relevant timescales of dense stellar systems:

And we integrate over all the possible impact parameters...

$$\delta v_{\text{TOT}}^2 = 8 N \left(\frac{G m}{R v} \right)^2 \int_{b_{\text{min}}}^R \frac{db}{b}$$

$$\delta v_{\text{TOT}}^2 = 8 N \left(\frac{G m}{R v} \right)^2 \ln \frac{R}{b_{\text{min}}}$$

* low integration limit: smallest b to avoid close encounter $\delta v_{\perp} \sim v$

$$v = \frac{2 G m}{b_{\text{min}} v} \implies b_{\text{min}} = \frac{2 G m}{v^2}$$

* top integration limit: size R of the system

1. Relevant timescales of dense stellar systems:

$$\delta v_{\text{TOT}}^2 = 8 N \left(\frac{G m}{R v} \right)^2 \ln \left(\frac{R v^2}{2 G m} \right)$$

Typical speed of a star in a virialized system

$$N m v^2 = \frac{G (N m)^2}{R} \implies v^2 = \frac{G}{N m} R$$

Replacing v

$$\frac{\delta v_{\text{TOT}}^2}{v^2} = \frac{8 \ln N}{N}$$

1. Relevant timescales of dense stellar systems:

$$v^2 = \frac{N}{8 \ln N} \delta v_{\text{TOT}}^2$$

Number of crossings of the system for which $\frac{\delta v_{\text{TOT}}^2}{v^2} = 1$

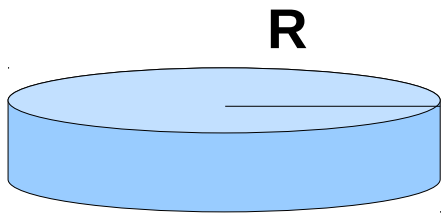
$$n_{\text{cross}} \cancel{\delta v_{\text{TOT}}^2} = v^2 = \frac{N}{8 \ln N} \cancel{\delta v_{\text{TOT}}^2}$$

1. Relevant timescales of dense stellar systems:

Number of crossings of the system for which $\frac{\delta v_{\text{TOT}}^2}{v^2} = 1$

$$n_{\text{cross}} = \frac{N}{8 \ln N}$$

CROSSING TIME = time needed to cross the system
(also named DYNAMICAL TIME)



$$t_{\text{cross}} = \frac{R}{v}$$

$$= \sqrt{\frac{R^3}{G M}} = \frac{1}{\sqrt{G \rho}}$$

1. Relevant timescales of dense stellar systems:

RELAXATION TIME = time necessary for stars in a system to lose completely the memory of their initial velocity

$$t_{\text{rlx}} = n_{\text{cross}} t_{\text{cross}} = \frac{N}{8 \ln N} \frac{R}{v}$$

with more accurate calculations, based on diffusion coefficients (Spitzer & Hart 1971):

$$t_{\text{rlx}} = 0.34 \frac{\sigma^3(r)}{G^2 m_* \rho_*(r) \ln \Lambda}$$

1. Relevant timescales of dense stellar systems:

The two expressions are almost equivalent

If we put $\sigma = v = (G N m / R)^{1/2}$
and $\rho \mu N m / R^3$
and $\ln \Lambda \sim \ln N$

$$t_{\text{rlx}} \propto \frac{\sigma^3}{G^2 m \rho \ln \Lambda} \sim \frac{(G N m R^{-1})^{3/2}}{G^2 N m^2 R^{-3} \ln N}$$

$$\sim G^{-1/2} N^{1/2} m^{-1/2} R^{3/2} \ln N^{-1}$$

$$\left(\frac{v}{v} \right)$$

multiply and
divide per v

$$\sim \left(\frac{N R}{G m} \right)^{1/2} v \ln N^{-1} \frac{R}{v}$$

Rearrange and
substitute again v

$$\sim \frac{N}{\ln N} \frac{R}{v}$$

1. Relevant timescales of dense stellar systems:

USEFUL BACK-OF-THE-ENVELOPE expression for t_{rlx} :

If we put $v = (G N m / R)^{1/2}$

$$t_{rlx} \sim \frac{N}{\ln N} \frac{R}{v} \sim \frac{N}{\ln N} \frac{R^{3/2}}{(G N m)^{1/2}}$$

$$\sim \frac{N^{1/2} R^{3/2}}{(G m)^{1/2} \ln N} \sim \frac{(m N)^{1/2} R^{3/2}}{G^{1/2} m \ln N}$$

$$\sim 15 \text{ Myr} \left(\frac{M_{TOT}}{10^4 M_{\odot}} \right)^{1/2} \left(\frac{R}{1 \text{ pc}} \right)^{3/2} \left(\frac{1 M_{\odot}}{m} \right)$$

1. Relevant timescales of dense stellar systems:

RELAXATION & THERMALIZATION

*Relaxation and thermalization are almost **SYNONYMOUS!***

* **Thermalization:**

- *is one case of relaxation*
- *is defined for gas (because needs definition of T), but can be used also for stellar system (kinetic extension of T)*
- *is the **process of particles reaching thermal equilibrium through mutual interactions** (involves concepts of equipartition and evolution towards maximum entropy state)*
- *has velocity distribution function: **Maxwellian** velocity*

* **Relaxation:**

- *is defined not only for gas*
- *is the **process of particles reaching equilibrium through mutual interactions** (but there might be many processes driving to relaxation not only 2-body relaxation)*

1. Relevant timescales of dense stellar systems:

Which is the typical t_{rlx} of stellar systems?

EXERCISE: CALCULATE t_{rlx} for

- the disk of the Milky Way
- the core of a globular cluster

1. Relevant timescales of dense stellar systems:

Which is the typical t_{rlx} of stellar systems?

- * **Globular clusters, dense young star clusters, nuclear star clusters** (far from SMBH influence radius)

$R \sim 1-10 \text{ pc}$, $N \sim 10^{3-6}$ stars, $v \sim 1-10 \text{ km/s}$

$$t_{\text{rlx}} \sim 10^{7-10} \text{ yr}$$

→ **COLLISIONAL**

- * **Galaxy field/discs**

$R \sim 10 \text{ kpc}$, $N \sim 10^{10}$ stars, $v \sim 100-500 \text{ km/s}$

$$t_{\text{rlx}} \gg \text{Hubble time}$$

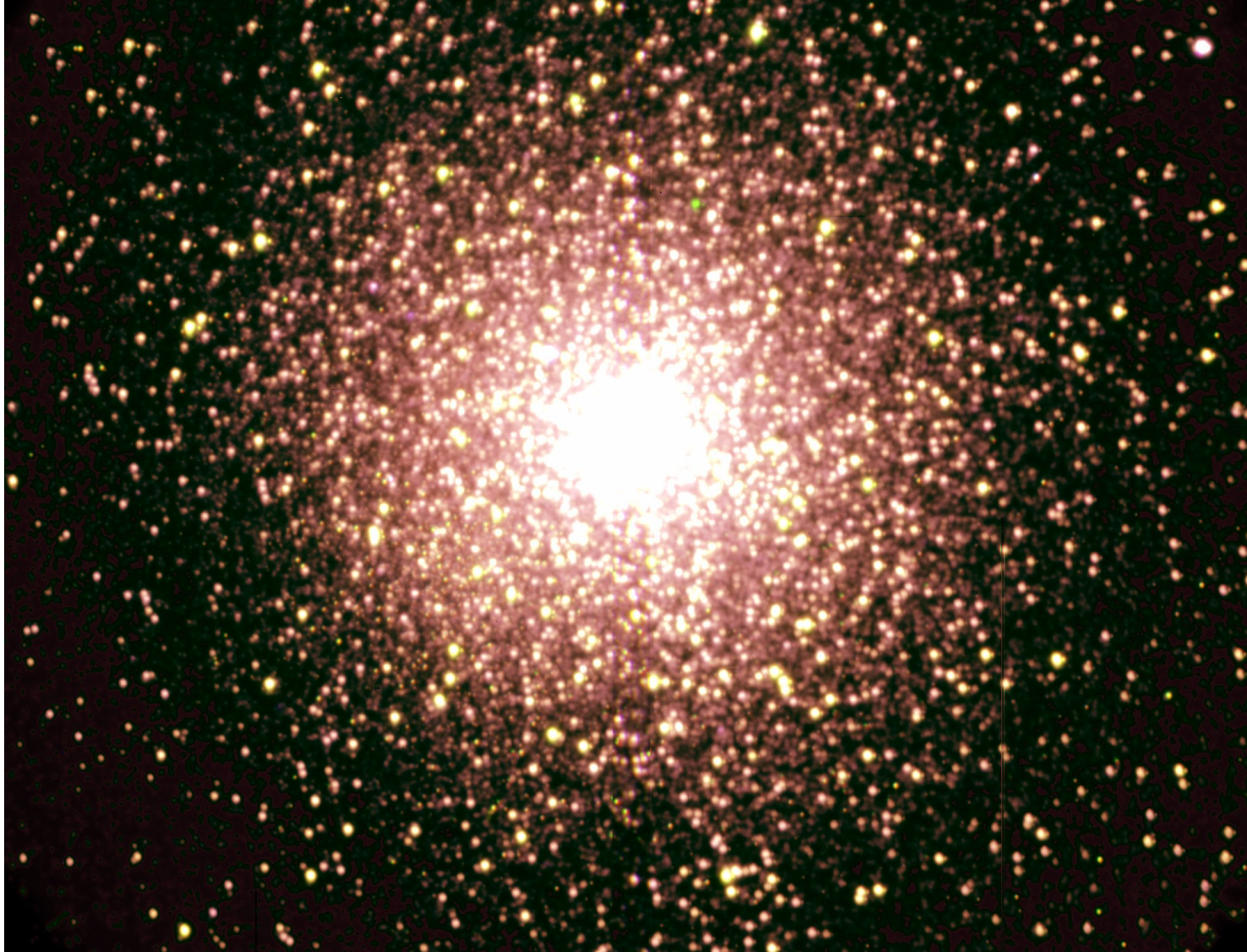
→ **COLLISIONLESS**

described by collisionless Boltzmann equation

$$\frac{df}{dt} = \frac{\partial f}{\partial t} + \sum_{i=1,6} \frac{\partial x_i}{\partial t} \frac{\partial f}{\partial x_i} = 0$$

1. Relevant timescales of dense stellar systems:

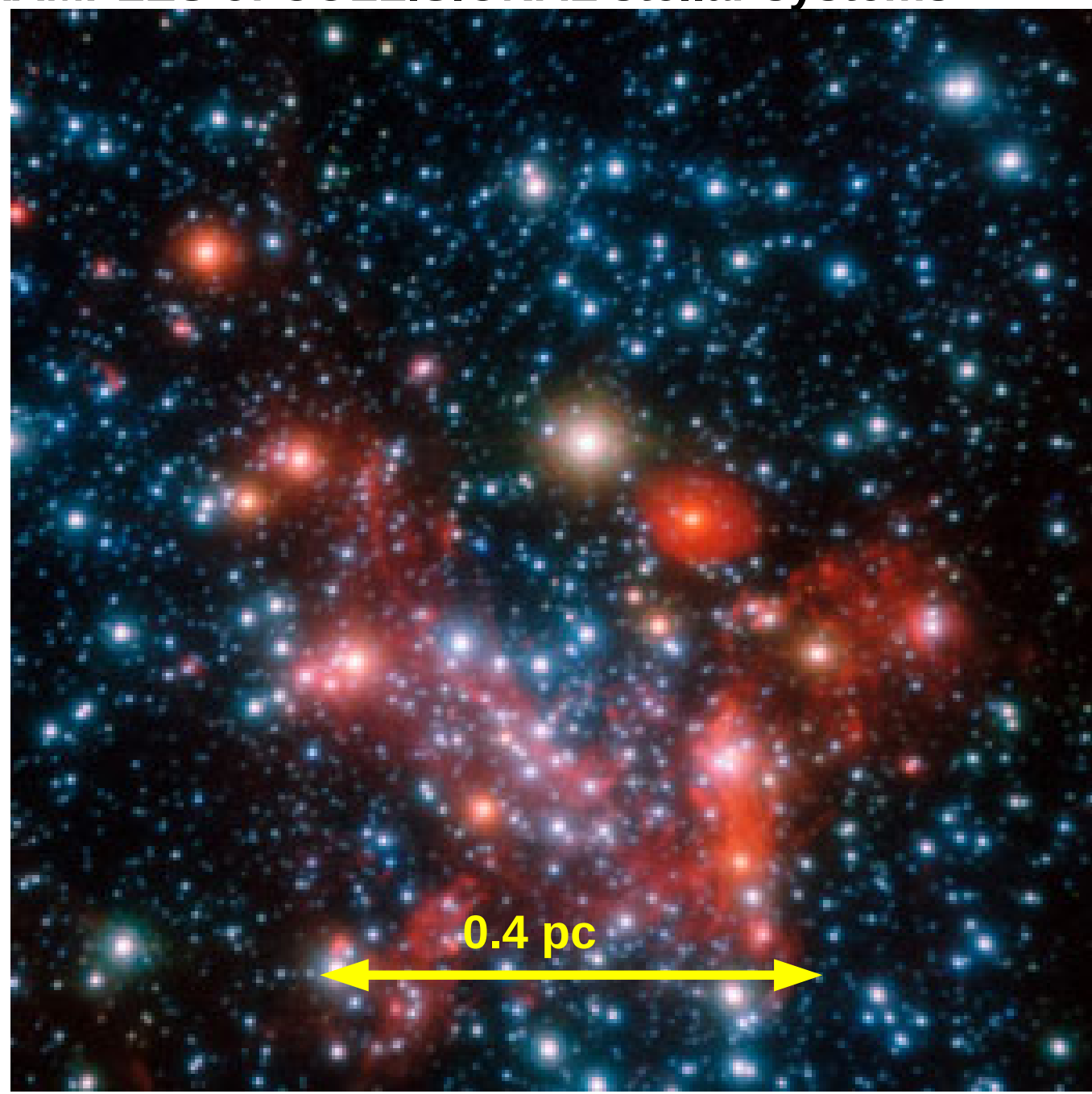
EXAMPLES of COLLISIONAL stellar systems



Globular clusters (47Tuc), by definition

1. Relevant timescales of dense stellar systems:

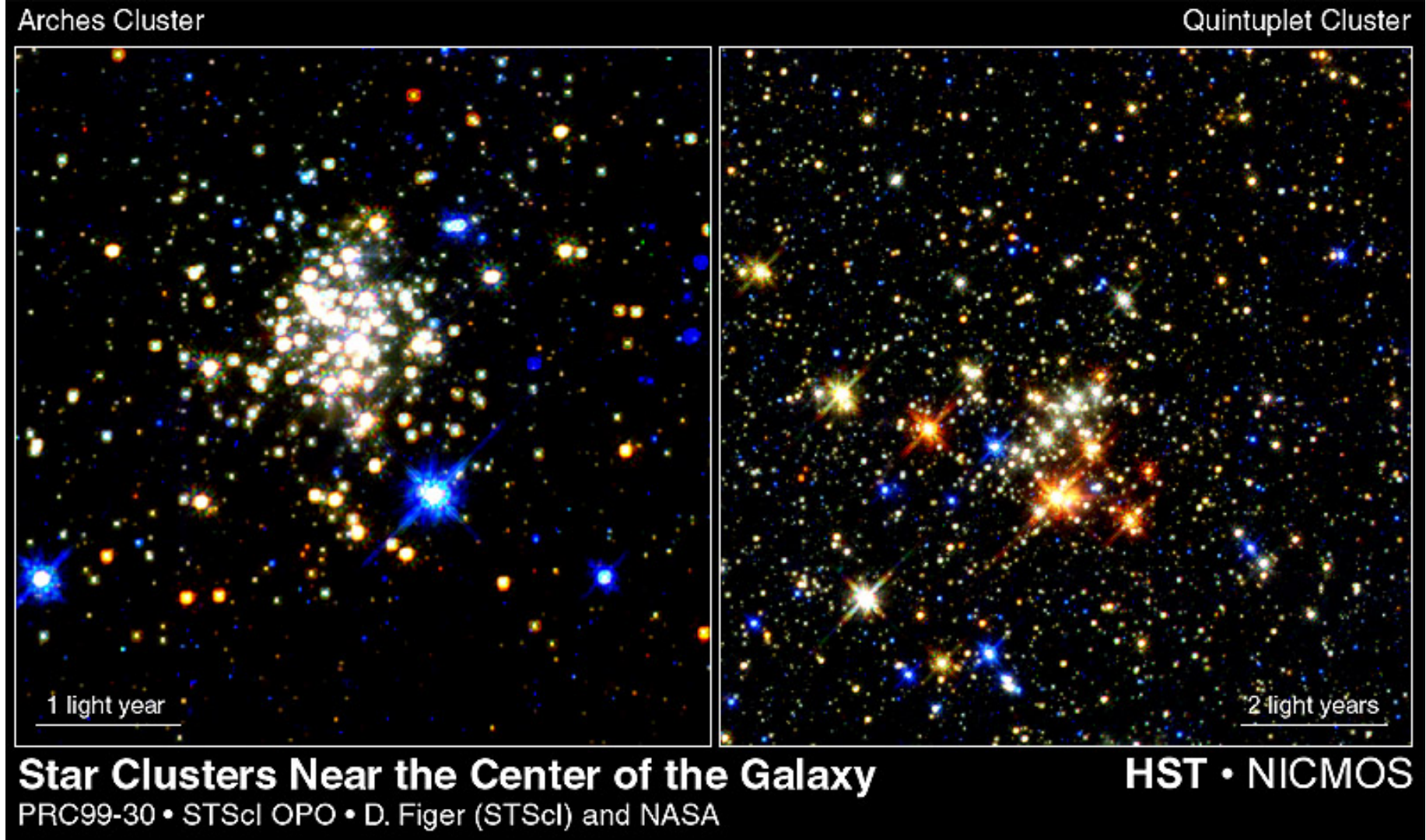
EXAMPLES of COLLISIONAL stellar systems



Nuclear star clusters (MW)
NaCo @ VLT
Genzel+2003

1. Relevant timescales of dense stellar systems:

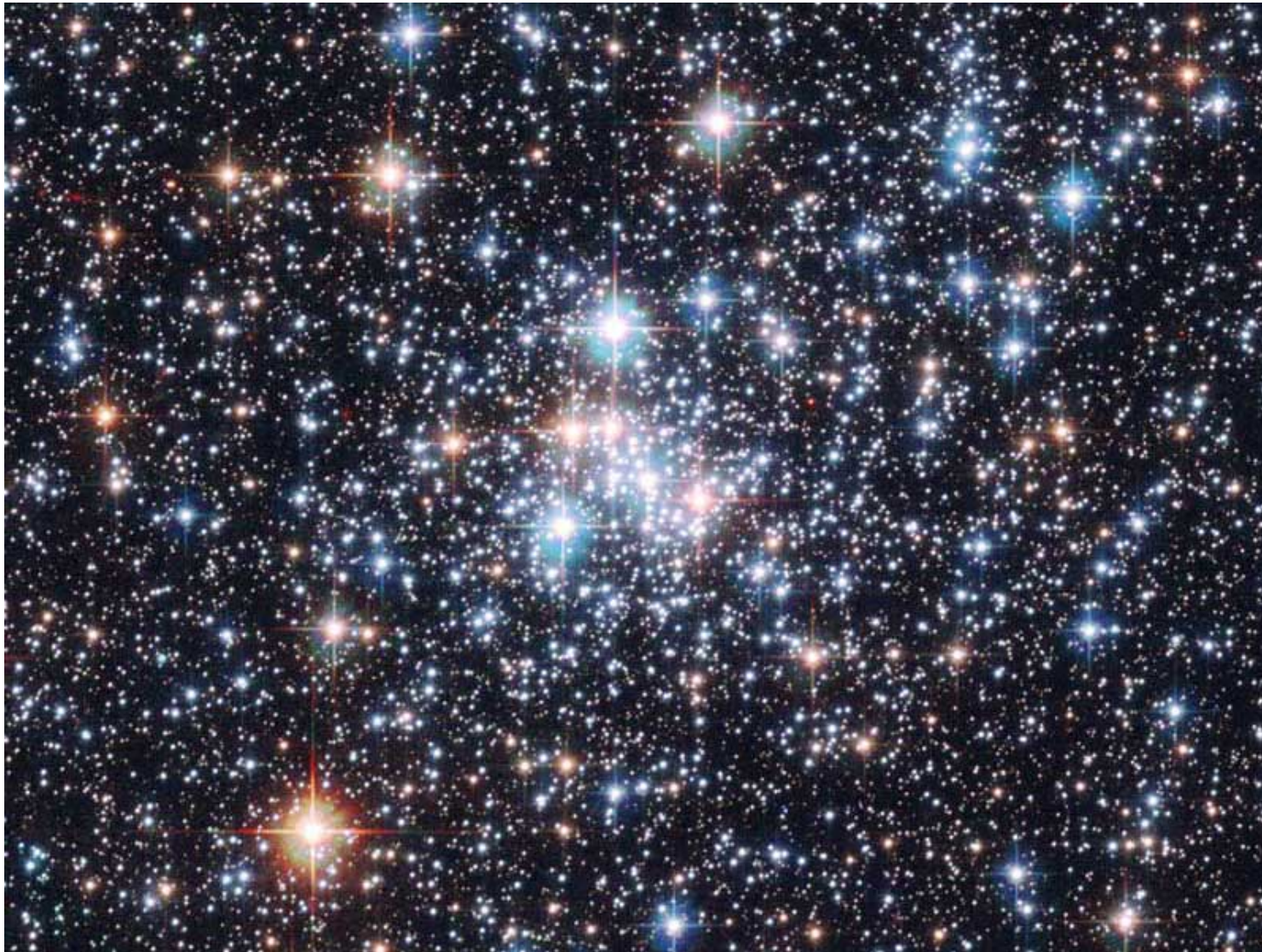
EXAMPLES of COLLISIONAL stellar systems



Young dense star clusters (Arches, Quintuplet)

1. Relevant timescales of dense stellar systems:

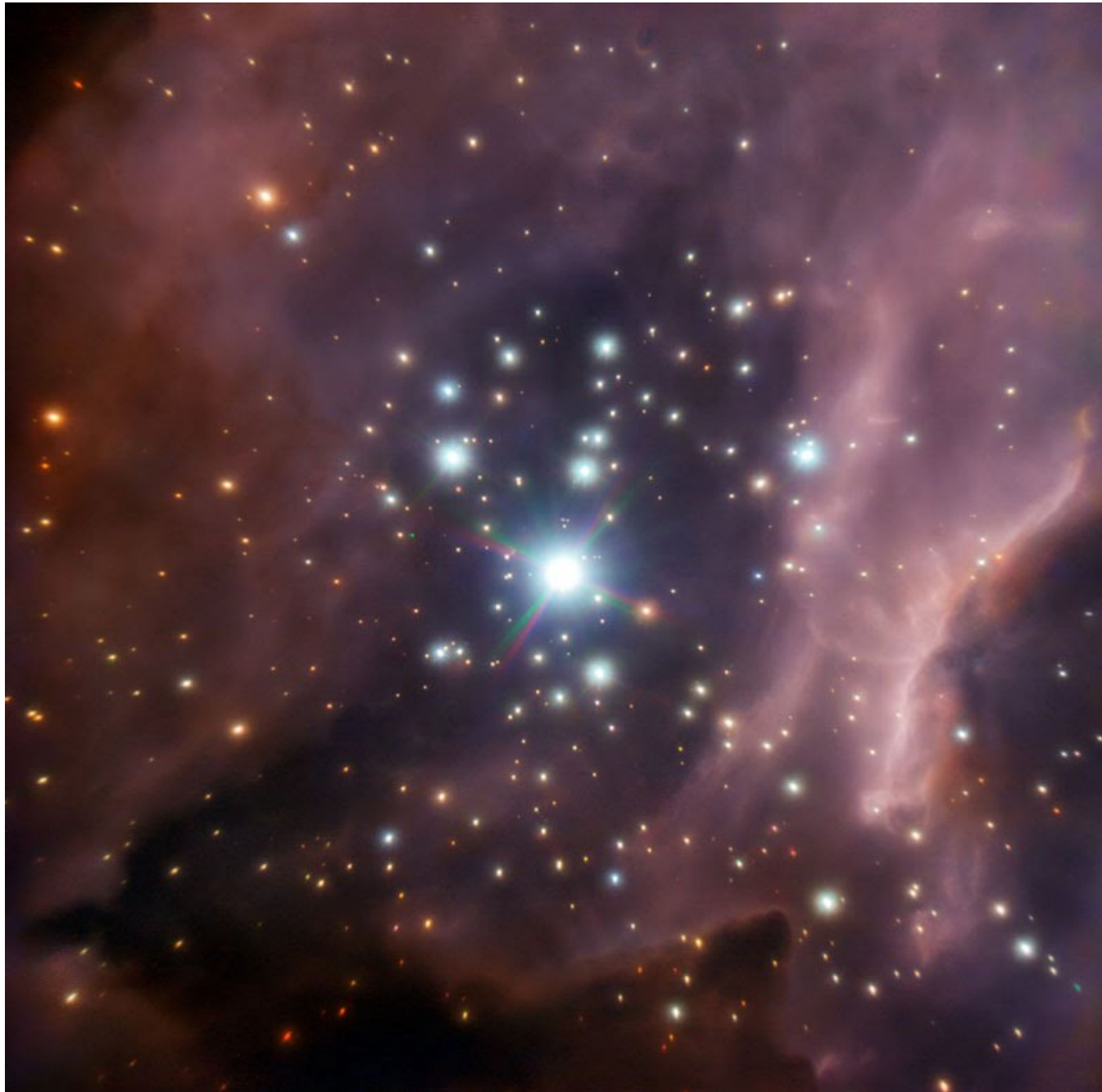
EXAMPLES of COLLISIONAL stellar systems



Open clusters, especially in the past (NGC290)

1. Relevant timescales of dense stellar systems:

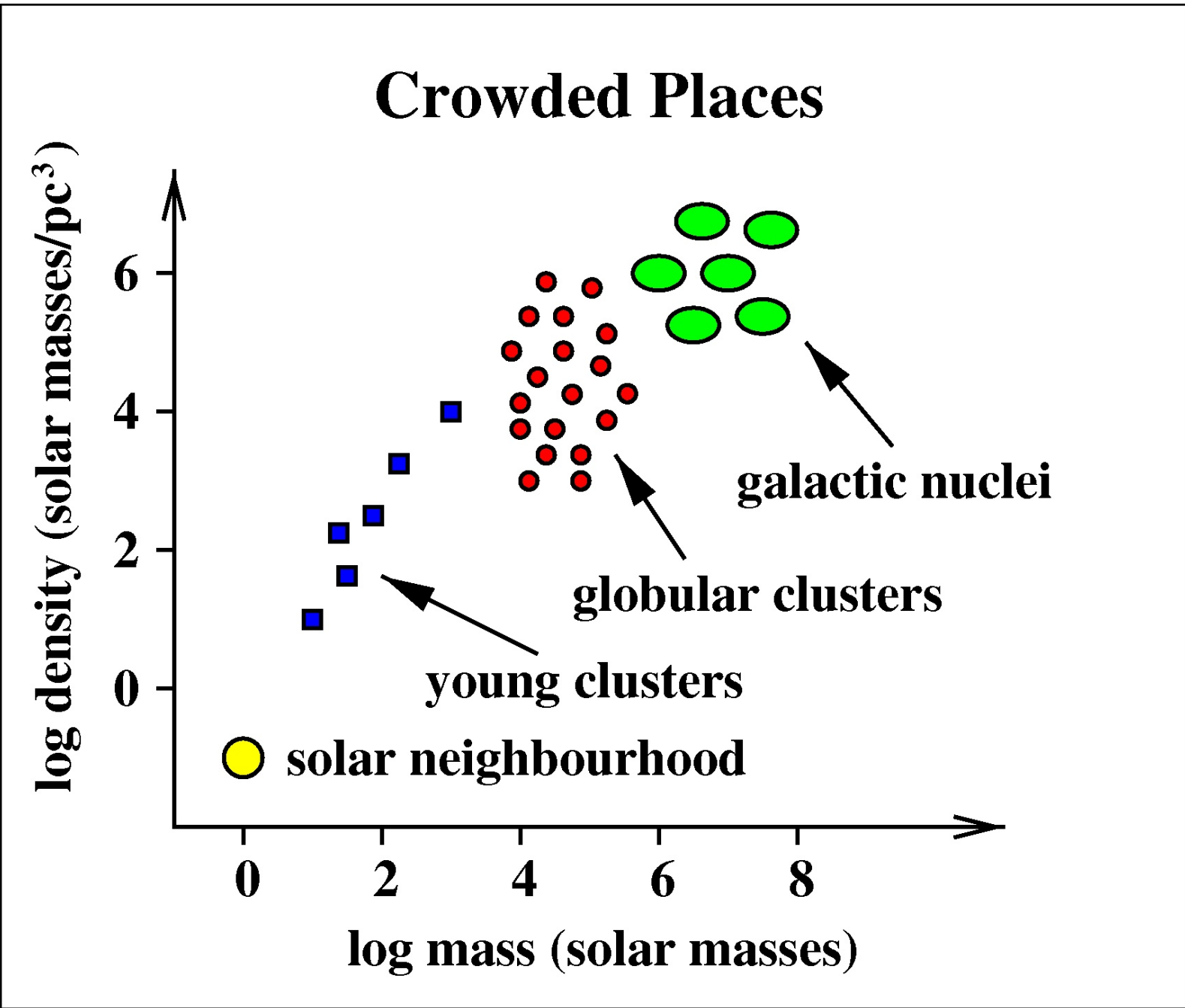
EXAMPLES of COLLISIONAL stellar systems



**Embedded
clusters,
i.e. baby clusters
(RCW 38)**
NaCo @ VLT

1. Relevant timescales of dense stellar systems:

DENSITY & MASS ORDER OF MAGNITUDES



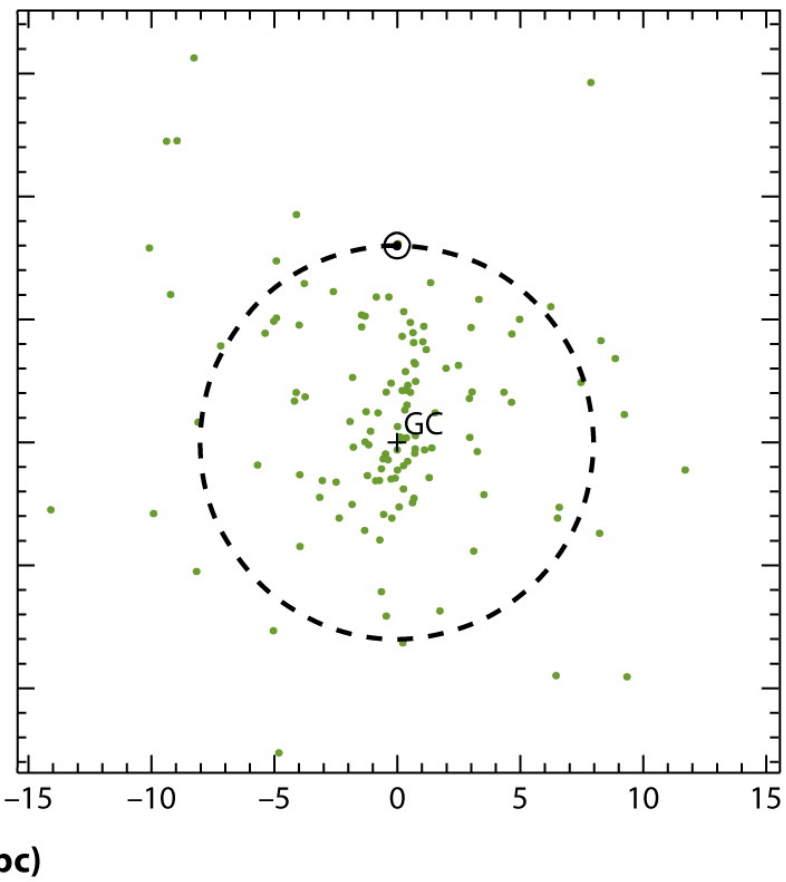
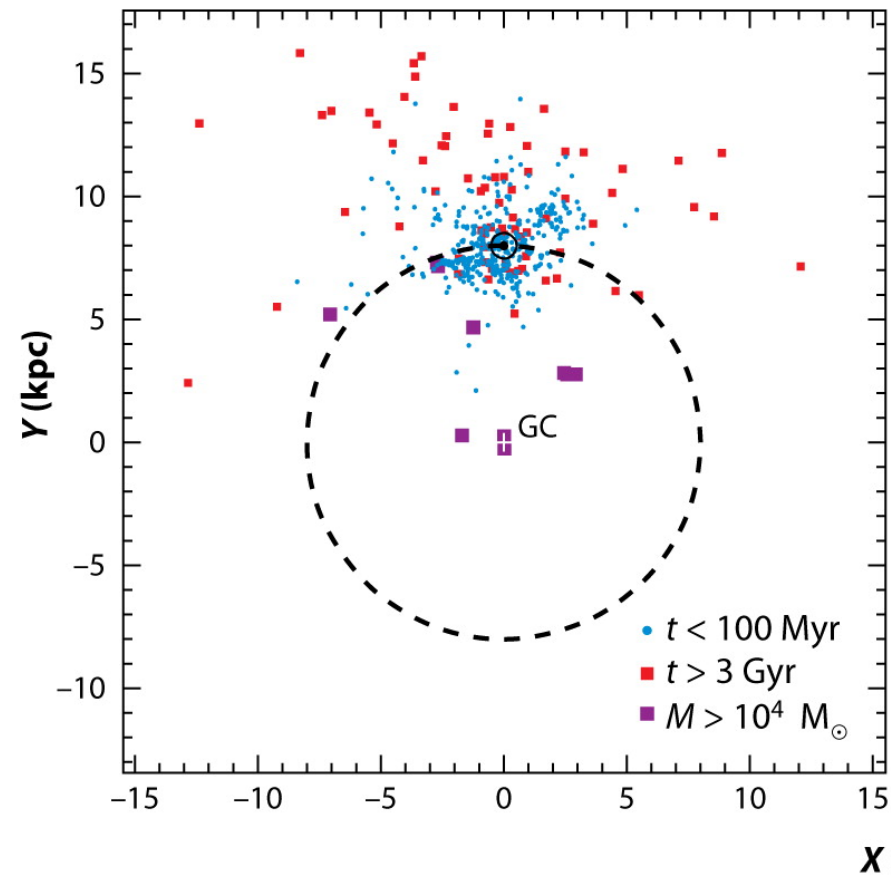
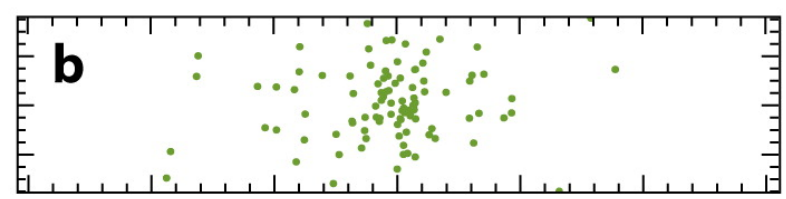
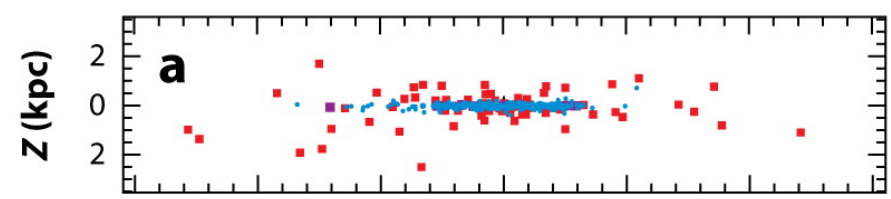
M. B. Davies,
2002,
astro-ph/0110466

1. Relevant timescales of dense stellar systems:

DISTRIBUTION of COLLISIONAL stellar systems in the MILKY WAY

Open clusters

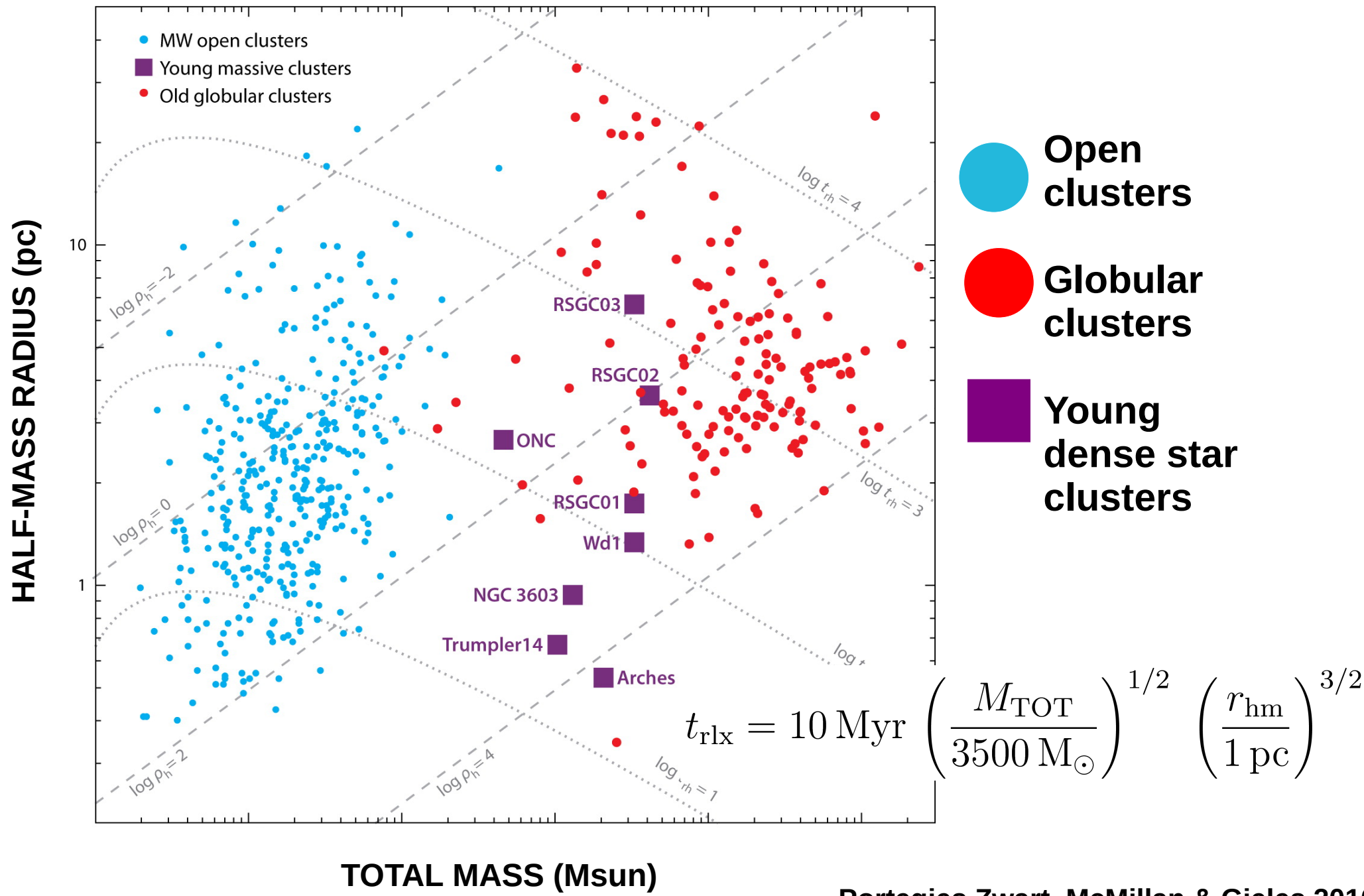
Globular clusters



LOBULAR CLUSTERS ARE A HALO POPULATION
YOUNG and OPEN CLUSTERS ARE A DISC POPULATION

1. Relevant timescales of dense stellar systems:

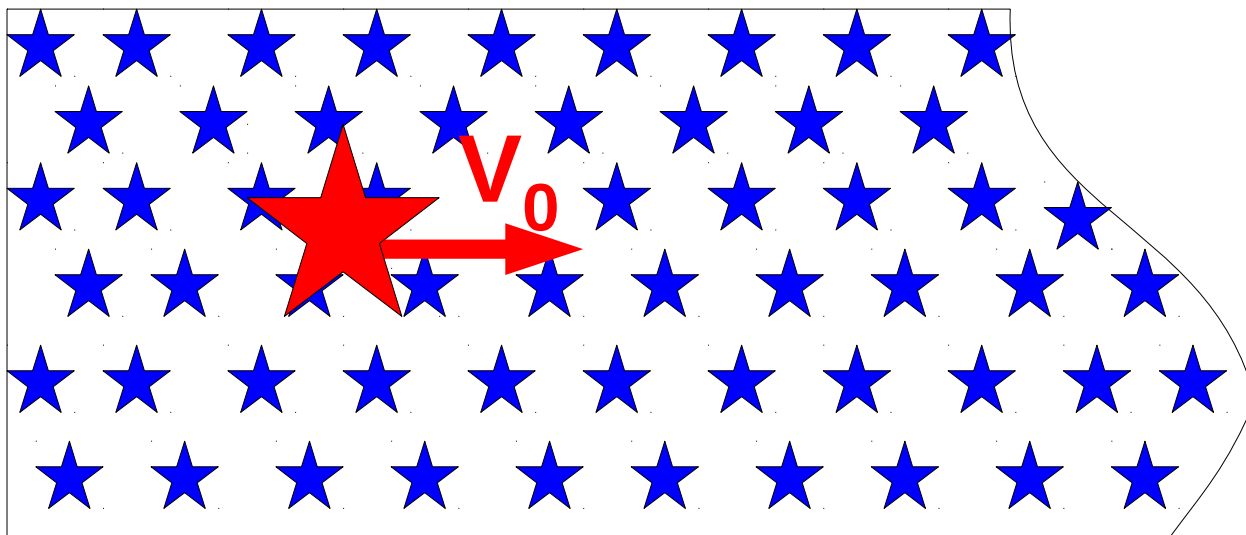
MAIN PROPERTIES of COLLISIONAL stellar systems in the MILKY WAY



1. Relevant timescales of dense stellar systems:

DYNAMICAL FRICTION TIMESCALE

A body of mass M , traveling through an infinite & homogeneous sea of bodies (mass m) suffers a steady deceleration: the dynamical friction



infinite & homogeneous sea: otherwise the body M would be deflected

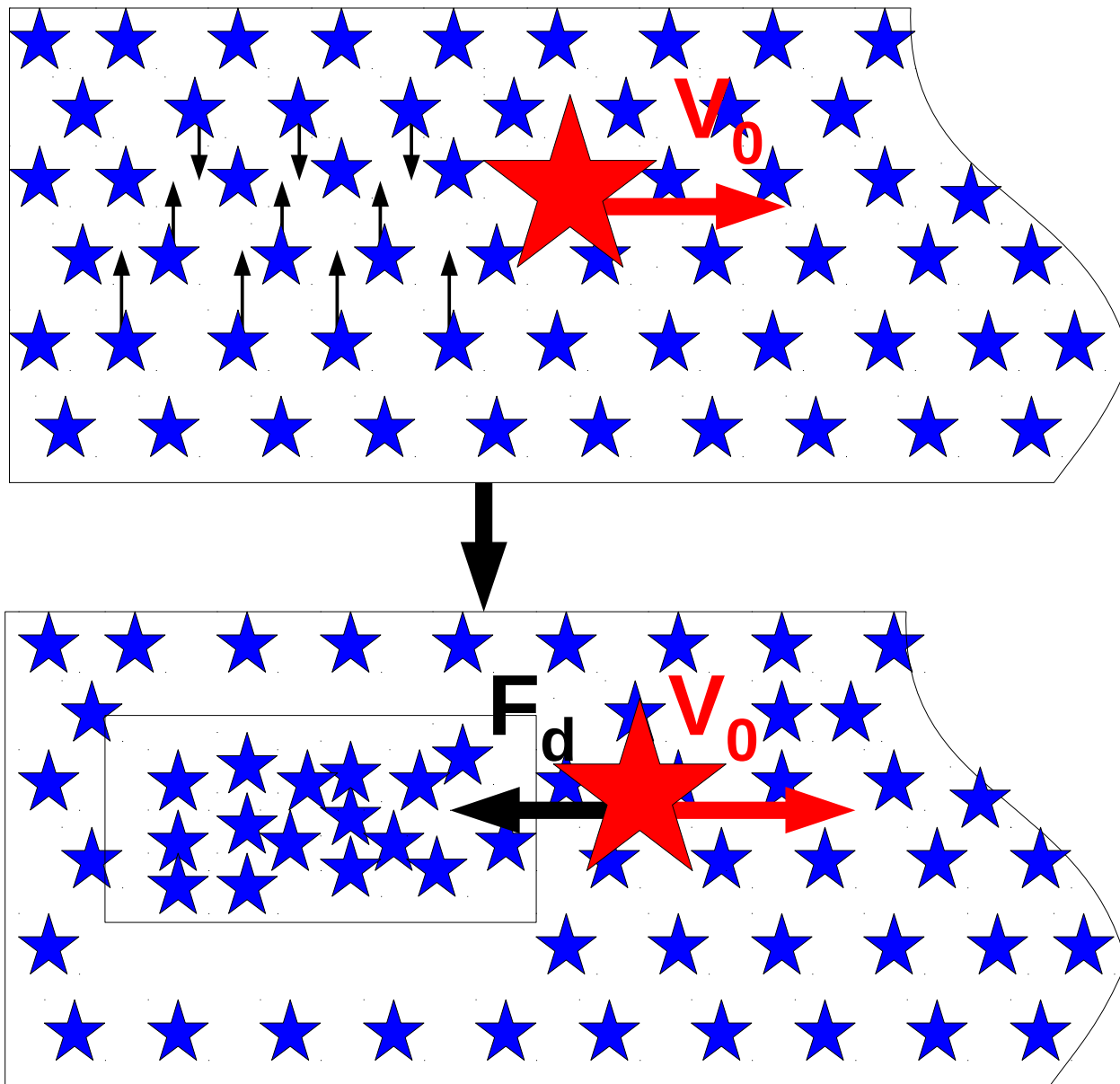
The sea exerts a force **parallel and opposite** to the velocity V_0 of the body

It can be shown that DYNAMICAL FRICTION TIMESCALE is

$$t_{df} = \frac{3}{4} \frac{\sigma^3(r)}{(2\pi)^{1/2} G^2 \ln \Lambda M \rho(r)}$$

1. Relevant timescales of dense stellar systems:

BASIC IDEA of DYNAMICAL FRICTION:



The heavy body M attracts the lighter particles.

When lighter particles approach, the body M has already moved and leaves a local overdensity behind it.

The overdensity attracts the heavy body (with force F_d) and slows it down.

1. Relevant timescales of dense stellar systems:

DYNAMICAL FRICTION vs 2-body RELAXATION:

**what is the relation between
two-body relaxation and
dynamical friction?**

1. Relevant timescales of dense stellar systems:

DYNAMICAL FRICTION vs 2-body RELAXATION:

Dynamical friction timescale:

$$t_{df} = \frac{3}{4} \frac{\sigma^3(r)}{(2\pi)^{1/2} G^2 \ln \Lambda M \rho(r)}$$

Two-body relaxation timescale:

$$t_{rlx} = 0.34 \frac{\sigma^3(r)}{G^2 m_* \rho_*(r) \ln \Lambda}$$

They are relatives..

$$t_{df} \sim \frac{m}{M} t_{rlx}$$

SAME DRIVER: GRAVITATIONAL ENCOUNTERS

2. Early evolution of dense star systems

How do star clusters form?

BOH

2. Early evolution of dense star systems

How do star clusters form?

- * from giant molecular clouds
- * possibly from aggregation of many sub-clumps
(hierarchical formation)

CLOUD SIMULATION

by
Matthew
Bate (Exeter):

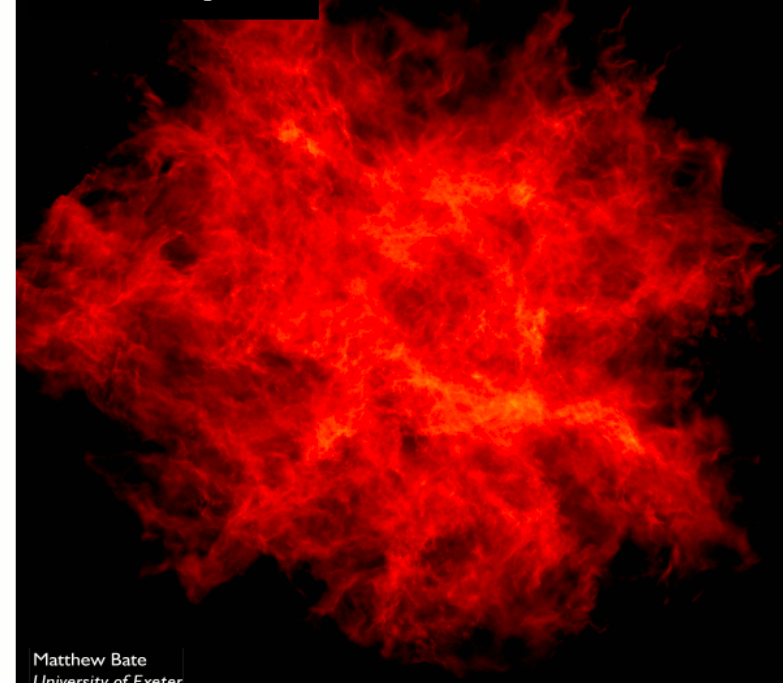
- gas
- gravity
- turbulence
- cooling /EOS
- fragmentation
- sink
particles

0 yr



Matthew Bate
University of Exeter

76k yr



Matthew Bate
University of Exeter

171k yr



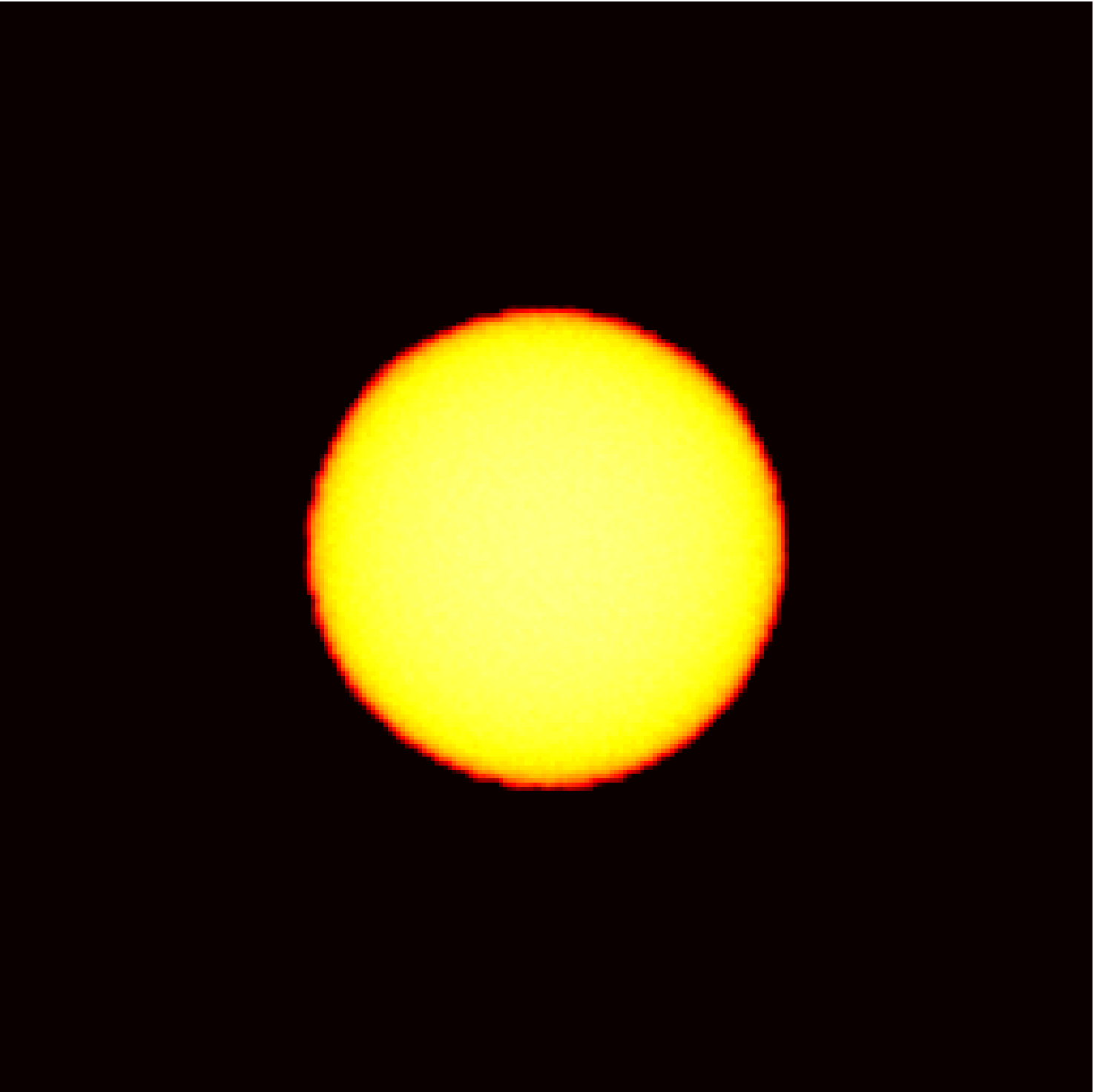
Matthew Bate
University of Exeter

210k yr



Matthew Bate
University of Exeter

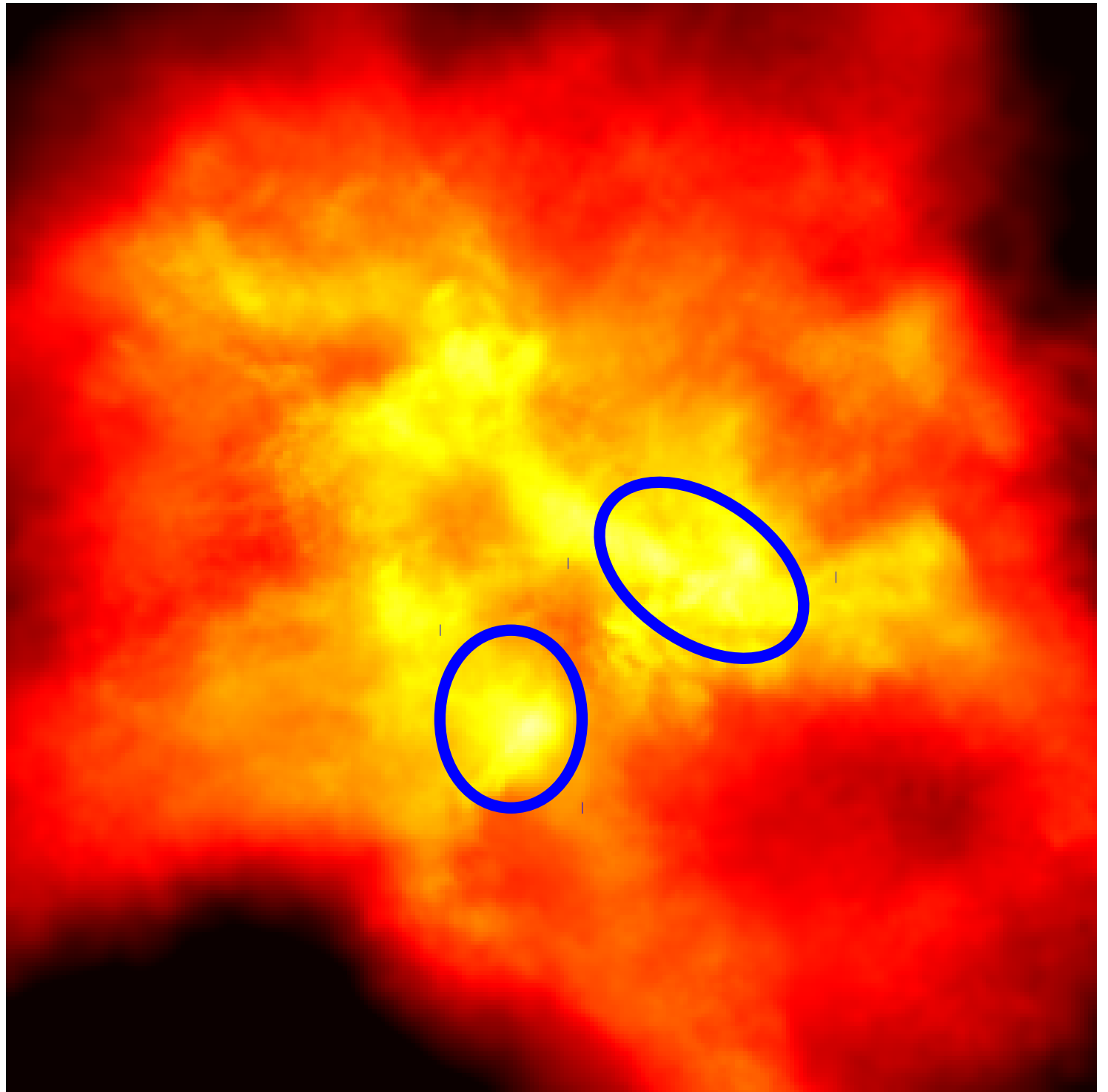
**CLOUD
SIMULATION
MOVIE**



**CLOUD
SIMULATION
MOVIE**

**SCs form
from
different
cores of a
molecular
cloud**

**More
filaments
than
spherical!**



2. Early evolution of dense star systems:

How do star clusters form?

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2. Early evolution of dense star systems:

How do star clusters form?

- * from giant molecular clouds**
- * possibly from aggregation of many sub-clumps
(hierarchical formation)**
- * can DIE by INFANT MORTALITY!!!**

2. Early evolution of dense star systems:

INFANT MORTALITY:= clusters can die when GAS is removed



**Embedded
CLUSTERS**

**GAS
REMOVAL**

DENSE CLUSTERS

bound

$n \sim 10^3\text{-}5 \text{ pc}^{-3}$ (coll.)

$\sim 10^3\text{-}6$ stars

OPEN CLUSTERS

loosely bound

$\sim 10^3\text{-}4$ stars

ASSOCIATIONS

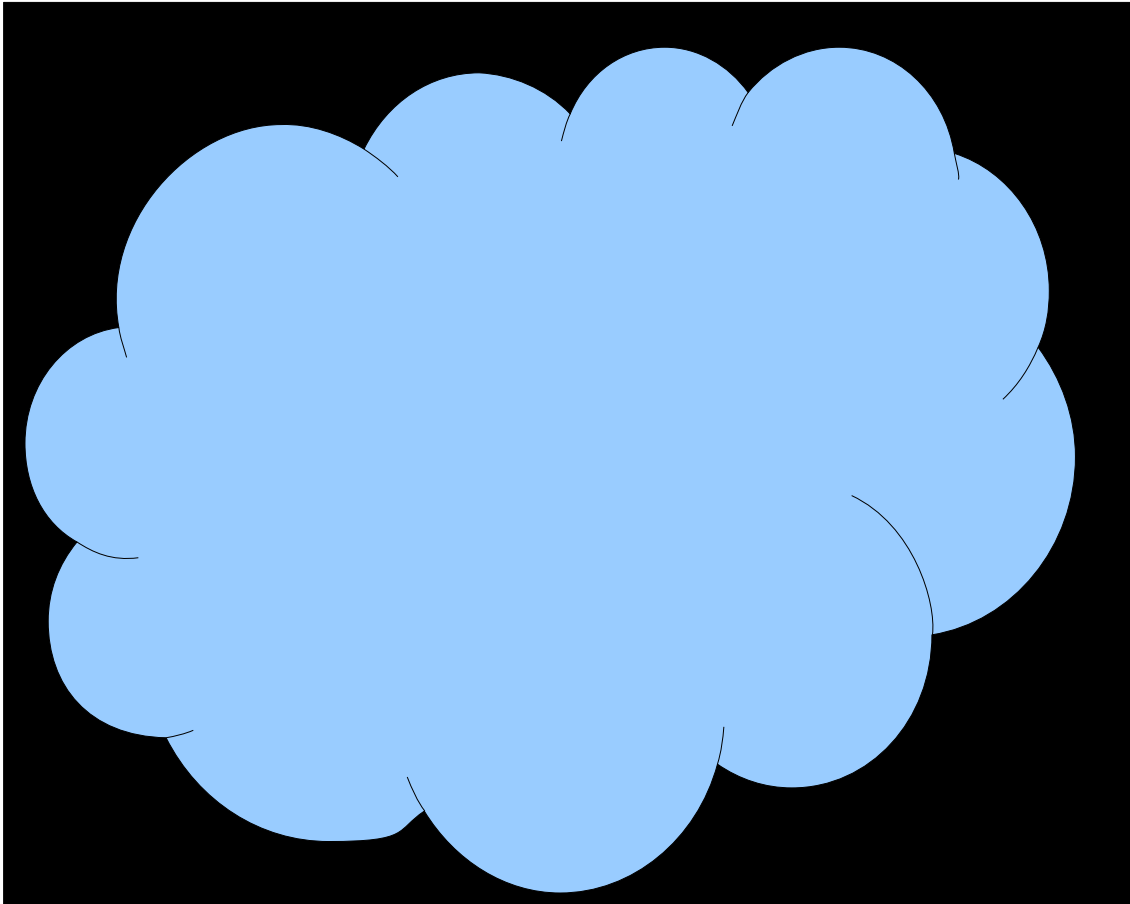
unbound

$<10^3$ stars

**OPEN and DENSE STAR CLUSTERS
as SURVIVORS of INFANT MORTALITY:
how and with which properties?**

2. Early evolution of dense star systems:

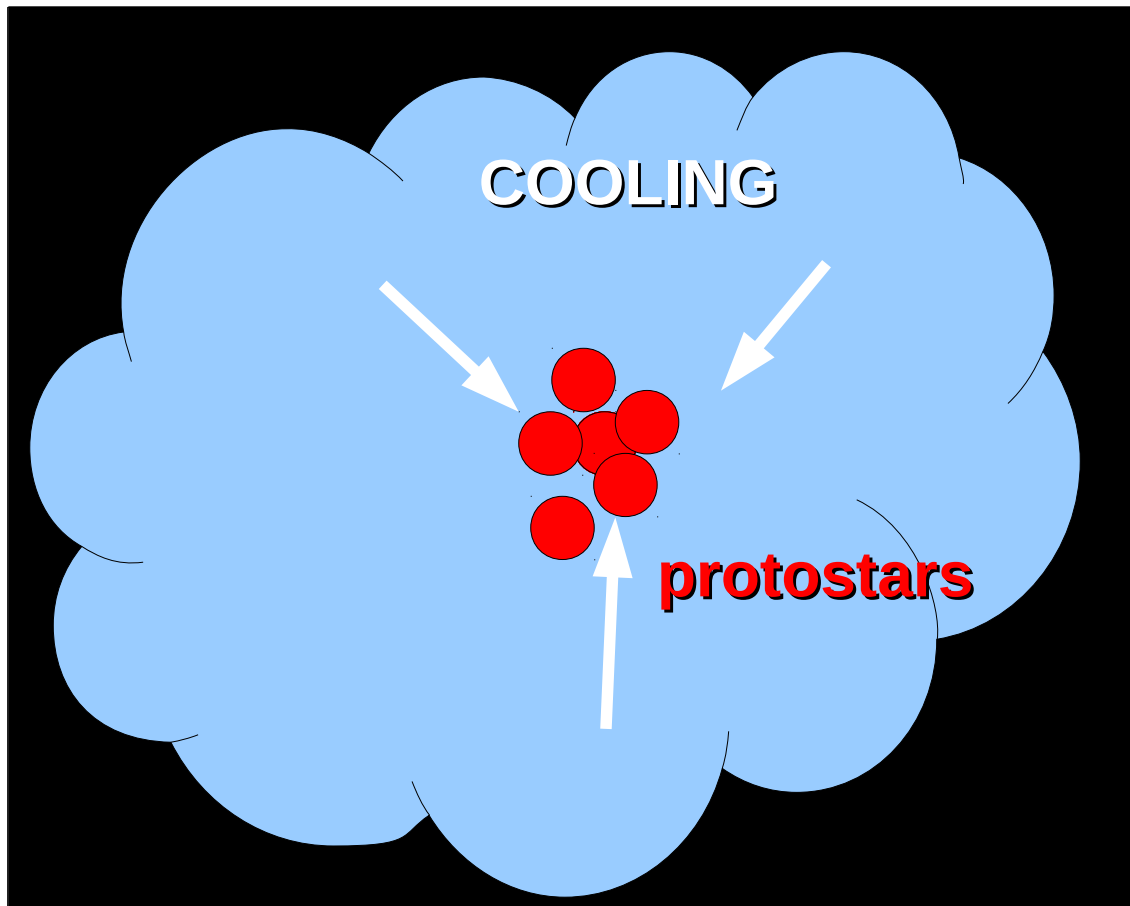
FORMATION of STAR CLUSTERS: basic concepts



**1 * giant molecular cloud:
 $10^{5-6} M_{\odot}$ of molecular gas,
mainly H_2 , in ~ 10 pc
radius, at 10-100 K**

2. Early evolution of dense star systems:

FORMATION of STAR CLUSTERS: basic concepts

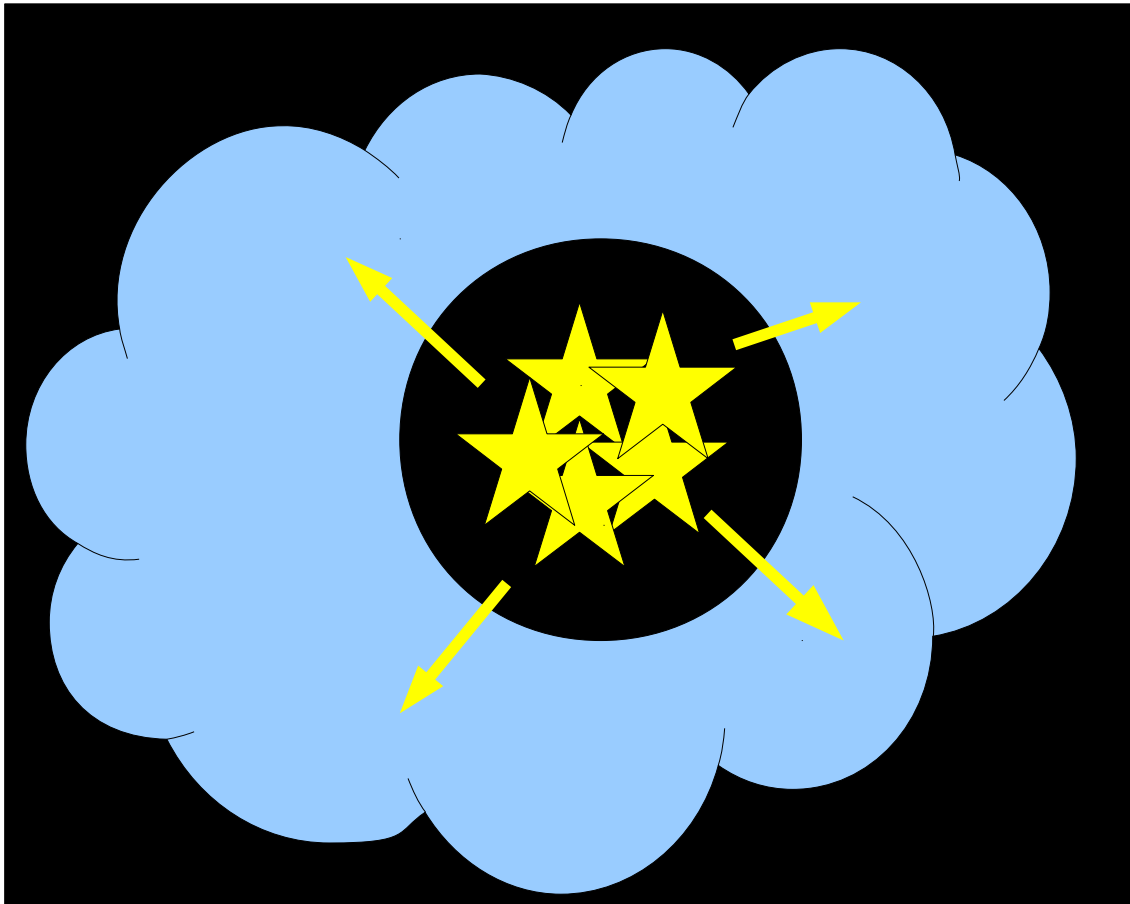


1 * giant molecular cloud

2 * gas cools down and compresses
→ protostars form

2. Early evolution of dense star systems:

FORMATION of STAR CLUSTERS: basic concepts



1 * giant molecular cloud

**2 * gas cools down and compresses
→ protostars form**

3 * protostars start irradiating and gas evaporates

2. Early evolution of dense star systems:

FORMATION of STAR CLUSTERS: basic concepts



1 * giant molecular cloud

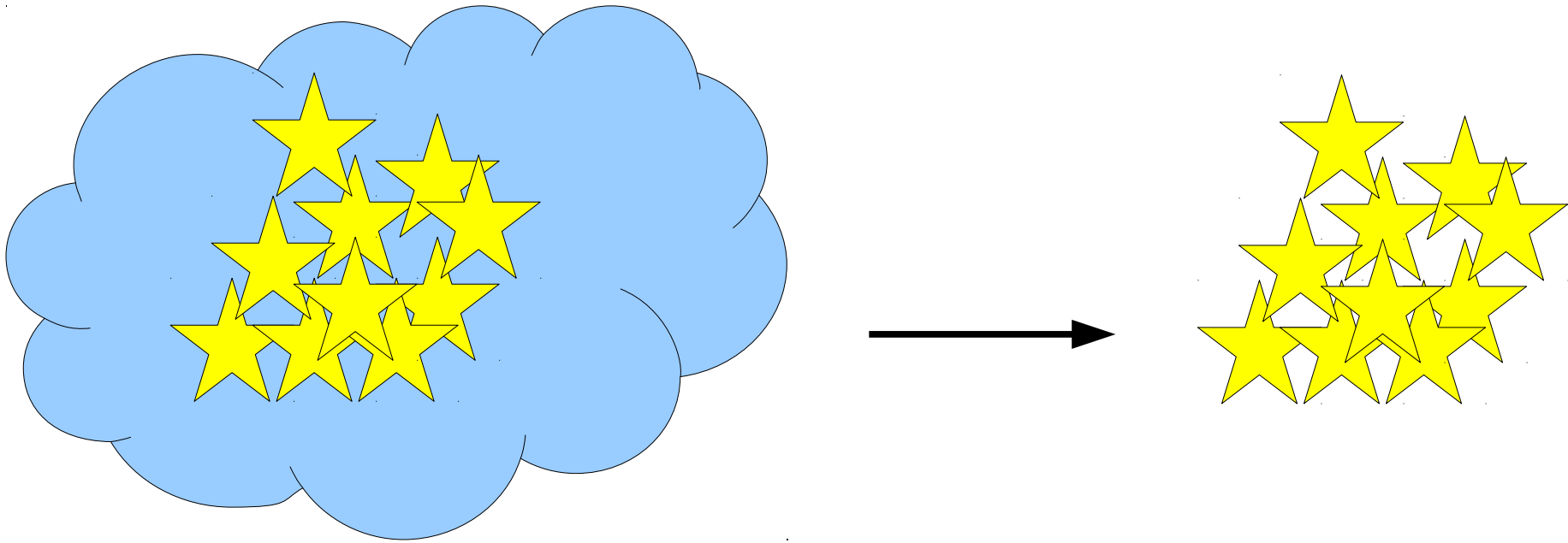
**2 * gas cools down and compresses
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3 * protostars start irradiating and gas evaporates

how many SCs survive gas evaporation?

2. Early evolution of dense star systems:

INFANT MORTALITY: a back to the envelope calculation



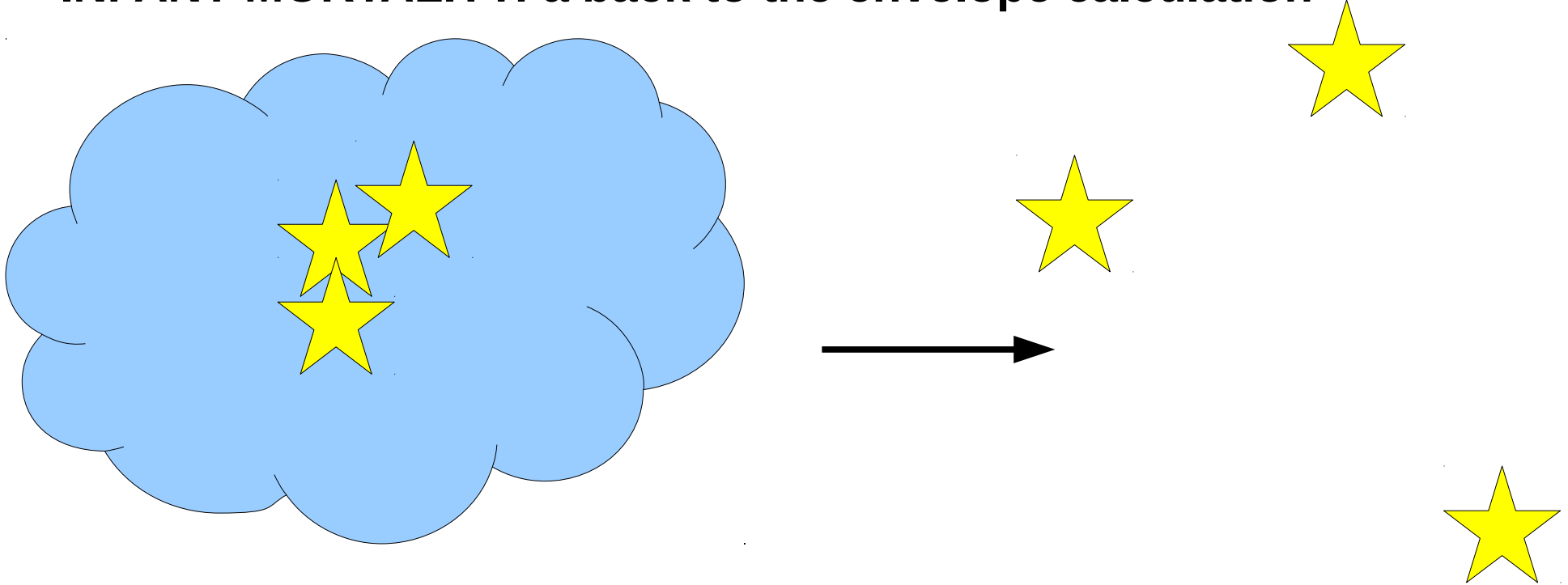
Intuitive argument:

$$|W_0| = G (M_{\text{gas}} + M_{\text{star}})^2 / R$$

If M_{star} large with respect to M_{gas} , cluster remains bound

2. Early evolution of dense star systems:

INFANT MORTALITY: a back to the envelope calculation



Intuitive argument:

$$|W_0| = G (M_{\text{gas}} + M_{\text{star}})^2 / R$$

If M_{star} large with respect to M_{gas} , cluster remains bound

If M_{star} small with respect to M_{gas} , then cluster becomes unbound

2. Early evolution of dense star systems:

INFANT MORTALITY: a back to the envelope calculation

(1) Velocity dispersion from virial theorem before gas removal:

$$\sigma_0^2 = \frac{G (M_{star} + M_{gas})}{R_0}$$

(2) Energy after gas removal (hypothesis of instantaneous gas removal):

$$E = \frac{1}{2} M_{star} \sigma_0^2 - \frac{G M_{star}^2}{R_0}$$

(3) Energy after new virialization:

$$E = -\frac{G M_{star}^2}{2 R}$$

New cluster size:

- From (2) = (3)

$$-\frac{G M_{star}^2}{2 R} = \frac{1}{2} M_{star} \sigma_0^2 - \frac{G M_{star}^2}{R_0}$$

2. Early evolution of dense star systems:

INFANT MORTALITY: a back to the envelope calculation

New cluster size:
- Using (1)

$$-\frac{M_{star}}{2R} = \frac{1}{2} \frac{(M_{star} + M_{gas})}{R_0} - \frac{M_{star}}{R_0}$$

-Rearranging

$$R = R_0 \frac{M_{star}}{M_{star} + M_{gas}} \frac{1}{\left(2 \frac{M_{star}}{M_{star} + M_{gas}} - 1\right)}$$

$R > 0$ only if

$$\frac{M_{star}}{M_{star} + M_{gas}} > 0.5$$

2. Early evolution of dense star systems:

INFANT MORTALITY: the complete picture

-DEPENDENCE on SFE : <30% disruption

-DEPENDENCE on t_{gas} :

explosive removal: $t_{\text{gas}} \ll t_{\text{cross}}$
[smaller systems]

adiabatic removal: $t_{\text{gas}} > \sim t_{\text{cross}}$
[dense clusters]

-DEPENDENCE on the (+/-) VIRIAL state
of the embedded cluster

-DEPENDENCE on Z: metal poor clusters more compact
than metal rich

Hills 1980; Lada & Lada 2003; Bastian & Goodwin 2006;
Baumgardt & Kroupa 2007; Bastian 2011;
Pelupessy & Portegies Zwart 2011

2. Early evolution of dense star systems:

How do star clusters form?

- * from giant molecular clouds
- * possibly from aggregation of many sub-clumps (hierarchical formation)
- * can DIE by INFANT MORTALITY!!!
- * if they survive infant mortality, gas-less star clusters can be described with distribution functions:
 - PLUMMER SPHERE
 - ISOTHERMAL SPHERE
 - LOWERED ISOTHERMAL SPHERE
 - KING MODEL

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**DON'T YOU NOTICE ANYTHING
STRANGE IN THIS SLIDE??**

2. Early evolution of dense star systems:

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**DON'T YOU NOTICE ANYTHING
STRANGE IN THIS SLIDE??**

3. Equilibrium models

DISTRIBUTION FUNCTION or PHASE SPACE DENSITY

$$f(\vec{x}, \vec{v}, t) d^3\vec{x} d^3\vec{v}$$

Number of stars in the infinitesimal volume $d^3\mathbf{x}$ and in the small range of velocities $d^3\mathbf{v}$

DISTRIBUTION FUNCTIONS ARE WELL DEFINED ONLY FOR COLLISIONLESS SYSTEMS!!

Because they can be CONTINUOUS only if potential is smooth

BUT if system is COLLISIONAL potential is not smooth, particles jump from one side to the other of the phase space!

For a short time even a collisional system can be defined by a distribution function (not correct but useful in practice)

Then 2-body relaxation produces jumps and collisional system passes from one equilibrium to another

3. Equilibrium models:

DISTRIBUTION FUNCTION or PHASE SPACE DENSITY

- * Equations of motion in the phase space using distribution functions can be expressed with **collisionless Boltzmann equation (CBE)**

$$\frac{df}{dt} = \frac{\partial f}{\partial t} + \sum_{i=1,6} \frac{\partial x_i}{\partial t} \frac{\partial f}{\partial x_i} = 0$$

same as continuity equation for fluids: valid only if no jumps

- * JEANS theorem: any steady-state solution of the CBE is a function of the integrals of motion and any function of the integrals of motion is a steady-state solution of the CBE

- * Poisson Vlasov equation describes relation between gravity force and its Sources (same as Gauss)

$$\nabla^2 \phi = 4 \pi G \rho$$

- * Often potentials and energies are given as

RELATIVE potential:

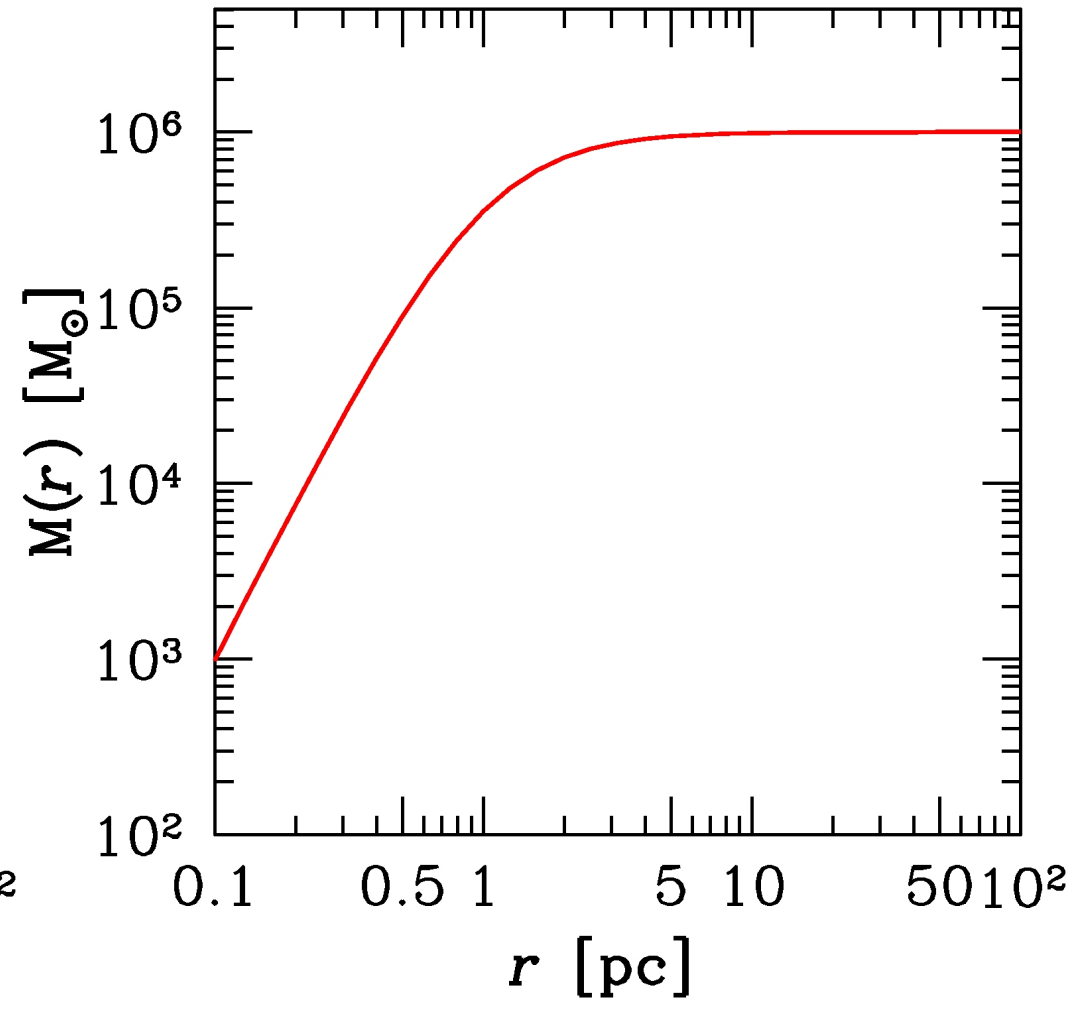
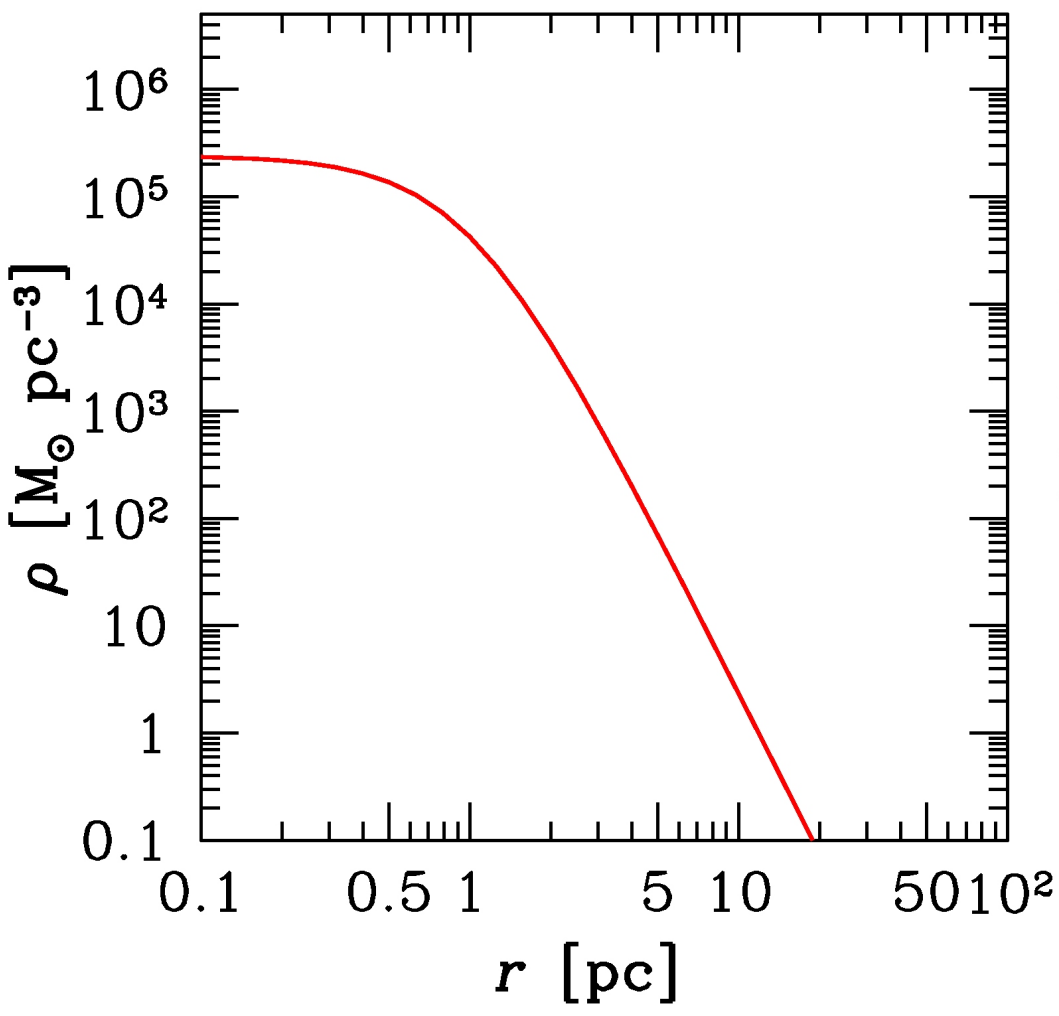
$$\Psi = -\Phi + \Phi_0$$

RELATIVE energy:

$$\mathcal{E} = -E + \Phi_0 = \Psi - \frac{1}{2}v^2$$

3. Equilibrium models:

Plummer sphere



3. Equilibrium models:

Plummer sphere

Isotropic velocity distribution function: $f(E) \propto \begin{cases} (-E)^p & \text{if } E < 0 \\ 0 & \text{if } E \geq 0 \end{cases}$

if $p=1$ corresponds to potential $\phi(r) = -\frac{GM}{(r^2 + a^2)^{1/2}}$

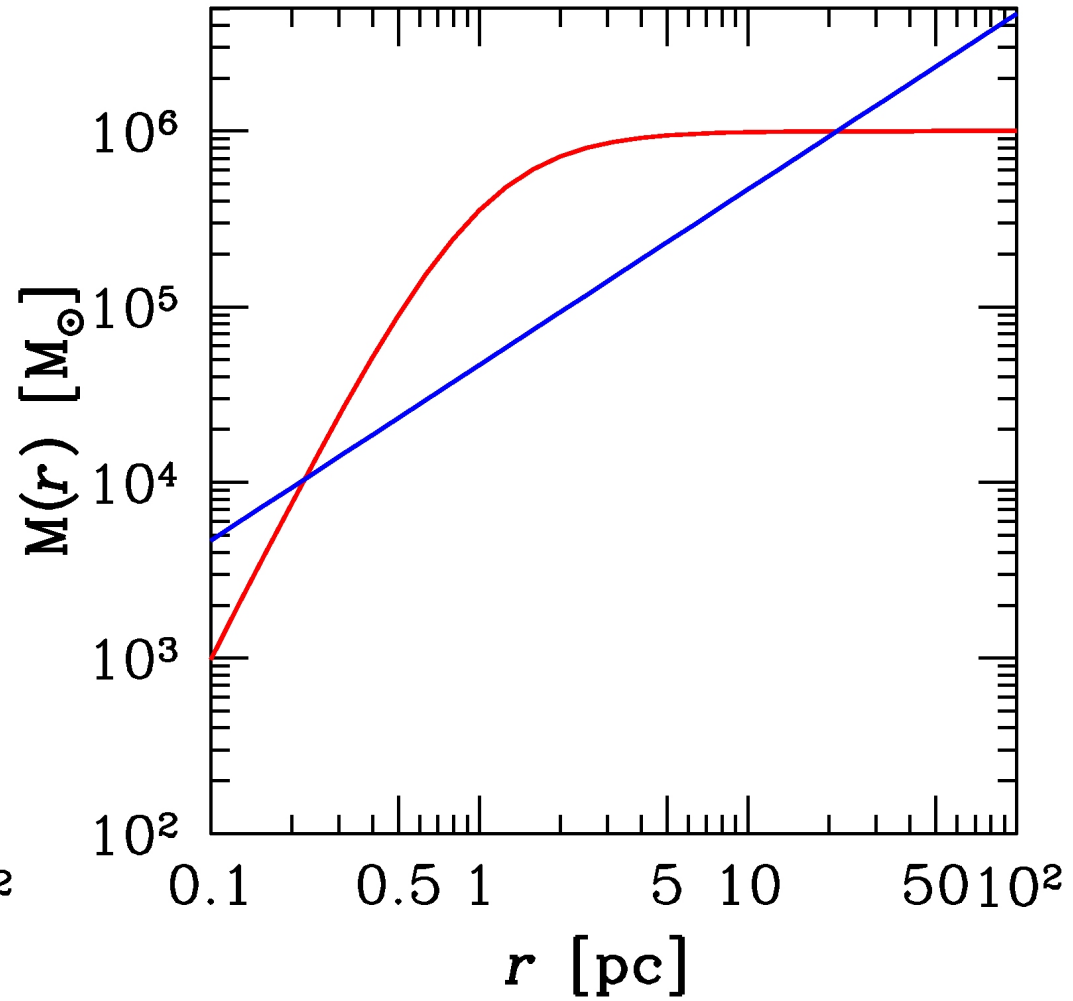
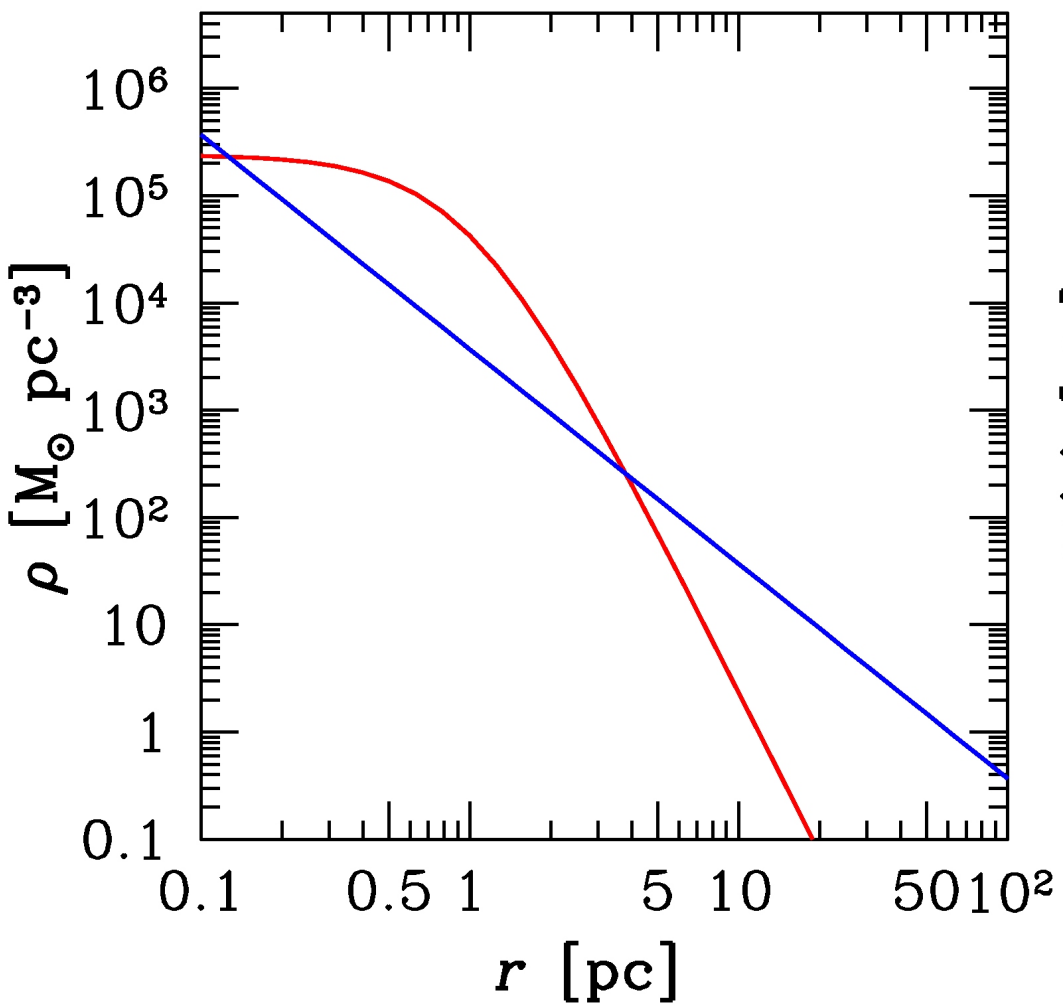
From Poisson equation $\nabla^2 \phi = 4\pi G \rho$

We derive density $\rho(r) = \frac{M}{\frac{4}{3}\pi a^3} \frac{1}{\left[1 + \left(\frac{r}{a}\right)^2\right]^{5/2}}$

and corresponding mass $M(r) = \frac{M}{a^3} \frac{r^3}{\left[1 + \left(\frac{r}{a}\right)^2\right]^{3/2}}$

3. Equilibrium models:

Isothermal sphere



3. Equilibrium models:

Isothermal sphere

* Why isothermal? From formalism of ideal gas $P = \frac{\kappa_B}{\mu m_p} \rho T$

If $T = \text{const}$ \longrightarrow $P = \text{const} \times \rho$

* For polytropic equation of state $P = \kappa \rho^\gamma$
is isothermal if $\gamma = 1$

if we assume
hydrostatic equilibrium

$$\frac{d\phi}{dr} = -\frac{1}{\rho} \frac{dP}{dr} = -\frac{\kappa d\rho}{\rho dr}$$

$\gamma = 1$

we derive the potential

$$\phi = -\kappa \ln \left(\frac{\rho}{\rho_c} \right)$$

using Poisson's equation we find

$$\rho(r) = \frac{\sigma^2}{2\pi G} r^{-2}$$

expressing the constant k with some physical quantities

3. Equilibrium models:

PROBLEMS of isothermal sphere

1) DENSITY goes to infinity if radius goes to zero

$$\rho(r) = \frac{\sigma^2}{2\pi G} r^{-2}$$

2) MASS goes to infinity if radius goes to infinity

$$M(r) = 4\pi \int_0^r \rho(r) r^2 dr = \frac{2\sigma^2}{G} r$$

3. Equilibrium models:

Non-singular isothermal sphere or King model

1) King model (also said non-singular isothermal sphere) solves the problem at centre by introducing a CORE

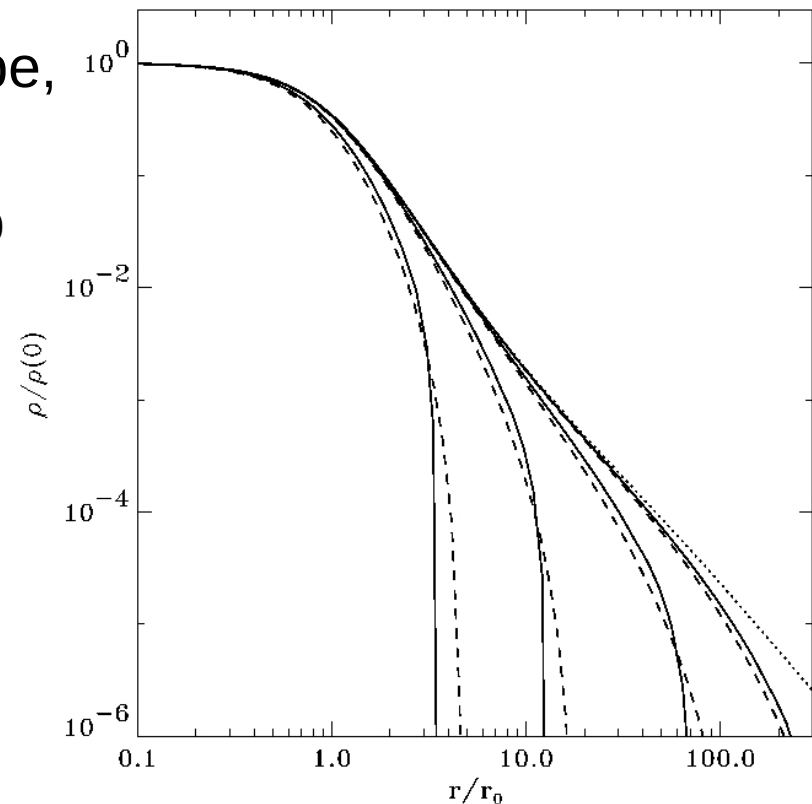
$$\tilde{\rho} = \frac{\rho}{\rho_0} \quad \tilde{r} = \frac{r}{r_0} \quad r_0 = \sqrt{\frac{9 \sigma^2}{4 \pi G \rho_0}}$$

r_0 is the radius at which the projected density falls to ~half

with the core, ρ has a difficult analytical shape, but can be approximated with the singular isothermal sphere for $r \gg r_0$ and with

$$\rho(r) = \rho_0 \frac{1}{\left[1 + \left(\frac{r}{r_0}\right)^2\right]^{3/2}}$$

for $r < \sim 2 r_0$



3. Equilibrium models:

Lowered non-singular isothermal sphere or lowered King model

2) LOWERED non-singular isothermal sphere := all King models where mass is truncated at a certain radius (does not go to infinity)

VELOCITY DISTRIBUTION FUNCTION:

$$f(E) \propto \begin{cases} \kappa \left(e^{-B E} - e^{-B E_e} \right) & \text{if } E < E_e \\ 0 & \text{if } E \geq E_e \end{cases}$$

DENSITY EXPRESSION:

$$\rho_K(\Psi) = \rho_1 \left[\exp(\Psi/\sigma^2) \operatorname{erf} \left(\frac{\sqrt{\Psi}}{\sigma} \right) - \sqrt{\frac{4\Psi}{\pi\sigma^2}} \left(1 + \frac{2\Psi}{3\sigma^2} \right) \right]$$

Relative potential

Error function

3. Equilibrium models:

Lowered non-singular isothermal sphere or lowered King model

2) LOWERED non-singular isothermal sphere := all King models where mass is truncated at a certain radius (does not go to infinity)

TIDAL RADIUS (r_t):

Radius at which $\Psi = 0$ (and $\rho=0$) $0 = \Psi(r_t) = -\Phi(r_t) + Const$

→ we can define

$$Const = \Phi(r_t) = -\frac{G M(r_t)}{r_t}$$

$$\Phi(0) = \Phi(r_t) - \Psi(0)$$

$$W_0 = \Psi(0) / \sigma^2$$

Dimensionless
central potential

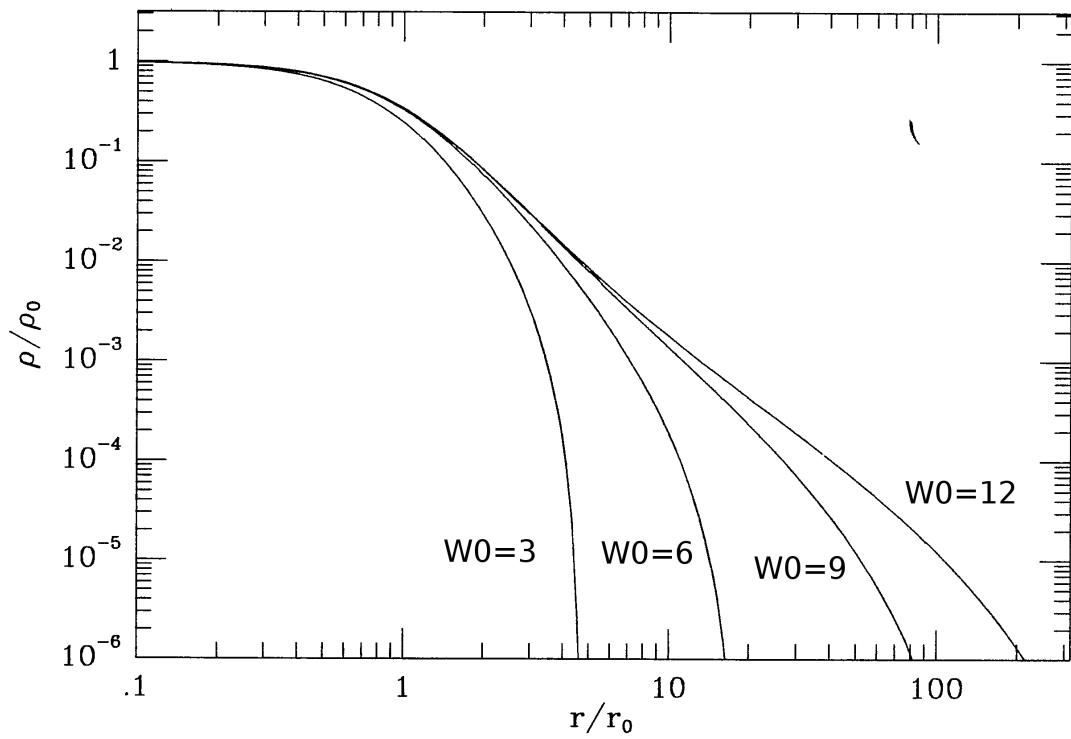
$$c = \log_{10}(r_t / r_0)$$

concentration

Most important parameters of the King model.

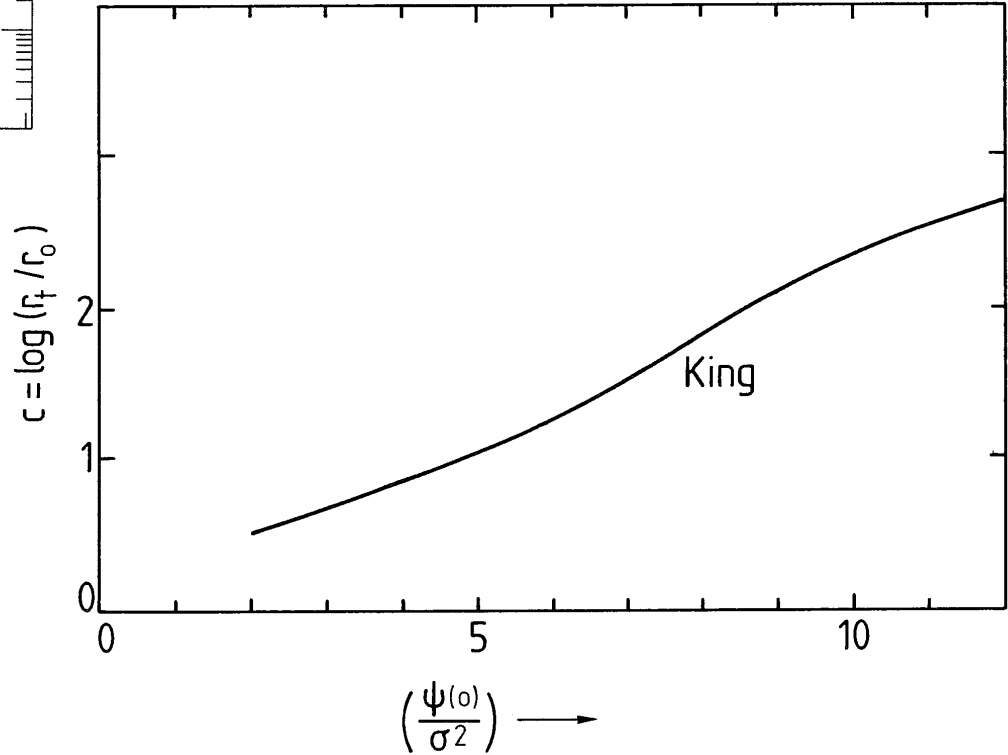
3. Equilibrium models:

Lowered non-singular isothermal sphere or lowered King model



ρ/ρ_0 versus r/r_0

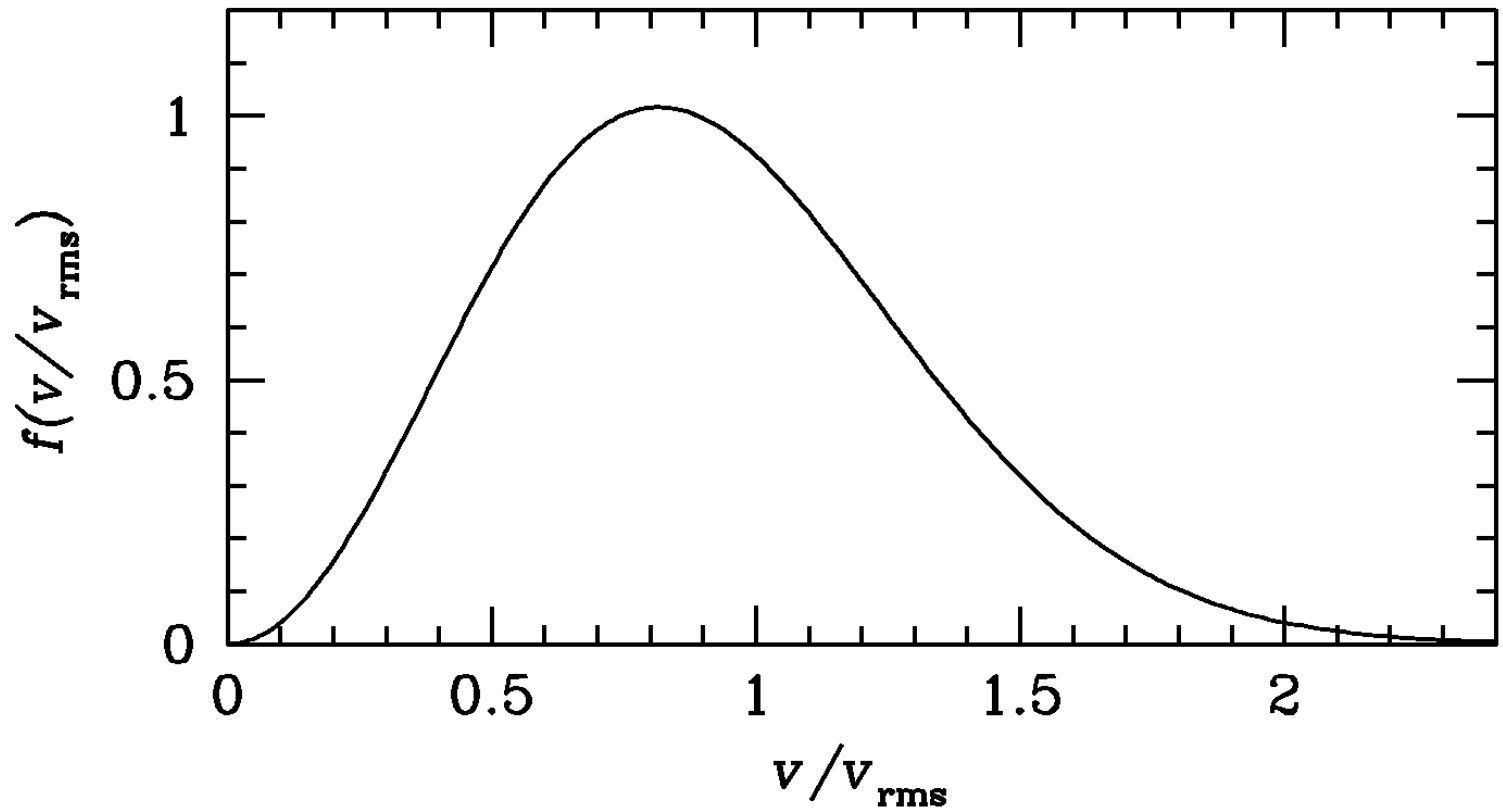
c versus W_0



3. Equilibrium models:

Lowered non-singular isothermal sphere or lowered King model

NOTE: VELOCITY DISTRIBUTION FUNCTION is the MAXWELLIAN for isothermal sphere and truncated Maxwellian for lowered non-singular isothermal sphere!!!



$$f(v) \propto v^2 e^{-m v^2 / (2 k_b T)}$$

4. N-body simulations of star clusters + star evolution

How do star clusters form?

- * from giant molecular clouds
- * possibly from aggregation of many sub-clumps (hierarchical formation)
- * can DIE by INFANT MORTALITY!!!
- * if they survive infant mortality, gas-less star clusters can be described with distribution functions:
 - PLUMMER SPHERE
 - ISOTHERMAL SPHERE
 - LOWERED ISOTHERMAL SPHERE
 - KING MODEL

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LOWERED ISOTHERMAL SPHERE

KING MODEL

- * collisional dynamics of a star cluster must be studied with dedicated N-body simulations that resolve two-body encounters!!!

4. N-body simulations of star clusters + star evolution

* Describing a collisional system with N-body simulations requires to resolve two-body encounters properly

→ solve Newton's equation directly, no approximations

$$\ddot{\vec{r}}_i = -G \sum_{j \neq i} m_j \frac{\vec{r}_i - \vec{r}_j}{|\vec{r}_i - \vec{r}_j|^3}$$

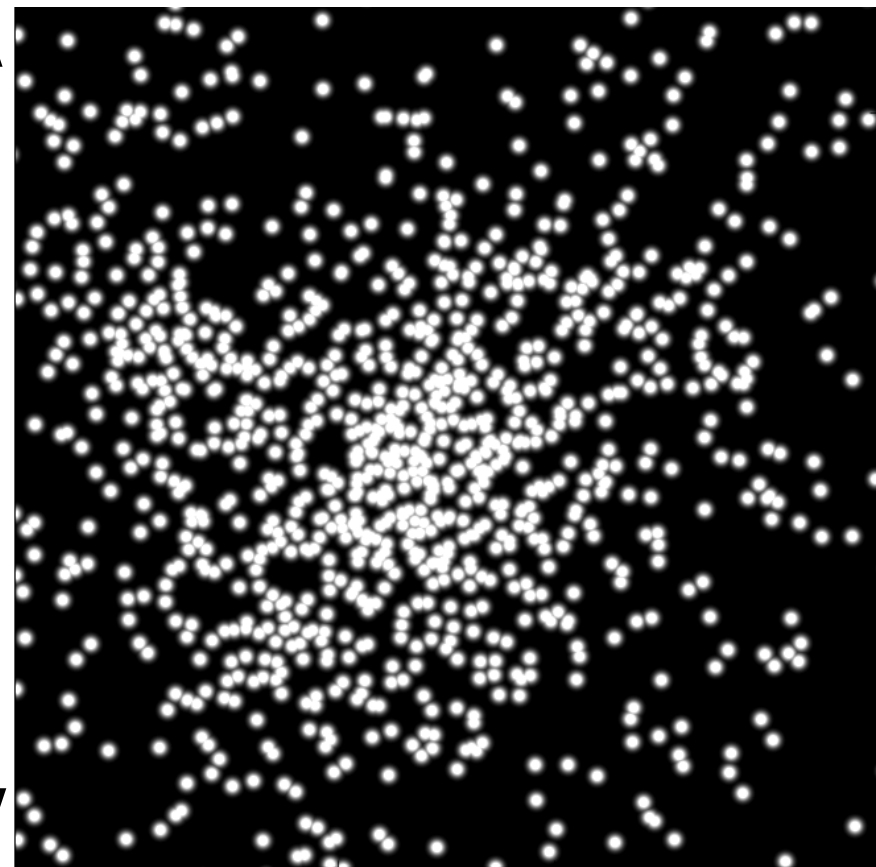
→ **DIRECT N-body codes** scaling as N^2

* Each particle ~ corresponds to a star, with its mass and radius

* Suitable for running on graphics processing units (GPUs)



2pc

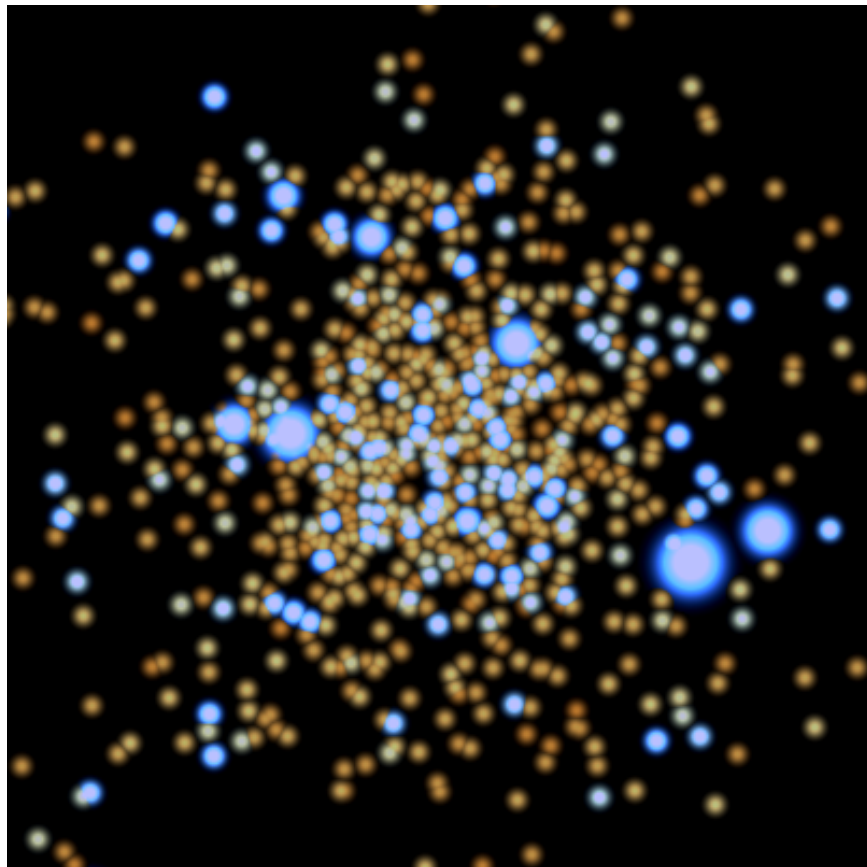


4. N-body simulations of star clusters + star evolution

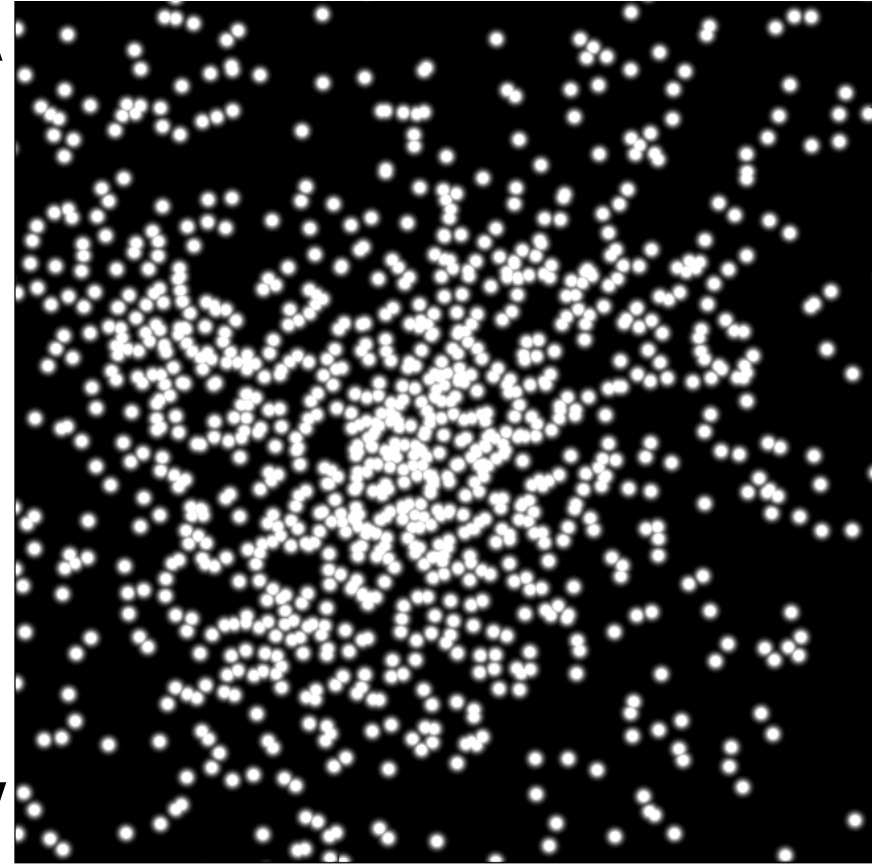
* **DIRECT N-body codes can be coupled with star evolution through a POPULATION SYNTHESIS approach**

→ **each particle DOES correspond to a single star with its own mass, radius, metallicity, luminosity, temperature THAT CHANGE IN TIME ACCORDING TO star evolution**

Gravity + stellar evolution



Gravity only

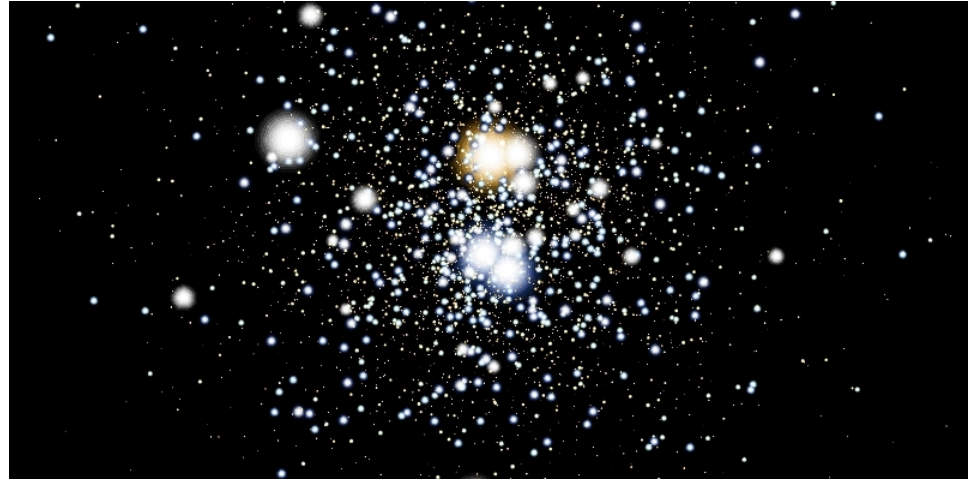


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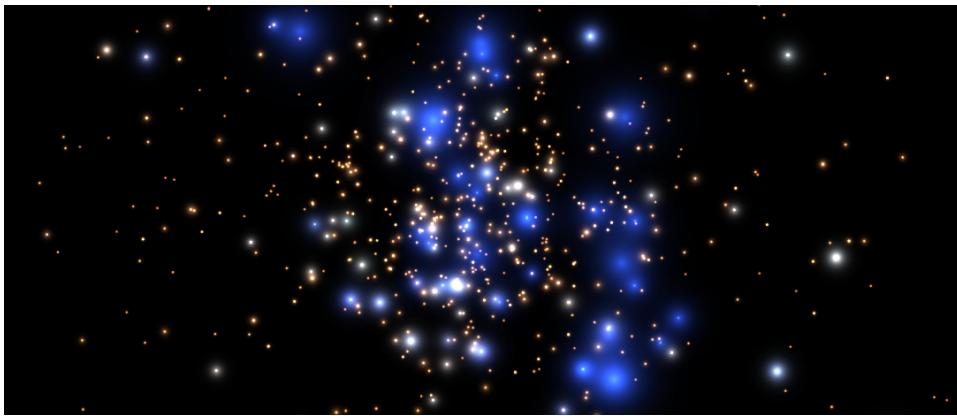
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Credits: A. Geller, Northwestern
Movie 5
Movie 6



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- * **Portegies Zwart, Gieles & McMillan 2010, ARA&A, 48, 431**